

## **FEniCS 2022 abstract: SOniCS: Interfacing SOFA and FEniCS for advanced constitutive models**

Arnaud Mazier, Sidaty El Hadramy, Jean-Nicolas Brunet, Jack S. Hale, Stéphane Cotin, Stéphane P.A. Bordas

The Simulation Open Framework Architecture (SOFA) is a software environment for building simulations with a particular focus on real-time medical applications, e.g. surgery. Its scope is far broader than the FEniCS Project, encompassing e.g. rigid body dynamics, interfacing with haptic devices, contact and visualisation. Naturally, it also includes some finite element models of soft tissue mechanics, but these capabilities are currently 'pre-baked' and limited to a few simple constitutive models.

The goal of this work is to incorporate state-of-the-art code generation tools from the FEniCS Project into SOFA in order to hugely increase SOFA's capabilities in terms of soft tissue mechanics. To this end we have developed a new SOFA plugin named SOniCS. For adding a new material model in SOniCS, the user describes its strain energy density function using UFL (Unified Form Language) syntax. Then, using FFCx (FEniCSx Form Compiler) we generate the C code associated with the kernels corresponding to the automatically differentiated cell-local residual and stiffness forms. Finally, we assemble these kernels in SOFA into global tensors and solve the resulting non-linear systems of equations.

The result is that it is now possible to straightforwardly implement complex material models such as the Holzapfel-Ogden anisotropic model into SOFA, and to use them alongside SOFA's existing strong feature set in medical simulation.

### References:

- Arnaud Mazier, Sidaty El Hadramy, Jean-Nicolas Brunet, Jack S. Hale, Stéphane Cotin, Stéphane P.A. Bordas. SOniCS: Interfacing SOFA and FEniCS for advanced constitutive models, submitted, 2022.
- François Faure, Christian Duriez, Hervé Delingette, Jérémie Allard, Benjamin Gilles, et al.. SOFA: A Multi-Model Framework for Interactive Physical Simulation. Yohan Payan. *Soft Tissue Biomechanical Modeling for Computer Assisted Surgery*, 11, Springer, pp.283-321, 2012, *Studies in Mechanobiology, Tissue Engineering and Biomaterials*.

This project has received funding from the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No. 764644. This abstract only contains the RAINBOW consortium's views and the Research Executive Agency and the Commission are not responsible for any use that may be made of the information it contains. This publication has been prepared in the framework of the DRIVEN project funded by the European Union's Horizon 2020 Research and Innovation programme under Grant Agreement No. 811099. This study is supported by the National Research Fund, Luxembourg, and cofunded under the Marie Curie Actions of the European Commission (FP7-COFUND) Grant No. 6693582. This project is supported by the "IHU Strasbourg - Institut de chirurgie guidée par l'image" Strasbourg, France.