

# Session Subtyping and Multiparty Compatibility using Circular Sequents

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## 6 — Abstract —

7 We present a structural proof theory for multi-party sessions, exploiting the expressive power of  
8 non-commutative logic which can capture explicitly the message sequence order in sessions. The  
9 approach in this work uses a more flexible form of subtyping than standard, for example, allowing a  
10 single thread to be substituted by multiple parallel threads which fulfil the role of the single thread.  
11 The resulting subtype system has the advantage that it can be used to capture compatibility in the  
12 multiparty setting (addressing limitations of pairwise duality). We establish standard results: that  
13 the type system is algorithmic, that multiparty compatible processes which are race free are also  
14 deadlock free, and that subtyping is sound with respect to the substitution principle. Interestingly,  
15 each of these results can be established using cut elimination. We remark that global types are  
16 optional in this approach to typing sessions; indeed we show that this theory can be presented  
17 independently of the concept of global session types, or even named participants.

18 **2012 ACM Subject Classification** Theory of computation → Type theory; Theory of computation  
19 → Proof theory; Theory of computation → Linear logic; Theory of computation → Process calculi

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## 24 **1 Introduction**

25 Session types are a class of type systems for modelling protocols that prescribe, not only the  
26 types of messages exchanged, but also the sequence in which they are communicated. The  
27 first session type systems were constrained to two parties. For such binary sessions, given a  
28 session type prescribing the behaviour of each of the participants, it is possible to determine  
29 whether the two behaviours are compatible, in the sense that they can interact together to  
30 successfully realise a protocol.

31 Here, in the introduction, we first make it clear there are obvious, underexploited,  
32 connections between compatibility in the binary setting and provability in non-commutative  
33 extensions of linear logic. The body of this work shows that these observations extend  
34 elegantly to the multiparty setting [32, 33], where multiparty compatibility is the problem of  
35 whether two or more participants realise a protocol when they communicate together.

36 **On the binary setting and non-commutative logic.** In the binary setting, compatibility  
37 holds when the two parties are dual to each other [30]. For example,  $!λ_1;(?λ_2 \wedge ?λ_3)$   
38 is dual to  $?λ_1;(!λ_2 \vee !λ_3)$ . The former types a process that is ready to output a message of  
39 type  $λ_1$ , and then receives either a message of type  $λ_2$  or  $λ_3$ . The latter types a process that  
40 is ready to receive a message of type  $λ_1$ , and then makes a choice between two branches,  
41 sending a message of type  $λ_2$  or  $λ_3$ . By building subtyping into the system [24, 23, 18],  
42 duality becomes a more flexible concept. For example, two processes of respective types  
43  $!λ_1;(?λ_2 \wedge ?λ_3)$  and  $?λ_1;!λ_2$  are also compatible. Notice a process of the type  $!λ_1;(?λ_2 \wedge ?λ_3)$



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44 offers two possible inputs, so is more than capable of responding correctly to  $?λ_1;!λ_2$ , which  
45 always chooses to send  $λ_2$  as its second action.

46 For binary sessions, compatibility is proven by showing that the dual of a type is a subtype  
47 of another type, for example establishing  $!λ_1;(?λ_2 ∧ ?λ_3) \leq !λ_1;?λ_2$ . In the original paper on  
48 session types [30], it was explicit that internal and external choice were inspired by the additive  
49 operators in linear logic [27, 26, 1]. For example, interpreting  $∧$  as additive conjunction in  
50 linear logic, subtype relation  $?λ_2 ∧ ?λ_3 \leq ?λ_2$  is a provable implication in linear logic. While  
51 pure linear logic has no concept of sequentiality (all operators are commutative), linear logic  
52 can be extended with non-commutative operators explicitly capturing sequentiality, allowing  
53 the above subtype judgement involving prefixing to be proven. In this work, we restrict  
54 ourselves to a fragment of non-commutative logic with action prefixing only, allowing us  
55 to retain a sequent calculus presentation. Full sequential composition can be achieved [34].  
56 However, for full sequential composition, it is necessary [50] to employ the calculus of  
57 structures [28]. The compromise adopted in this work, of restricting non-commutative logic  
58 to prefixing, allows us to formulate our subtype system using the sequent calculus, whilst  
59 still working within a fragment of a conservative extension of linear logic.

60 **Contribution to the multiparty setting.** Using non-commutative extensions of linear  
61 logic to model multiparty session types provides additional expressive power. In particular,  
62 the subtype system obtained allows more session types to be compared than possible using  
63 established subtype systems [25]. Indeed the subtype system obtained is sufficiently rich, so  
64 that subtyping can be used to evaluate compatibility in the multi-party setting. The notion  
65 of *multiparty compatibility* enforced by this methodology allows session types to be used  
66 to guarantee that multiparty sessions are deadlock free without the need for a global type  
67 choreographing all processes. An advantage of avoiding global types is that we can check  
68 compatibility for protocols for which no global type exists [48].

69 **Problems with pairwise duality resolved.** Early work on multi-party session types [8,  
70 21] employed a notion of compatibility based on the notion of duality for binary types applied  
71 pairwise. In that early work, we take each pair of participants and *restrict them only to the*  
72 *inputs and outputs between the participants selected*, and then check whether each pair of  
73 projections are dual. Pair-wise duality fails to guarantee deadlock freedom, since process  
74  $?λ_1;!λ_2 \parallel ?λ_2;!λ_3 \parallel ?λ_3;!λ_1$  deadlocks, despite participants being pair-wise dual (e.g., restricting  
75 the first two participants to their mutual communications gives types  $!λ_2$  and  $?λ_2$ , which are  
76 dual). The process above consists of three participants in parallel each waiting to receive a  
77 message, from another process before producing an output. The process is clearly deadlocked  
78 since all inputs await a message that never arrives.

