

ISCS Symposium

# Towards assimilating InSAR data into a model of a highly anisotropic aquifer system

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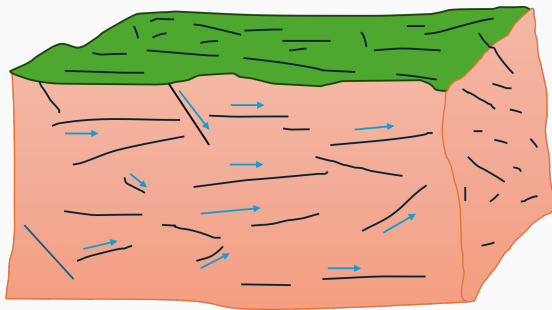
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## Groundwater flow in fractured aquifers

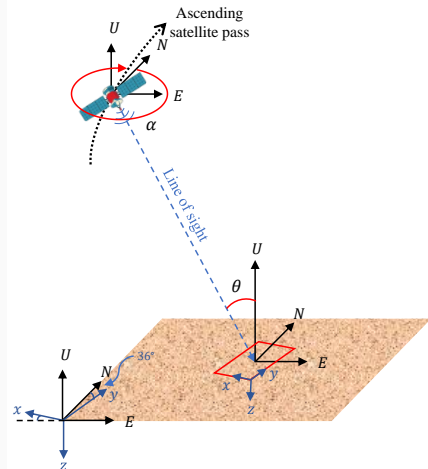
- Water flow in many aquifers is highly influenced by **anisotropy**, often caused by features like fractures and faults.
- Most existing Bayesian inference methods assume **isotropic** prior models, which may oversimplify real subsurface conditions.



Fractured aquifer

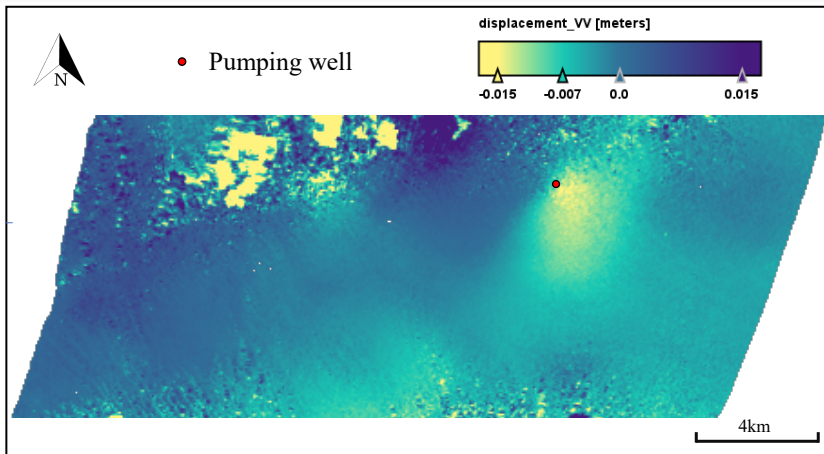
# Using InSAR to Reveal Aquifer Secrets

- What is InSAR?
- Recent work (Alghamdi et al., 2024; Salehian Ghamsari et al., 2025) has proposed **InSAR** (Interferometric Synthetic Aperture Radar) data to improve aquifer property estimation.



from (Salehian Ghamsari, van Dam, & Hale, 2025)

## Leveraging InSAR to uncover subsurface anisotropy



InSAR surface displacement of Nevada aquifer pumping test (Burbey, Warner, Blewitt, Bell, & Hill, 2006)

## Research objective

- **Goal:** Develop a mathematical framework to assimilate InSAR-derived surface displacement data into a groundwater model for estimating **anisotropic hydraulic conductivity (AHC)**.
- **Forward Modeling:** Use a poroelastic finite element model that incorporates AHC to simulate line-of-sight (LOS) surface displacements detectable by InSAR (Salehian Ghamsari et al., 2025).
- **Prior Modeling:** We develop a probabilistic model for describing anisotropy in aquifer systems that can incorporate prior information from complex, potentially multi-modal, structural geological data.



