

SMALL SATELLITE ACTIVE SPACE DEBRIS REMOVAL APPLICATION FOR UNCOOPERATIVE SPACE DEBRIS

Maxime Hubert Delisle, Xiao Li, Baris Can Yalcin, Miguel Olivares-Mendez, Carol Martinez

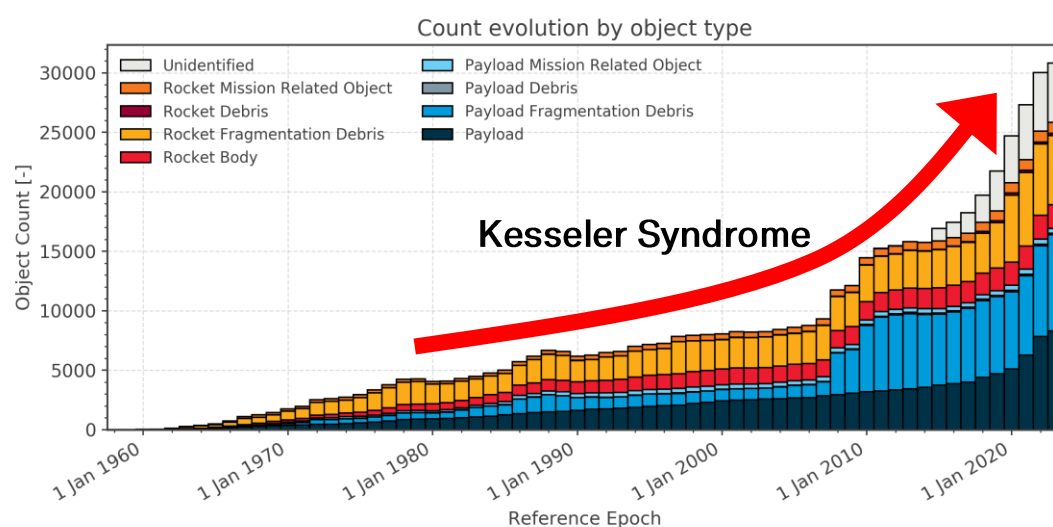


6 Rue Richard Coudenhove-Kalergi, 1359, Luxembourg, Luxembourg
maxime.hubertdelisle@uni.lu

FACULTY OF SCIENCE, TECHNOLOGY AND MEDICINE

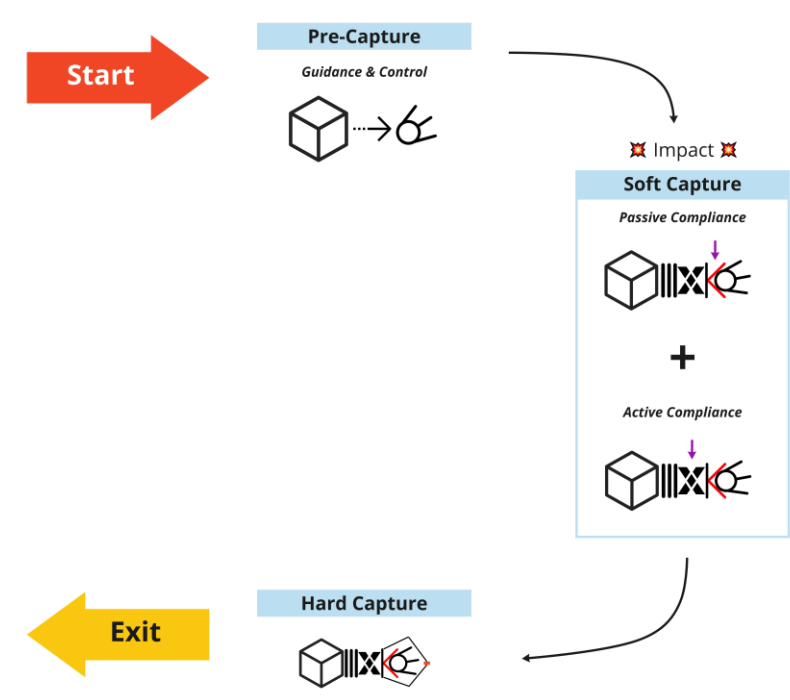
CONTEXT

- Exponential growth of space debris in orbit
- Active Debris Removal (ADR) needed for stabilising the exponential growth of space debris
- Developed systems are one-to-one design solutions for large debris (1 system able to capture 1 debris)