79 The current work, and related work [20, 15, 48, 39, 19], addresses the above limitation  
80 of pair-wise duality by proposing more sophisticated notions of *multi-party compatibility*.  
81 The work on which this builds [15] (which concerned a finite fragment of Scribble [31]),  
82 handles multiparty compatibility as a special case of subtyping. In this work, as required,  
83 our example processes in the previous paragraph would **not** be multi-party compatible. The  
84 rules of the system in this paper are determined by logical principles (cut-elimination).

85 **Related paradigms.** This paper does not follow the Curry-Howard inspired proofs-  
86 as-processes school; instead, it follows a processes-as-formulae [10, 36] approach closer to  
87 intersection types [44] and algorithmic subtyping [47]. For multiparty sessions, the processes-  
88 as-formulae [15] and proofs-as-processes paradigms [12, 11] emerged simultaneously. Papers  
89 following the Curry-Howard approach typically aim to design new (higher-order) session  
90 calculi where the process terms are proofs in an established logic. In contrast, in the processes-  
91 as-formulae approach pursued here, we typically harness the power of structural proof theory

92 to design new logics that can directly embed established session calculi [17], while respecting  
 93 their semantics. In this work, linear implication in the logical system introduced provides us  
 94 with a notion of session subtyping preserving deadlock freedom.

95 **Summary.** In Section 2, we explain how the notion of multiparty subtyping is more  
 96 flexible than established notions of subtyping for multiparty sessions, illustrated using an  
 97 example where a participant is substituted by two participants. Section 3 formally develops  
 98 a theory of session subtyping and multiparty compatibility in a coinductive sequent calculus.  
 99 That section concludes with an example where we guarantee the deadlock freedom of a  
 100 session for which no global type exists.

## 101 2 Motivating Example: A Generalised Substitution Principle

102 The problem of defining a subtype system for multiparty sessions is *in a sense* solved in the  
 103 synchronous setting [14, 25]. Soundness in that work is defined according to a *substitution*  
 104 *principle* [41], informally stated in related work [25] as: “If  $T \mathcal{R} T'$ , then a process of type  $T'$   
 105 engaged in a well-typed session may be safely replaced with a process of type  $T$ .” Here  $\mathcal{R}$  is  
 106 a candidate subtype relation and “safely” is formalised in terms of deadlock freedom.

107 In the above related work, the substitution principle allows one (single threaded) parti-  
 108 cipant to replace another participant. In the current paper, we take a broader interpretation  
 109 of the substitution principle, permitting more parallelism to be introduced. We allow parti-  
 110 cipants in a session to be replaced by any number of participants, e.g., a single thread of  
 111 type  $T$  can be replaced by two parallel participants of type  $T_1$  and  $T_2$ , where  $T_1 \otimes T_2 \leq T$ .  
 112 This allows parallel components to be introduced with additional communications, while  
 113 preserving the ability of the multiple components to fulfil the role of the original components.  
 114 An example is provided next.

115 **An authorisation protocol.** We provide an example that is out of scope of the substi-  
 116 tution principle in related work mentioned above, but within the scope of the substitution  
 117 principle in the current paper. In the example that follows, we consider an application where  
 118 a *Trusted App* is replaced by an *Untrusted App* and an *OAuth Server*. This demands a rich  
 119 multi-party subtype system accounting for parallelism and interactions.

120 Consider the protocol realised by the three participants in Fig. 1, which are modelled as  
 121 threads in a typical session calculus. In this authorisation protocol, the *Trusted App* asks the  
 122 *Owner* of a resource for permission before it accesses the *Resource*.

```

Owner:      ?login_page(app_ID, scope); (!deny ⊕ !authorise(name, password))

Resource:   recX.(?release + ?request(token); (!revoke ⊕ !response(data); X))

Trusted App: !login_page(app_ID, scope);
              ?deny;!release + ?authorise(name, password);
              recY.!release ⊕ !request(token);
              ?revoke + ?response(data); Y
  
```

■ **Figure 1** The local behaviours of three participants in an authorisation protocol.

123 *Owner*: This could be you — the human user, who owns the resource. You get redirected  
 124 to a login page containing the *app\_ID* for the *Trusted App* and a *scope* indicating the  
 125 resources requested (e.g., personal contact details). If you chose to approve authorisation,

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126 you grant access to the resource by providing your *name* and *password*. You do however  
 127 have the ability to chose not to approve, choosing the branch  $!deny$  in the **internal choice**,  
 128 notated  $\oplus$  in the process *Owner* in Fig. 1.

129 *Resource*: A token is used by the *Trusted App* to prove it has the right to access the  
 130 resource. The *Resource* can be accessed many times by the *Trusted App* until the token  
 131 expires or is revoked. The expiry of a token is modelled here by the *Resource* making an  
 132 internal choice, deciding whether to provide data or revoke.

133 *Trusted App*: Since the App is trusted it presents directly the login page to the user. If  
 134 the *Resource Owner* approves, the same App manufactures a token which is used to access  
 135 the resource. Notice **external choice**, notated  $+$ , is used for inputs.

136 A problem with the above protocol is that user credentials are provided directly to the  
 137 *Trusted App*. Furthermore, the *Trusted App* does not only know the credentials of the owner  
 138 of the resource, it must also know how to manufacture tokens to access the resource; hence,  
 139 in principle, has the right to freely access the resource without asking permission. Thus,  
 140 there is no security offered to the *Resource Owner* or *Resource* if the app is compromised.

141 **Substituting one participant with two participants**. We can address the above  
 142 limitation by making use of the OAuth 2.0 protocol [29] where handling of credentials and  
 143 generation of tokens is handled by an *OAuth Server* that the *Owner* trusts more than the  
 144 app. We can refine the above protocol by substituting *Trusted App* with two processes in  
 145 parallel: an *Untrusted App* and *OAuth Server*, defined in Fig. 2.