## Forward model

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## Three-field Biot equations with AHC

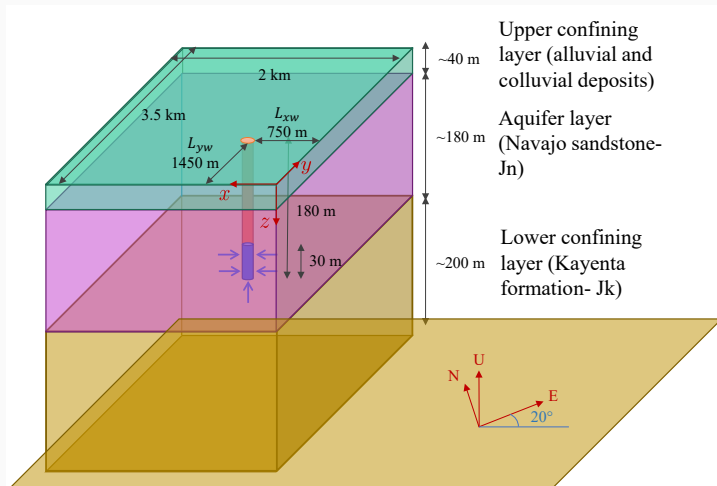
Find the fluid-pore pressure  $p : \Omega \times (0, T] \rightarrow \mathbb{R}$ , deformation  $u : \Omega \times (0, T] \rightarrow \mathbb{R}^3$  and fluid flux  $q : \Omega \times (0, T] \rightarrow \mathbb{R}^3$  such that:

$$\begin{aligned}(S_\epsilon p + \alpha \nabla \cdot u)_t + \nabla \cdot q &= f_p \text{ on } \Omega \times (0, T], \\ -\nabla \cdot \bar{\sigma}(u, p) &= f_u \text{ on } \Omega \times (0, T], \\ q + k \nabla p &= 0 \text{ on } \Omega \times (0, T],\end{aligned}$$

$k$  is the anisotropic hydraulic conductivity (AHC) tensor

$$k = \left[ \begin{array}{cc|c} k_{xx} & k_{xy} & 0 \\ k_{yx} & k_{yy} & 0 \\ \hline 0 & 0 & k_{zz} \end{array} \right],$$

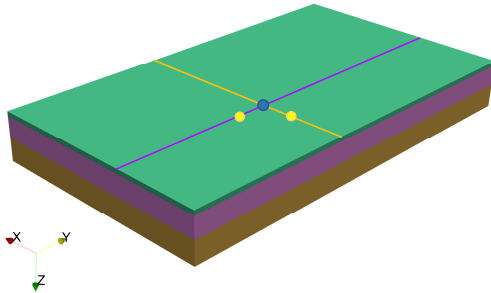
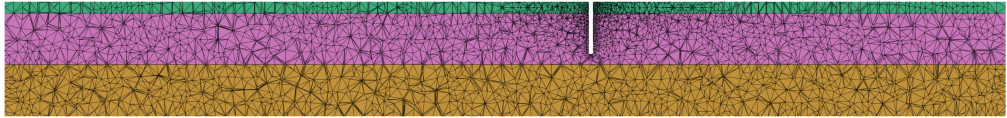
# Simplified conceptual model of the Anderson Junction aquifer system



from (Salehian Ghamsari et al., 2025)