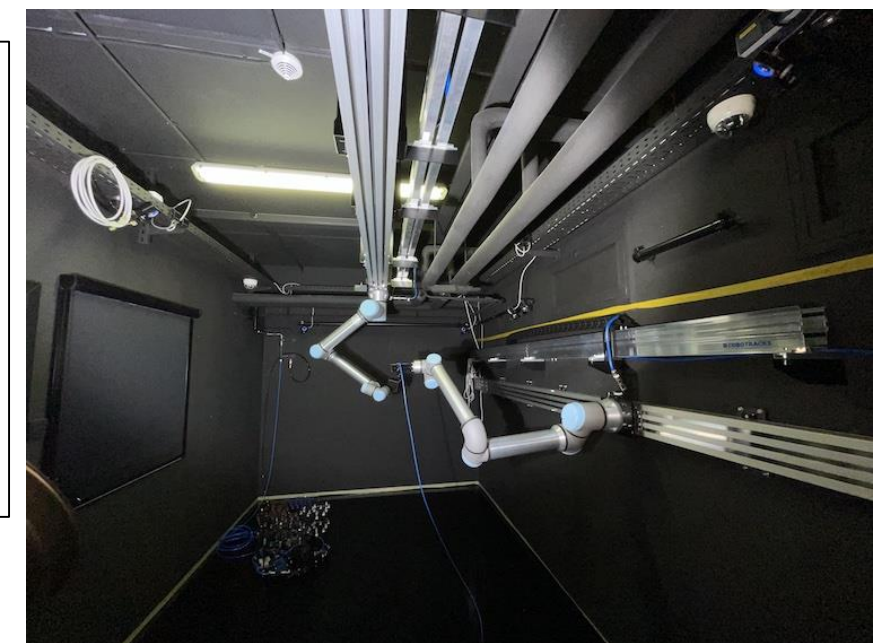
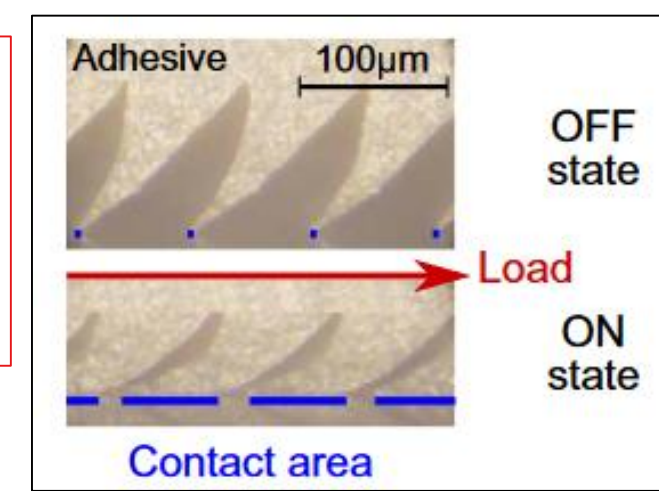
DESIGN REQUIREMENTS

- Data Analysis** of the trackable objects in Low-Earth Orbit (LEO)
- A **one-to-many solution** → 1 system can be used to capture different debris
- Integrates two types of capture:
 - Soft Capture** complies and retains the debris from being pushed away at the impact.
 - Hard Capture** secures the link with the debris and ensures the system ready for deorbiting.
- The mechatronic system must be **autonomous**.
- The system targets **flat surfaces**.