*Untrusted App*:

```
!initiate(add_ID, scope);
?close + ?authorisation_code(code);
  !exchange(app_ID, secret, code);
  ?close + ?access_token(token);
    recY.!request(token);(?revoke + ?response(data);Y)
```

*OAuth Server*:

```
?initiate(app_ID, scope);
!login_page(app_ID, scope);
(?deny;!close;!release) + ?authorise(name, password);
  (!close;!release)  $\oplus$  !authorisation_code(code);
    ?exchange(app_ID, secret, code);
    (!close;!release)  $\oplus$  !access_token(token)
```

■ **Figure 2** Two participants that can safely replace the *Trusted App* in Fig. 1

146 The OAuth protocol enables the *Untrusted App* to access the *Resource*, for which per-  
 147 mission is required from the *Owner*, in such a way that the *Owner* never discloses their  
 148 credentials to the *Untrusted App*. The *Owner* permits the *OAuth Server* to grant an access  
 149 token to the *Untrusted App* that can be used to access the *Resource*. We briefly describe  
 150 informally each process.

151 *OAuth Server*: As a mediator between the *Untrusted App* and *Resource Owner*, the  
 152 *OAuth Server* receives an initiate request from the *Untrusted App*, resulting in the *Resource*  
 153 *Owner* being redirected to a login page. Notice the *OAuth Server* reacts to the decision of  
 154 the *Resource Owner* to either provide credentials or end the session, indicated by an *external*  
 155 choice. Notice, after that point, that the server makes two internal choices: the first issuing  
 156 a *code* to the *Untrusted App* only if the correct credentials were provided by the *Owner*; the

157 second issuing an access token only if the *Untrusted App* provides its correct credentials (and  
 158 the correct *code*). If all is correct, a *token* is eventually issued to the *Untrusted App*.

159 *Untrusted App*: The *Untrusted App* initiates the protocol. It then reacts, indicated by  
 160 external choices, to whether the *Resource Owner* and *OAuth Server* grant access. If an access  
 161 *token* is granted, the token can be used repeatedly to access the resource requested.

162 **What the subtype system guarantees here.** The *Trusted App* can be replaced by  
 163 *Untrusted App*  $\parallel$  *OAuth Server* while preserving deadlock freedom of the protocol. We know  
 164 this because the type of *App*  $\parallel$  *OAuth* is a subtype of the type of *Trusted App*, by using the  
 165 subtype system introduce in the next section. Furthermore, for protocols of the complexity of  
 166 this OAuth example, it is not immediately obvious whether all roles are correctly implemented  
 167 such that deadlock freedom is guaranteed. We can also use the subtype system introduced  
 168 in the next section to check whether participants together are multiparty compatible.

### 169 3 A Proof System for Subtyping and Multiparty Compatibility

170 In this section, we introduce session types and a proof system for expressing session types  
 171 called **Session**, which defines our subtype system for multiparty sessions. Later in this section,  
 172 having introduced **Session**, we define multiparty compatibility and race freedom, and use  
 173 these properties to establish our main deadlock freedom result.

174 Session types are defined according to the following syntax. Note we could have propositional  
 175 data types (*nat*, *bool*, etc.), but accommodating such data types is a perpendicular  
 176 issue to this work, hence we simply label messages ( $\lambda_1$ ,  $\lambda_2$ , etc.).

177 ► **Definition 1** (session types). Session types for threads are *defined by*:

$$178 \quad L ::= \bigwedge_{i \in I} ?\lambda_i; L_i \mid \bigvee_{i \in I} !\lambda_i; L_i \mid \mu t. L \mid t \mid \text{ok}$$

179 Session types for networks are *defined by*:

$$180 \quad N ::= L \mid N \wp N \mid N \otimes N$$

181 We refer to both of the above simply as session types, which are ranged over by  $T$ ,  $U$ ,  $V$ . We  
 182 restrict ourselves to guarded recursion, avoiding the type  $\mu t. t$ . Index sets  $I$  are finite.

183 The constant **ok** is used to type networks that, on all paths, either successfully terminate or  
 184 progress forever. Intersection types (abbreviated as  $\wedge$  when there are two branches) are used  
 185 to type external choices between inputs; while union types (abbreviated as  $\vee$ ) type internal  
 186 choices between outputs.

187 Actions  $\pi$  are either of the form  $!\lambda$  or  $? \lambda$ . Whenever there is only one branch in a  
 188 union/intersection type, we simply write the action prefixed type  $\pi; T$ , which is used to type  
 189 a process that performs an input or output and then behaves as  $T$ . As standard, we allow **ok**  
 190 to be omitted, by abbreviating  $\pi; \text{ok}$  as  $\pi$ .

191 Notably, the syntax features two commutative multiplicative operators  $\wp$  and  $\otimes$ . When  
 192 typing multiparty sessions we employ only  $T \otimes U$ , representing two parallel sessions  $T$  and  $U$   
 193 that may communicate and interleave actions. The operator  $T \wp U$  is introduced to complete  
 194 the theory, as the dual to parallel composition, and is used in subtyping proofs. Future work  
 195 may also use  $\wp$  as an additional modelling device that prevents one session from interfering  
 196 with another session. As a consequence of including the pair of multiplicatives, every session  
 197 type, has a dual type, its co-type, given by the function below.