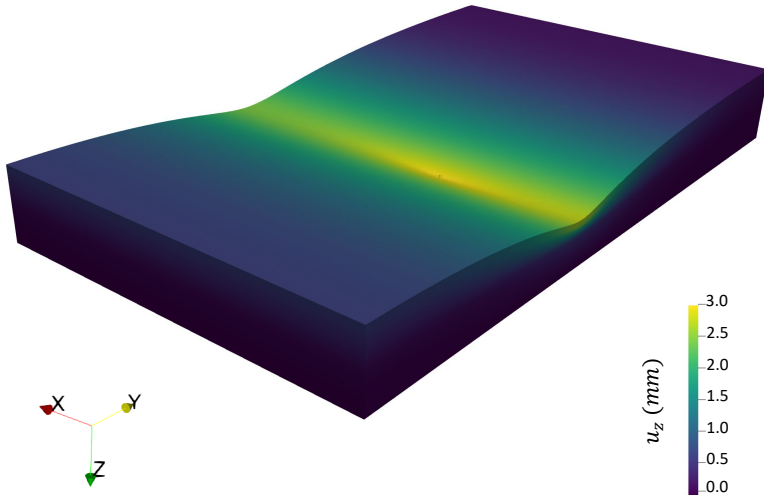


# Generated 3D mesh of the aquifer system



- Upper confining layer
- Aquifer layer
- Lower confining layer
- Pumping well
- Observation wells
- Line  $yy'$
- Line  $xx'$

## Magnified visualization of aquifer displacement



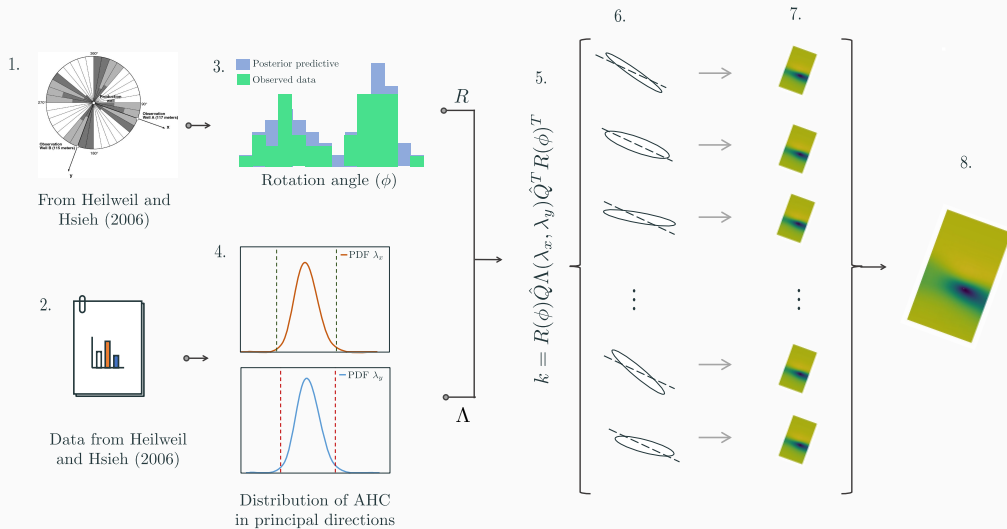
## Stochastic extension

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# AHC Magnitude and Direction

- The poroelastic PDE model requires the anisotropic hydraulic conductivity (AHC) tensor to be **symmetric positive definite (SPD)** to ensure mathematical well-posedness (Aris, 2012).
- (Shivanand, Rosić, & Matthies, 2024) recently proposed a Lie group approach for constructing symmetric positive definite matrices.
- Building on this, we develop a **stochastic prior model** for the AHC tensor that allows independent control of both:
  - **Magnitude**
  - **Direction**

# Methodology



## Methodology

- It is well known that any  $k$  can be decomposed into a tensor of eigenvalues  $\Lambda$  and a tensor of eigenvectors  $Q$

$$k = Q\Lambda Q^T.$$

- We can further rotate the eigenvectors  $Q$  by applying a rotation tensor  $R$

$$k = (RQ)\Lambda(RQ)^T,$$

- Using the rotation angle  $\phi$  about the  $z$ -axis, we construct a rotation tensor  $W$  as