HYBRID-COMPLIANT CONCEPT

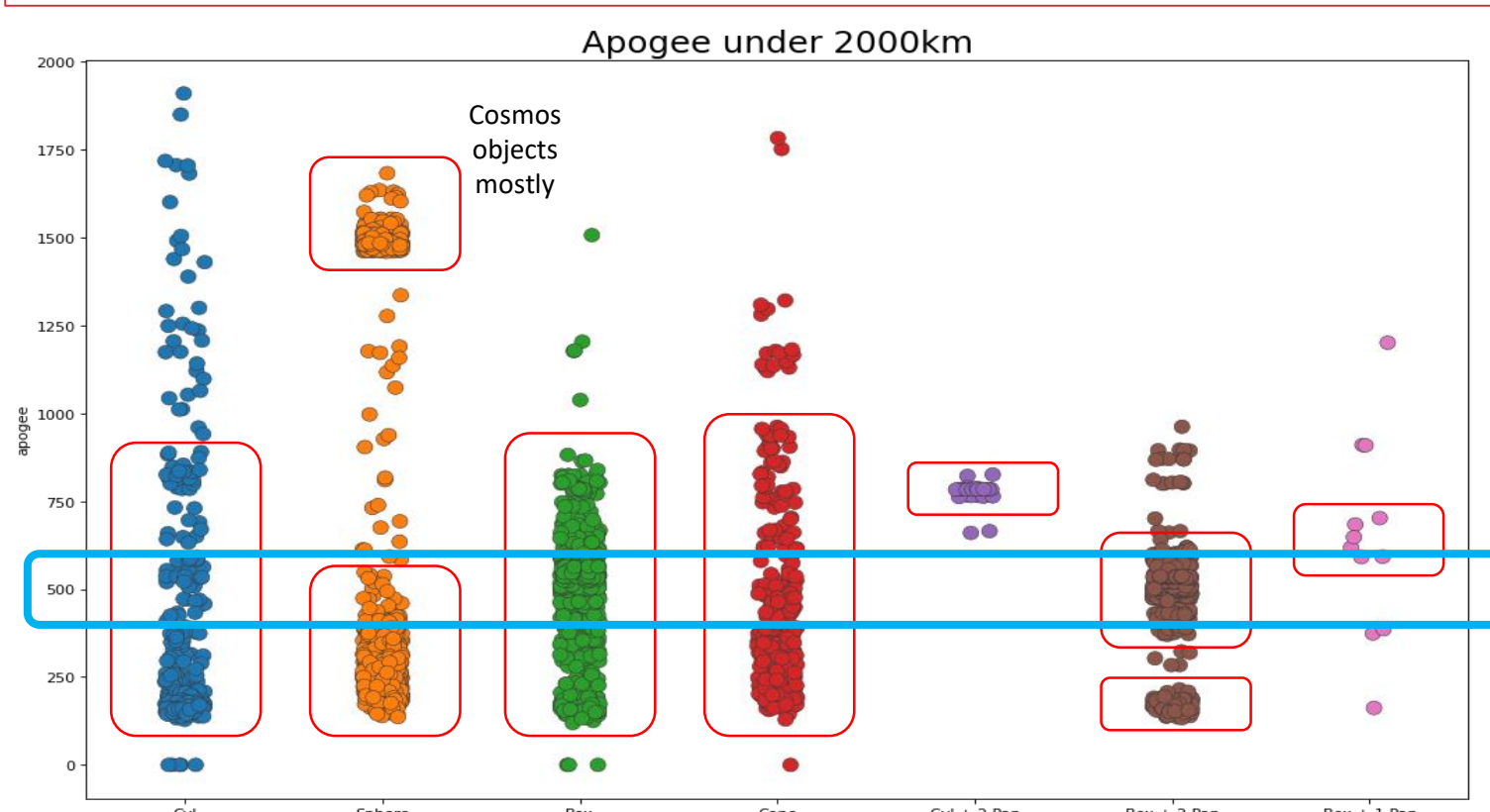
- Hybrid-compliant mechanism** → **Active + Passive Compliance**, dissipating impact energy
 - Active Compliance** → linear actuators + impedance controller
 - Passive Compliance** → revolute joints + torsional springs
- The system's stiffness can be **adaptive** to the debris mass, and approach velocity
- Use of **bio-inspired dry adhesive** from the gecko fingers
 - Van der Waals interactions to stick with the debris surface.
 - Tests in the **ZeroG Lab** of SpaceR



ZeroG Lab

RESEARCH

What range of debris to target?



Shape	Amount	% of LEO small debris total
Sphere	1044	25.08
Box	949	22.80
Box + 2 Pan	669	16.07
Cyl	457	10.98
Cone	274	6.58
Box + 2 Ant	113	2.72