198 ► **Definition 2** (co-type). Co-types are *defined by* the following mapping over types, prefixed

199 types and actions:

$$\begin{array}{lllll} \overline{\bigwedge_{i \in I} T_i} = \bigvee_{i \in I} \overline{T_i} & \overline{\bigvee_{i \in I} T_i} = \bigwedge_{i \in I} \overline{T_i} & \overline{\pi; T} = \overline{\pi} ; \overline{T} & \overline{! \lambda} = ? \lambda & ? \overline{\lambda} = ! \lambda \\ \overline{T \otimes U} = \overline{T} \wp \overline{U} & \overline{T \wp U} = \overline{T} \otimes \overline{U} & \overline{\mu t. T} = \mu t. \overline{T} & \overline{t} = t & \overline{OK} = OK \end{array}$$

200 In addition to the duality between the multiplicatives, described above, the de Morgan duality between  $\vee$  and  $\wedge$  is standard for session types. The co-type of a prefix action interchanges send and receive, and dualises the continuation. The unit  $OK$  is self-dual. Since we have only 201 guarded recursion, we treat fixed points equi-recursively, hence the fixed point operator is 202 self-dual. Intuitively, equi-recursive types are treated equivalently to their infinite unfoldings.

203 Note co-types and the use of two multiplicatives is optional in this work. Having co-types 204 reduces the number of rules in the next section by avoiding two sided sequents.

### 210 3.1 Deriving subtype judgements using the rules of Session

211 The rules of Session are defined in Fig. 3, using, in proof theoretic terms, a circular (or 212 cyclic) sequent calculus [9, 4] — which is, in type theoretical terms, a coinductive algorithmic 213 subtype system [47]. We employ an explicit algorithmic presentation of such a circular system 214 where we have an axiom [LEAF] which is enabled whenever there is a loop in the proof 215 returning to a sequent visited earlier in the proof. This algorithmic approach to coinduction 216 is standard in type theory [2], being sound and complete for infinite proofs such as these due 217 to the restriction to guarded recursion.

218 We explain the notation  $[\Theta] \Gamma \vdash$ . The sequent  $\Gamma$  is a (comma separated) multiset of 219 types, hence types in a sequent can commute (exchange) inside a sequent, but cannot be 220 duplicated (contraction) or removed (weakening). A **set of sequents**  $\Theta$ , where each sequent 221 in the set is separated using  $\|$ , is employed to define an algorithmic coinductive system, by 222 remembering sequents that may be revisited. We omit  $\Theta$  if it is empty.

223 ▶ **Remark 3.** Note that proof systems typically formalise *provability of formulae*, written  $\vdash T$ . 224 For a tight match with session type conventions (without breaking the logical convention 225 that  $\wedge$  is conjunctive), we instead formulate *provability of duals of formulae*. To emphasise 226 that we formulate probability of duals we write sequents as  $T \vdash$ , which is equivalent to  $\vdash \overline{T}$ .

227 **Subtypes.** Using co-types (Def. 2) and the rules in Fig. 3, subtyping can be defined as 228 follows. Note, a type is closed when no type variables appear free.

229 ▶ **Definition 4** (subtyping). *We say a closed type  $T$  is a subtype of another closed type  $U$ , 230 written  $T \leq U$ , whenever  $T, \overline{U} \vdash$  holds in Session.*

231 Note that in linear logic a linear implication  $T \multimap U$  holds whenever  $\overline{T \otimes U}$  is provable. 232 Translating to provability of duals, proving  $\overline{T \otimes U}$  is equivalent to establishing  $T, \overline{U} \vdash$ . 233 Indeed subtyping as defined above is a conservative extension of linear implication in linear 234 logic (with the mix rule). In what follows, we confirm that standard subtype judgements 235 are covered by the above definition. In addition, some additional subtype judgements hold, 236 which are particular to the multiparty setting.

237 We briefly highlight that most rules are standard rules from linear logic and coinductive 238 proof systems. Examples appear in the next section. Rules are well-defined over closed types.

239 **Rules from MALL.** Most rules of Session are rules of Multiplicative Additive Linear 240 Logic (MALL), dualised in order to formalise provability of duals. The rule [TIMES] breaks 241 down types into their parallel components. The rule [PAR] is required for subtyping in the 242 presence of parallelism. The axiom [OK] indicates that a protocol with no more actions has

$$\begin{array}{c}
\begin{array}{c}
\text{[OK]} \qquad \qquad \qquad \text{[LEAF]} \qquad \qquad \qquad \text{[FIX-}\mu\text{]} \\
\text{[}\Theta\text{] } \text{OK} , \text{ OK} , \dots \text{ OK} \vdash \qquad \qquad \text{[}\Theta\text{] } \llbracket \Gamma \rrbracket \Gamma \vdash \qquad \qquad \dfrac{}{\text{[}\Theta\text{] } \mu t.T , \Gamma \vdash \{^{\mu t.T}/t\} , \Gamma \vdash} \\
\text{[MEET]} \qquad \qquad \qquad \text{[JOIN]} \\
\text{[}\Theta\text{] } ?\lambda_j;T_j , \Gamma \vdash \text{ for some } j \in I \qquad \qquad \qquad \text{[}\Theta\text{] } !\lambda_j;T_j , \Gamma \vdash \text{ for all } j \in I \\
\hline
\text{[}\Theta\text{] } \bigwedge_{i \in I} ?\lambda_j;T_i , \Gamma \vdash \qquad \qquad \qquad \text{[}\Theta\text{] } \bigvee_{i \in I} !\lambda_j;T_i , \Gamma \vdash
\end{array} \\
\begin{array}{c}
\text{[PREFIX]} \qquad \qquad \qquad \text{[TIMES]} \qquad \qquad \qquad \text{[PAR]} \\
\text{[}\Theta\text{] } T , U , \Gamma \vdash \qquad \qquad \qquad \text{[}\Theta\text{] } T , U , \Gamma \vdash \qquad \qquad \qquad \text{[}\Theta\text{] } T , \Gamma_1 \vdash \text{ [}\Theta\text{] } U , \Gamma_2 \vdash \\
\text{[}\Theta\text{] } !\lambda;T , ?\lambda;U , \Gamma \vdash \qquad \qquad \qquad \text{[}\Theta\text{] } T \otimes U , \Gamma \vdash \qquad \qquad \qquad \text{[}\Theta\text{] } T \wp U , \Gamma_1 , \Gamma_2 \vdash
\end{array}
\end{array}$$

■ **Figure 3** A presentation of the algorithmic coinductive proof system **Session**. Note, to align with session type conventions, the system establishes provability of duals.