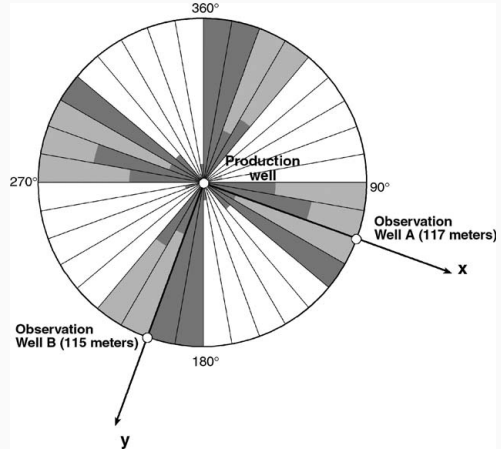
$$W = \phi \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$$

$$R = \exp(W).$$

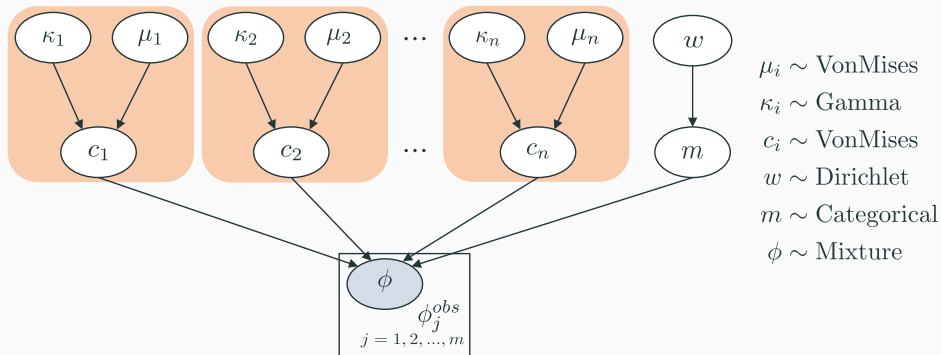
## Prior information

Source of uncertainty in anisotropic hydraulic conductivity (AHC) tensor

- **Magnitude ( $\Lambda$ ):** the reported uncertainty of hydraulic conductivity magnitude in regional study
- **Direction ( $R$ ):** fracture outcrop data



# Rotation angle model

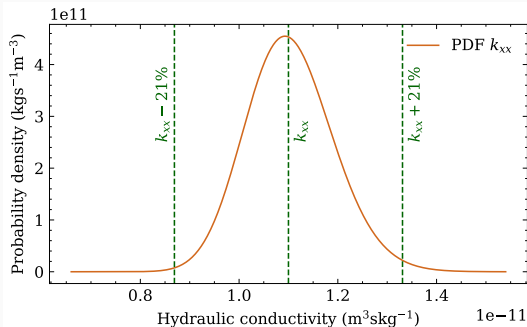




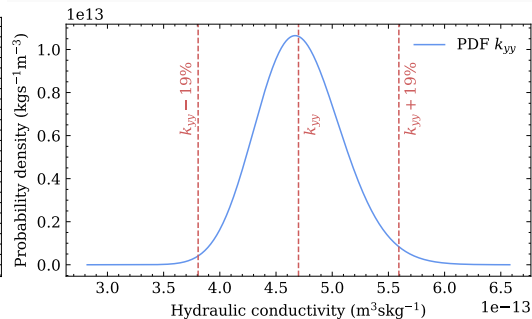
# Eigenvalue model

$$\lambda_x \sim \text{lognorm}(\hat{\mu}_x, \hat{\sigma}_x^2)$$

$$\lambda_y \sim \text{lognorm}(\hat{\mu}_y, \hat{\sigma}_y^2)$$



Distribution of AHC magnitude in the major axis.



Distribution of AHC magnitude in the minor axis.

## Anisotropic hydraulic conductivity model

- AHC tensors with randomness in both scaling and rotation

$$k(\omega) = R(\phi) \hat{Q} \Lambda(\lambda_x, \lambda_y) \hat{Q}^T R(\phi)^T.$$

- AHC tensors with randomness only in scaling ( $\phi$  is known)

$$k_s(\omega) = \hat{Q} \Lambda(\lambda_x, \lambda_y) \hat{Q}^T.$$

- AHC tensors with randomness only in rotation (both  $\lambda_x$  and  $\lambda_y$  are known)

$$k_r(\omega) = R(\phi) \hat{Q} \hat{\Lambda}(\hat{\lambda}_x, \hat{\lambda}_y) \hat{Q}^T R(\phi)^T.$$