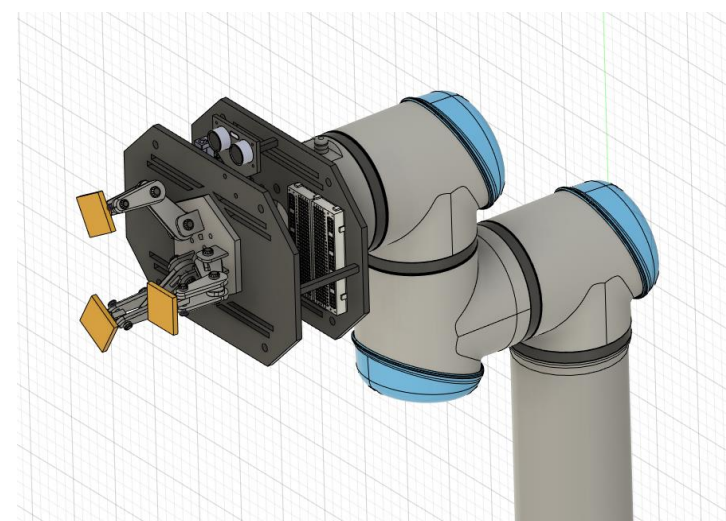
Table 1. Main Debris Shapes Found In LEO (mass ≤ 100 kg)

Passive Compliance Unit

From Concept...