243 successfully terminated (this rule is valid for **MALL** with mix). Rules [JOIN] and [MEET] are  
 244 (dualised) standard rules for the additives of linear logic.

245 **Rules for equi-recursion.** Fixed points can be unfolded using the rule [FIX- $\mu$ ]. Axiom  
 246 [LEAF] is applied when we reach a previously visited sequent, completing a loop.

247 **Rule [Prefix].** The exception to the above established rules for equi-recursion and **MALL**  
 248 is the [PREFIX] rule. This is used to model an interaction between two processes where one  
 249 sends and the other receives. The rule enforces a causal order on interactions.

### 250 3.2 On notable admissible rules and algorithmic subtyping

251 For a proof system, we say a rule is *admissible*, whenever anything provable in the system  
 252 with the rule present is provable in the same system but with the rule removed. We highlight  
 253 the following three notable rules that are admissible in **Session**.

$$\begin{array}{c}
\begin{array}{c}
\text{[CUT]} \qquad \qquad \qquad \text{[INTR]} \qquad \qquad \qquad \text{[MIX]} \\
\text{[}\Theta\text{] } \Gamma_1 , T \vdash \text{ [}\Theta\text{] } \bar{T} , \Gamma_2 \vdash \qquad \qquad \dfrac{I \subseteq J \quad \text{[}\Theta\text{] } T_k , U_k , \Gamma \vdash \text{ for all } k \in I}{\text{[}\Theta\text{] } \bigvee_{i \in I} !\lambda_i;T_i , \bigwedge_{j \in J} ?\lambda_j;U_j , \Gamma \vdash} \qquad \qquad \dfrac{\text{[}\Theta\text{] } \Gamma_1 \vdash \text{ [}\Theta\text{] } \Gamma_2 \vdash}{\text{[}\Theta\text{] } \Gamma_1 , \Gamma_2 \vdash}
\end{array}
\end{array}$$

255 **Cut elimination and algorithmic subtyping.** The admissibility of [CUT], called  
 256 cut elimination, is the corner stone of proof theory, since many results in logic (e.g., the  
 257 consistency of classical logic) can be proven as corollaries of cut elimination. Since cut  
 258 elimination justifies that rules are consistently defined, we present cut elimination in **Session**  
 259 as a theorem.

260 ▶ **Theorem 5** (cut elimination). *The [CUT] rule is admissible in **Session**.*

261 To see that the above holds, observe that, trivially, the unfolding of a proof in **Session** to  
 262 infinite proofs (over infinitely unfolded terms) is sound, and, due to regularity, complete  
 263 (i.e., an infinite proof will always eventually loop on every branch, allowing [LEAF] to be  
 264 applied). Thus it is sufficient to show that cut elimination holds for the finite proof system.  
 265 This follows by observing that the standard normalisation steps for **MALL**, plus cases for

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266 [PREFIX], can be applied to unfold a cut free proof to an arbitrary depth. We show only the  
 267 principal case for [PREFIX], which is given by the following proof normalisation step.

$$\frac{\frac{\frac{\Gamma_1, U, T \vdash}{\Gamma_1, ?\lambda; U, !\lambda; T \vdash} \quad \frac{\bar{T}, V, \Gamma_2 \vdash}{? \lambda; \bar{T}, !\lambda; V, \Gamma_2 \vdash}}{? \lambda; T, !\lambda; V, \Gamma_2 \vdash} \text{[CUT]}}{\Gamma_1, ?\lambda; U, !\lambda; V, \Gamma_2 \vdash} \sim \frac{\frac{\Gamma_1, U, T \vdash \quad \bar{T}, V, \Gamma_2 \vdash}{\Gamma_1, U, V, \Gamma_2 \vdash} \text{[CUT]}}{\Gamma_1, ?\lambda; U, !\lambda; V, \Gamma_2 \vdash}$$

269 An immediate consequence of cut elimination for session types is that subtyping relation  
 270  $\leq$  is transitive. It is also reflexive by a simple induction on the structure of types.

271 ▶ **Corollary 6.** *If  $T \leq U$  and  $U \leq V$ , then  $T \leq V$ . Also, we have  $T \leq T$ .*

272 From the perspective of type theory this is a standard result that **must** hold in order to  
 273 recommend an *algorithmic subtype system*. An algorithmic subtype system is expressed  
 274 without a cut (or transitivity) rule, since cut violates what is known as the *sub-formula*  
 275 *property*. The sub-formula property states that every formula appearing in the premise is a  
 276 sub-formula of one of formulae appearing in the conclusion (up to unfolding of equi-recursion,  
 277 which is allowed here due to regularity). The sub-formula property guarantees that proof  
 278 search in Session terminates.

279 **Admissibility of [INTR].** Established algorithmic subtype systems usually employ a  
 280 rule of the form [INTR]. That rule can be simulated by using [JOIN], [MEET] and [PREFIX],  
 281 without loss of expressive power. For example, the following sequent, provable using the rule  
 282 [INTR] is also provable as follows.

$$\frac{\frac{\frac{\frac{\overline{\text{OK}}, \text{OK} \vdash}{? \lambda_1, !\lambda_1 \vdash} \text{[PREFIX]}}{(? \lambda_1 \wedge ? \lambda_2), !\lambda_1 \vdash} \text{[MEET]}}{(? \lambda_1 \wedge ? \lambda_2), (!\lambda_1 \vee !\lambda_2) \vdash} \text{[JOIN]}}{\frac{\frac{\overline{\text{OK}}, \text{OK} \vdash}{? \lambda_2, !\lambda_2 \vdash} \text{[PREFIX]}}{(? \lambda_1 \wedge ? \lambda_2), !\lambda_2 \vdash} \text{[MEET]}}{(? \lambda_1 \wedge ? \lambda_2), (!\lambda_1 \vee !\lambda_2) \vdash} \text{[JOIN]}$$