## Forward uncertainty propagation

The mean of the LOS displacement is then computed as

$$\mu(u_{\text{LOS}}(x, t)) := \frac{1}{N} \sum_{i=1}^N u_{\text{LOS}}(x, t, k_i),$$

and the unbiased estimation of standard deviation is calculated as

$$\text{Std}(u_{\text{LOS}}(x, t)) := \left[ \frac{1}{N-1} \sum_{i=1}^N [u_{\text{LOS}}(x, t, k_i) - \mu(u_{\text{LOS}}(x, t))]^2 \right]^{1/2}.$$

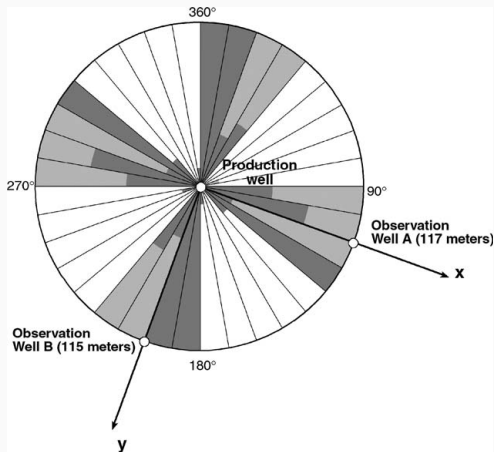
## First scenario

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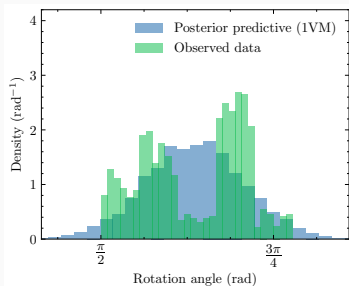
## Prior information (first scenario)

Source of uncertainty in anisotropic hydraulic conductivity (AHC) tensor **with** (Heilweil & Hsieh, 2006) results

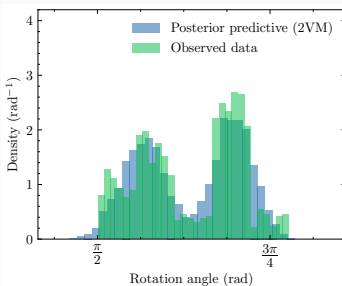
- **Magnitude ( $\Lambda$ ):**  $\approx 20\%$  uncertainty in magnitude of principal directions.
- **Direction ( $R$ ):** Multimodal uncertainty in fracture outcrop data. (uncertainty only in  $x$  direction)



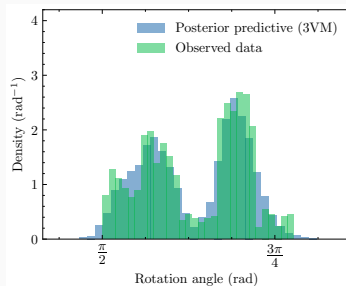
# Random rotation angle: model selection



Posterior predictive distribution  
of 1VM.



Posterior predictive distribution  
of 2VM.



Posterior predictive distribution  
of 3VM.

## Random rotation angle: model selection

Model	elpd_loo	p_loo	elpd_diff	SE
3VM	276.80	23.41	0.00	20.63
2VM	260.81	4.95	15.99	21.52
1VM	44.48	1.41	232.32	13.98

**Table 1:** Model selection results.

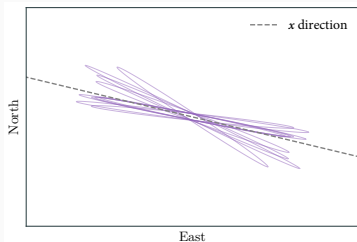
- elpd\_loo: Expected log pointwise predictive density.
- p\_loo: Estimated effective number of parameters.
- elpd\_diff: The difference in ELPD between models, computed relative to the top-ranked model.
- SE: Standard error of the ELPD estimate.