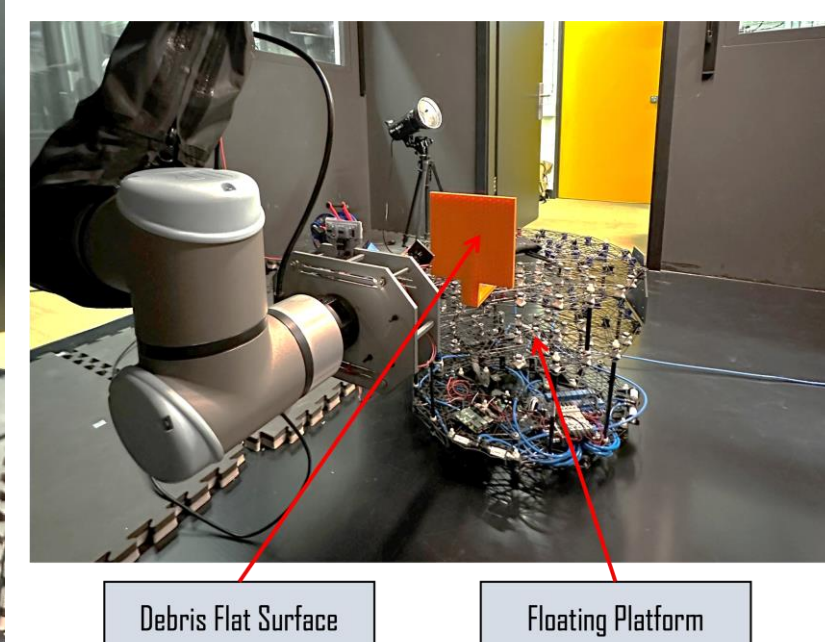
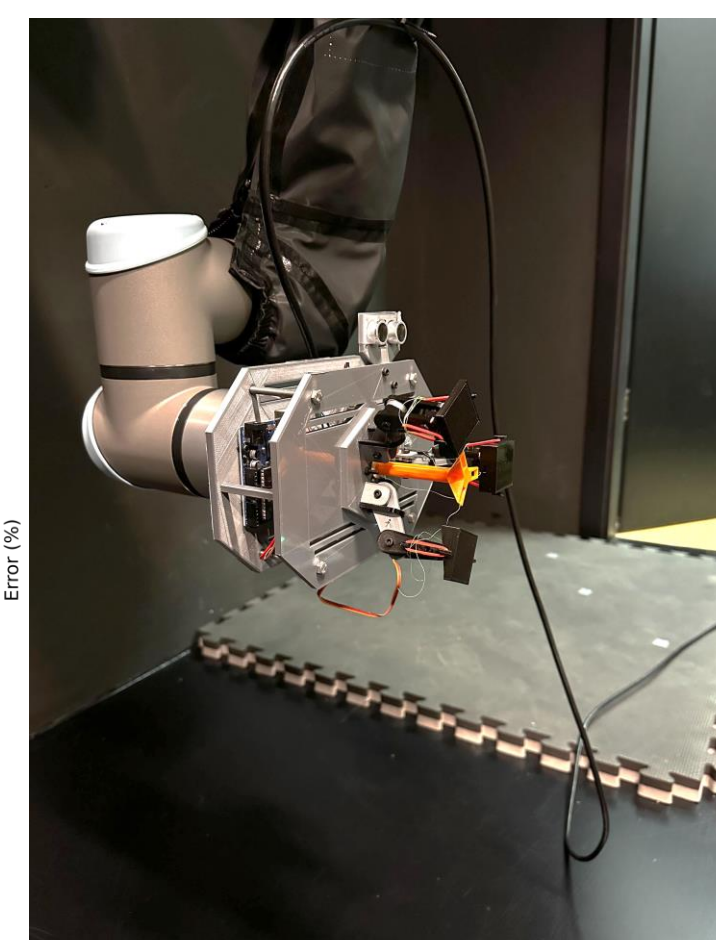
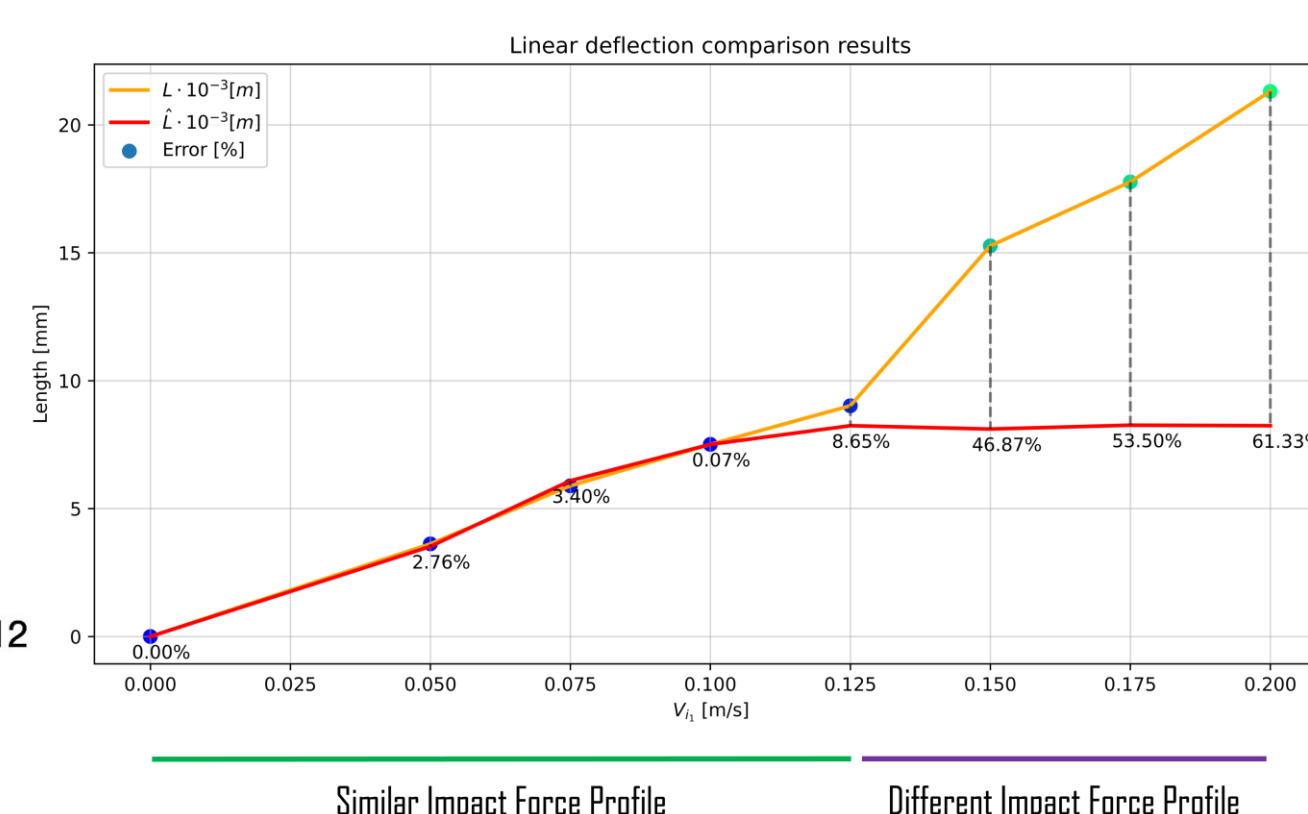
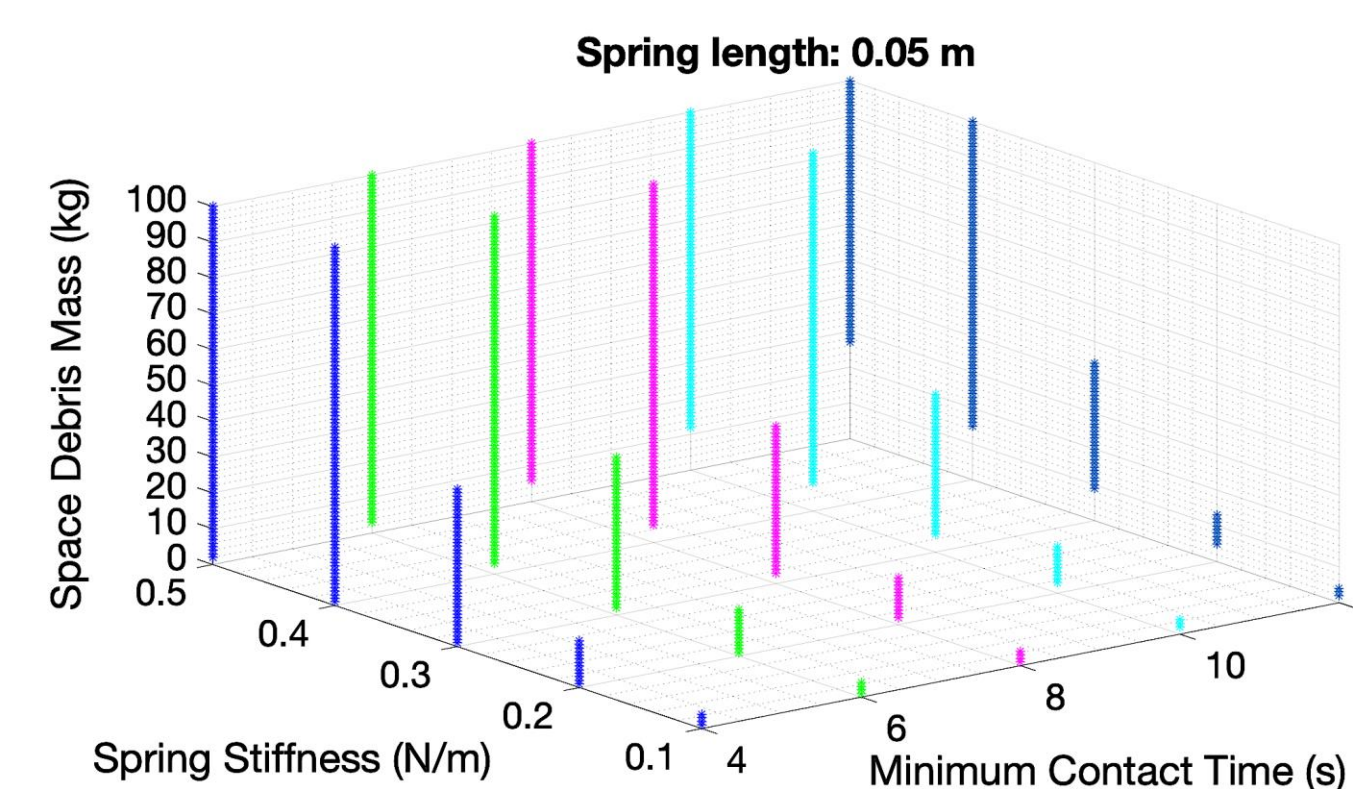


...to Prototype...



...Ready to be tested in the lab!

Impact Behaviour Simulations & Tests



FUTURE WORKS

- Implement and test Passive Compliance + Active Compliance in the ZeroG Lab
- Concept, Prototype and Tests of the Hard Capture
- Disseminate the results in journals and conferences

REFERENCES

- Hubert Delisle, M.; Christidi-Loumpasfiski, O.-O.; Yalcin, B.C.; Li, X.; Olivares-Mendez, M.; Martinez, C. Hybrid-Compliant System for Soft Capture of Uncooperative Space Debris. *Appl. Sci.* **2023**, *13*, 7968. <https://doi.org/10.3390/app13137968>
- Yalcin, B.C.; Martinez, C.; Hubert Delisle, M.; Rodriguez, G.; Zheng, J.; Olivares-Mendez, M. ET-Class: An Energy Transfer-Based Classification of Space Debris Removal Methods and Missions. *Front. Space Technol.* **2022**, *3*, 23.

ACKNOWLEDGEMENTS

SnT-SpaceR has conducted this study under Luxembourg National Research Fund (FNR)—CASED funding for “design of a Capturing, Absorbing, SEcuring system for active space Debris removal—CASED” project FNR16678722.