284 However, we cannot simulate all proofs involving the three rules discussed above, if, instead,  
 285 only [INTR] is employed. The following cannot be proven using only [INTR].

$$\frac{\frac{\frac{\frac{\overline{\text{OK}}, \text{OK}, \text{OK} \vdash}{! \lambda_3, \text{OK}, ? \lambda_3 \vdash} \text{[PREFIX]}}{! \lambda_3, \text{OK}, ? \lambda_2 \wedge ? \lambda_3 \vdash} \text{[MEET]}}{! \lambda_1; ! \lambda_3, ? \lambda_1, ? \lambda_2 \wedge ? \lambda_3 \vdash} \text{[PREFIX]}}{! \lambda_1; ! \lambda_3, ? \lambda_1 \wedge ? \lambda_4, ? \lambda_2 \wedge ? \lambda_3 \vdash} \text{[MEET]}}{! \lambda_1; ! \lambda_3 \vee ! \lambda_2; ! \lambda_4, ? \lambda_1 \wedge ? \lambda_4, ? \lambda_2 \wedge ? \lambda_3 \vdash} \text{[JOIN]}$$

287 The following is an example of a coinductive proof that, similarly to the above proof,  
 288 cannot be established using only [INTR]. In the following proof, assume  $T = \mu t.(!\lambda_1; t \vee !\lambda_2; t)$ ,  
 289  $U = \mu u.(? \lambda_1; u)$ , and  $V = \mu v.(? \lambda_2; v)$ . We also abbreviate sequents  $\Gamma = T, U, V$  and  
 290  $\Gamma' = !\lambda_1; T, U, V$  and  $\Gamma'' = !\lambda_2; T, U, V$ , but notice only  $\Gamma$  is used rule [LEAF].

$$\frac{\frac{\frac{\frac{\overline{[\Gamma'] \llbracket \Gamma] \Gamma \vdash}}{[\Gamma' \llbracket \Gamma] ! \lambda_1; T, ? \lambda_1; U, V \vdash} \text{[PREFIX]}}{[\Gamma] ! \lambda_1; T, U, V \vdash} \text{[FIX-}\mu\text{]}}{\frac{\frac{\overline{[\Gamma''] \llbracket \Gamma] \Gamma \vdash}}{[\Gamma'' \llbracket \Gamma] ! \lambda_2; T, U, ? \lambda_2; V \vdash} \text{[PREFIX]}}{[\Gamma] ! \lambda_2; T, U, V \vdash} \text{[FIX-}\mu\text{]}}}{\frac{[\Gamma] ! \lambda_1; T \vee ! \lambda_2; T, U, V \vdash}{\frac{[\Gamma] ! \lambda_1; T, U, V \vdash}{\frac{[\Gamma] T, U, V \vdash}{T, U \otimes V \vdash}} \text{[FIX-}\mu\text{]}}} \text{[JOIN]}} \text{[FIX-}\mu\text{]}} \text{[TIMES]}$$

292 Notice, the above proof establishes  $\mu\mathbf{u}.(\lambda_1;\mathbf{u}) \otimes \mu\mathbf{v}.(\lambda_2;\mathbf{v}) \leq \mu\mathbf{t}.(\lambda_1;\mathbf{t} \wedge \lambda_2;\mathbf{t})$  — a subtype  
 293 judgement decomposing a single threaded participant into two concurrent threads.

294 **Admissibility of [Mix].** The fact that the [Mix] rule is admissible allows scenarios  
 295 where separate parallel communications can occur. For example, the subtype judgement  
 296  $\lambda_1 \otimes \lambda_1 \otimes \lambda_2 \otimes \lambda_2 \leq \text{ok}$  (which also holds in pure linear logic **with** mix only), can be  
 297 established by the following proof in **Session without** using mix.

$$\frac{\overline{\text{OK}, \text{OK}, \text{OK}, \text{OK}, \text{OK} \vdash} \quad [\text{OK}]}{\lambda_1, \lambda_1, \lambda_2, \lambda_2, \text{OK} \vdash} \quad [\text{PREFIX}] \text{ (twice)} \\ \frac{\lambda_1, \lambda_1, \lambda_2, \lambda_2, \text{OK} \vdash \quad [\text{PREFIX}] \text{ (twice)}}{\lambda_1 \otimes \lambda_1 \otimes \lambda_2 \otimes \lambda_2, \text{OK} \vdash} \quad [\text{TIMES}] \text{ (twice)}$$

299 The admissibility of [Mix] is a corollary of Theorem 5.

### 300 3.3 Typing multiparty compatible networks, by using subtyping

301 The syntax of processes is defined by the following grammar.

302 ▶ **Definition 7** (Processes). Processes for threads *are defined by*:

$$303 \quad \mathbb{P} ::= \Sigma_{i \in I} ?\lambda_i; \mathbb{P}_i \mid \oplus_{i \in I} !\lambda_i; \mathbb{P}_i \mid \mu X. \mathbb{P} \mid X \mid 1$$

304 Processes for networks *are defined by grammar*:  $\mathbb{N} ::= \mathbb{P} \mid \mathbb{N} \parallel \mathbb{N}$ .

305 We simply refer to both of the above as processes, ranged over by  $P, Q, R, \dots$ .

306 Internal choice  $\oplus$  defines a process ready to perform **any** of the given outputs, and external  
 307 choice  $\sum$  indicates a process ready to perform **some** input. We typically abbreviate  $!\lambda; P$   
 308 and  $!\lambda_1; P_1 \oplus !\lambda_2; P_2$  for the unary and binary versions of the above external choice. Similarly,  
 309  $? \lambda; P$  and  $? \lambda_1; P_1 + ? \lambda_2; P_2$  can be used for internal choices.