- Calculating random hydraulic conductivity tensors
- Using FEniCSx on ULHPC to run the poroelastic finite element model
- Running in parallel with thousands of random tensors
- Statistical analysis of the outputs

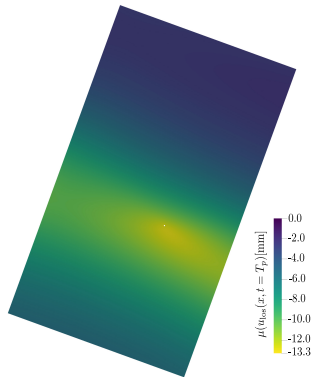




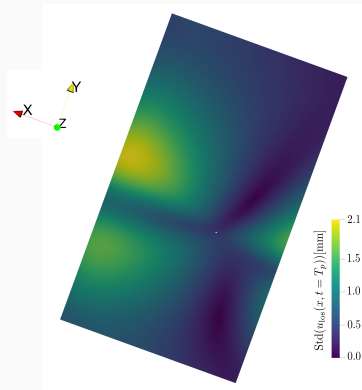
# Forward uncertainty analysis: random scaling and rotation AHC



Elliptical representation of random AHC tensors.



Mean of LOS displacement.



Standard deviation of LOS displacement.

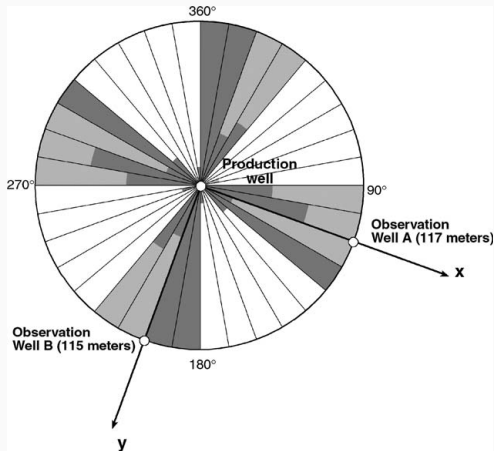
## Second scenario

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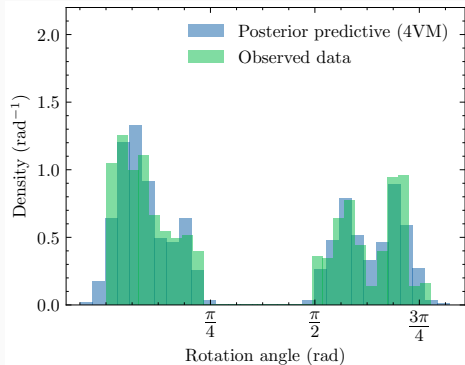
## Prior information (second scenario)

Source of uncertainty in anisotropic hydraulic conductivity (AHC) tensor **without** (Heilweil & Hsieh, 2006) results

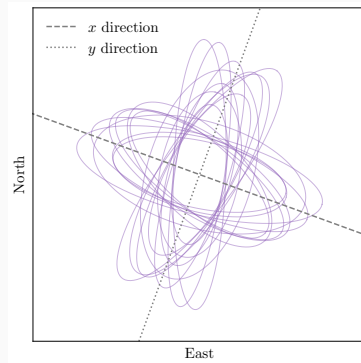
- **Magnitude ( $\Lambda$ ):** no information available
- **Direction ( $R$ ):** Multimodal uncertainty in fracture outcrop data. (uncertainty in both  $x$  and  $y$  directions)



# Random rotation angle and random AHC

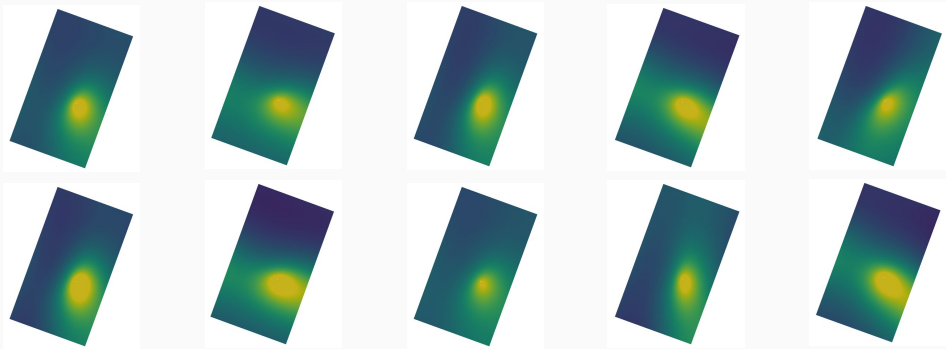


Posterior predictive distribution of mixture of four von Mises model for the major principal direction.