$$\frac{\Delta \vdash P_i : \mathbb{T}_i \ (i \in I)}{\Delta \vdash \Sigma_{i \in I} ?\lambda_i; P_i : \bigwedge_{i \in I} ?\lambda_i; \mathbb{T}_i} \quad [\text{T-EXTCH}] \quad \frac{\Delta \vdash P_i : \mathbb{T}_i \ (i \in I)}{\Delta \vdash \oplus_{i \in I} !\lambda_i; P_i : \bigvee_{i \in I} !\lambda_i; \mathbb{T}_i} \quad [\text{T-INTCH}] \\ \Delta, X : \mathbf{t} \vdash X : \mathbf{t} \quad [\text{T-VAR}] \quad \frac{\Delta, X : \mathbf{t} \vdash P : \mathbb{T}}{\Delta \vdash \mu X. P : \mu \mathbf{t}. \mathbb{T}} \quad [\text{T-REC}] \\ \frac{\Delta \vdash P : \mathbb{T} \quad \Delta \vdash Q : \mathbb{U}}{\Delta \vdash P \parallel Q : \mathbb{T} \otimes \mathbb{U}} \quad [\text{T-PAR}] \quad \Delta \vdash 1 : \text{ok} \quad [\text{T-1}] \quad \frac{\Delta \vdash P : \mathbb{T} \quad \mathbb{T} \leq \mathbb{U}}{\Delta \vdash P : \mathbb{U}} \quad [\text{SUBSUMPTION}]$$

■ **Figure 4** Typing rules for processes, making use of the subtype relation  $\leq$  in Def. 4.

310 Multiparty compatible processes are those with type **ok**. Note, for any interesting example,  
 311 this will involve applying SUBSUMPTION.

312 ▶ **Definition 8** (compatibility). *Process  $P$  is multiparty compatible whenever  $\vdash P : \text{ok}$ , ac-  
 313 cording to the rules of Fig. 4, where environment  $\Delta$  associates process variables to type  
 314 variables.*

315 Any application of the [SUBSUMPTION] rule can always be delayed to the final step. I.e.,  
 316 we calculate the minimal type for the whole network, then apply [SUBSUMPTION].

317 ▶ **Theorem 9** (algorithmic typing). *If  $\vdash P : \mathbb{U}$  then we can construct a  $\mathbb{T}$  such that  $\mathbb{T} \leq \mathbb{U}$   
 318 holds and  $\vdash P : \mathbb{T}$  holds without using the [SUBSUMPTION] rule.*

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319 The above result is another consequence of cut elimination.

320 An immediate consequence is that, if  $P$  is multiparty compatible, there exists  $T$  such that  
 321  $\vdash P : T$ , without using the *subsumption* rule, and  $T \vdash$  holds. For example, proofs from the  
 322 previous section can be used to establish that networks such as the following are multiparty  
 323 compatible:  $! \lambda_1; ! \lambda_3 \oplus ! \lambda_2; ! \lambda_4 \parallel ? \lambda_1 + ? \lambda_4 \parallel ? \lambda_2 + ? \lambda_3$  and  $\mu t. (! \lambda_1; t \oplus ! \lambda_2; t) \parallel \mu u. (? \lambda_1; u) \parallel \mu v. (? \lambda_2; v)$ . Furthermore, the multiparty compatibility of the processes from Sec. 2 can be  
 325 established in this way.

326 **Note on open sessions.** We select a flexible presentation in Fig. 4, since, as a bonus,  
 327 we can also use the above type system to reason about open sessions, which may be  
 328 missing participants in order for multiparty compatibility to hold. For example, by using  
 329 [SUBSUMPTION] and the processes from Sec. 2, we have the following type judgement.

$$330 \quad \vdash Owner \parallel Untrusted\ App \parallel OAuth\ Server : \mu t. (!release \oplus !request(token); \\ (?revoke + ?response(data); t))$$

331 The above type judgement indicates an “interface” exposed by the open session given by  
 332 network  $Owner \parallel Untrusted\ App \parallel OAuth\ Server$ . Hence, if composed with a process that  
 333 interacts with the interface given by the dual of the above type (such as *Resource* from  
 334 Sec 2) we can judge the whole system to be multiparty compatible. Composition of two  
 335 open sessions can be performed by using [T-PAR] and then applying [SUBSUMPTION] to the  
 336 resulting type to show that, together, they inhabit type  $\text{ok}$ , assuming that together the  
 337 processes are multiparty compatible (alternatively, when composed, they may expose another  
 338 interface if the composition of two open sessions is still an open session). Note this achieves  
 339 the same effect as applying a rule of the following form.

$$340 \quad \frac{\Delta \vdash P : T \otimes U \quad \Delta \vdash Q : \bar{U} \otimes V}{\Delta \vdash P \parallel Q : T \otimes V} \text{ [T-CUT]}$$

341 The above rule, derivable using [T-PAR] and [SUBSUMPTION], achieves the effect of a “con-  
 342 necting cut”, as desired in recent work on open multiparty sessions [6].