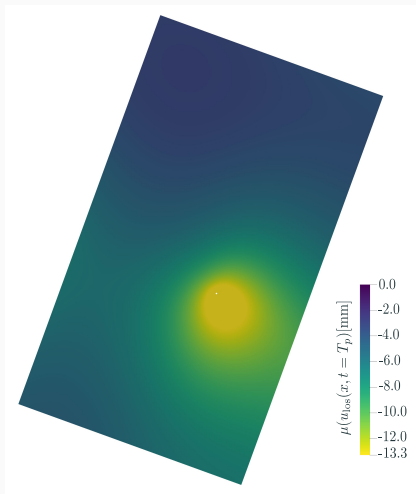
Elliptical representation of random AHC tensors.

## Forward uncertainty analysis

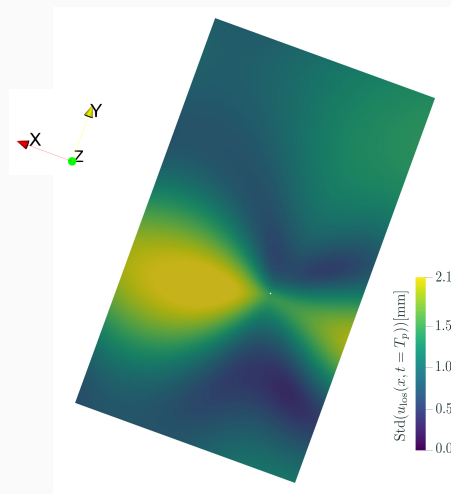


Samples of LOS displacement.

# Forward uncertainty analysis



Mean of LOS displacement.



Standard deviation of LOS displacement.

# Conclusion

- By calibrating the model against fracture outcrop and optionally pump test data from Anderson Junction, we were able to express two conceptual states of belief about the site.
- The proposed methodology provides a flexible tool for modeling the effect of random anisotropy on InSAR-measurable surface displacements.
- The proposed stochastic model could work as a prior in a Bayesian inference setting where InSAR-derived line-of-sight data contains information about AHC.

## Future work:

- ✈ We will solve an inverse problem using InSAR data to estimate AHC

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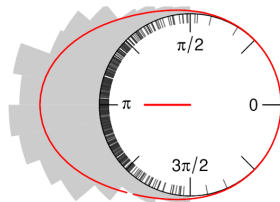
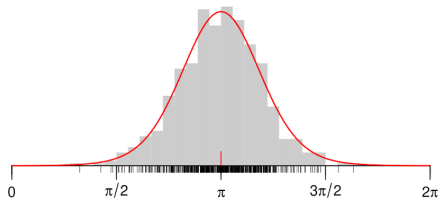
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# The von-Mises distribution

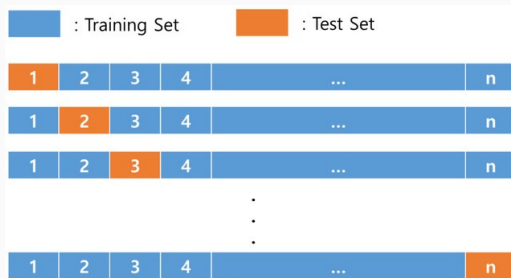


From (Lang et al., 2020)

$$f(\phi(\omega_r)|\mu, \kappa) = \frac{\exp(\kappa \cos(\phi(\omega_r) - \mu))}{2\pi I_0(\kappa)}$$

where  $I_0$  is the modified Bessel function of order 0.

# Leave-one-out cross-validation



From (Cha et al., 2020)

- $ELPD_{loo}$ : expected log pointwise predictive density.  
Higher ELPD indicates higher out-of-sample predictive fit (“better” model).
- $P_{loo}$ : Estimated effective number of parameters.