### 343 3.4 Guaranteeing deadlock freedom (via race freedom)

344 In order to prove deadlock freedom of multiparty compatible networks, we require a reduction  
 345 system for closed networks, defined by the rules in Fig. 5. As standard [17], different  
 346 behaviours are forced for internal choice and external choice. When ranging over all executions,  
 347 for external choice, we consider all branches, as indicated by the transition rule for *internal*  
 348 *choice* ( $\oplus$ ). Notice that, in order for a communication to occur, we must have committed to  
 349 a single branch of the internal choice, forcing all branches to be resolved. However, we need  
 350 only select one of the inputs with the corresponding output label in an external choice ( $\sum$ )  
 351 for a communication to occur.

$$\begin{array}{c} \frac{j \in I}{\oplus_{i \in I} ! \lambda_i; Q_i \longrightarrow ! \lambda_j; Q_j} \quad \frac{j \in I}{! \lambda_j; P \parallel \sum_{i \in I} ? \lambda_i; Q_i \longrightarrow P \parallel Q_j} \quad \frac{}{\text{rec} X. P \longrightarrow P \{ \text{rec} X. P / x \}} \\ \hline \frac{P \longrightarrow P'}{P \parallel Q \longrightarrow P' \parallel Q} \quad \frac{P \equiv P' \quad P' \longrightarrow Q' \quad Q' \equiv Q}{P \longrightarrow Q} \quad \frac{P \parallel (Q \parallel R) \equiv (P \parallel Q) \parallel R}{P \parallel Q \equiv Q \parallel P} \quad \frac{P \parallel P \equiv P}{P \parallel 1 \equiv P} \end{array}$$

■ **Figure 5** Reduction system for networks.

352     **Race freedom.** Some multiparty compatible networks with race conditions are not  
 353     deadlock free. Races can be avoided by naming participants and ensuring each branch of an  
 354     external choice awaits a message from the same participant but is labelled differently compared  
 355     to other branches of that external choice. For example, the following multiparty compatible  
 356     networks have races, hence should be rejected. For network  $! \lambda_1; ! \lambda_2 \oplus ! \lambda_1; ! \lambda_3 \parallel ? \lambda_1; ? \lambda_2 + ? \lambda_1; ? \lambda_3$ ,  
 357     when  $\lambda_1$  is sent it may be received by the wrong branch of the external choice resulting in  
 358     deadlock. Similarly, network  $! \lambda_1; ? \lambda_2 \parallel ! \lambda_1 \parallel ? \lambda_1; ! \lambda_2; ? \lambda_1$ , may deadlock if the second process  
 359     engages in a communication before the first.

360     While explicitly naming participants, as described above, would avoid such examples, for  
 361     added flexibility we show that we can also achieve race freedom without naming participants.  
 362     This additional flexibility is necessary for examples such as in Sec. 2, where one participant  
 363     is replaced by two or more participants (hence if participants were named we would require a  
 364     mechanism such as internal delegation [13] to allow one participant act on behalf of another).  
 365     An added benefit of avoiding races without naming participants is that we may guarantee  
 366     race freedom without relying on participant names to guide reductions.

367     Race freedom can be formulated in terms of a type inference problem using the race type  
 368     system in Fig. 6, where  $A$  *race type* is of the form  $\langle o:\alpha, i:\chi \rangle$ , where  $\alpha$  and  $\chi$  are sets of sets  
 369     of labels. The former,  $\alpha$ , represents a set of sets of output labels — one set of labels for each  
 370     thread in a network. The latter  $\chi$  represents a set of sets of inputs — one set of labels for  
 371     each external choice somewhere in the network. We also require a “participant condition”  
 372     ensuring all branches of a choice talk to the same process, formalised as follows.

373     ► **Definition 10.** A race type  $\langle o:\alpha, i:\chi \rangle$  satisfies the participant condition whenever, for  
 374     all  $x \in \chi$  and  $y, z \in \alpha$ , if  $x \cap y \neq \emptyset$  and  $x \cap z \neq \emptyset$  then  $y = z$ . A process  $P$  is race free,  
 375     whenever there exists a race type  $\langle o:\alpha, i:\chi \rangle$  satisfying the participant condition such that  
 376      $\vdash P : \langle o:\alpha, i:\chi \rangle$  using the rules of Fig. 6.

$$\begin{array}{c}
 \frac{\Sigma \vdash P_i : \langle o:\{x_i\}, i:\chi_i \rangle \ (i \in I) \quad (\forall i, j \in I) \lambda_i = \lambda_j \text{ implies } i = j}{\Sigma \vdash \Sigma_{i \in I} ? \lambda_i; P_i : \left\langle o: \left\{ \bigcup_{i \in I} x_i \right\}, i: \bigcup_{i \in I} \chi_i \cup \{ \{ \lambda_i : i \in I \} \} \right\rangle} \text{ [R-EXTCH]} \\
 \\ 
 \frac{\Sigma \vdash P_i : \langle o:\{x_i\}, i:\chi_i \rangle \ (i \in I)}{\Sigma \vdash \oplus_{i \in I} ! \lambda_i; P_i : \left\langle o: \left\{ \bigcup_{i \in I} x_i \cup \{ \lambda_i : i \in I \} \right\}, i: \bigcup_{i \in I} \chi_i \right\rangle} \text{ [R-INTCH]} \\
 \\ 
 \frac{\Sigma \vdash P : \langle o:\alpha, i:\chi \rangle \quad \Sigma \vdash Q : \langle o:\beta, i:\zeta \rangle \quad \left( \bigcup \alpha \right) \cap \left( \bigcup \beta \right) = \emptyset \quad \left( \bigcup \chi \right) \cap \left( \bigcup \zeta \right) = \emptyset}{\Sigma \vdash P \parallel Q : \langle o:\alpha \cup \beta, i:\chi \cup \zeta \rangle} \text{ [R-PAR]} \\
 \\ 
 \Sigma, X : \langle o:\alpha, i:\chi \rangle \vdash X : \langle o:\alpha, i:\chi \rangle \quad \text{[R-VAR]} \qquad \Sigma \vdash 1 : \langle o:\emptyset, i:\emptyset \rangle \quad \text{[R-1]} \\
 \\ 
 \frac{\Sigma, X : \langle o:\alpha, i:\chi \rangle \vdash P : \langle o:\alpha, i:\chi \rangle}{\Sigma \vdash \mu X. P : \langle o:\alpha, i:\chi \rangle} \text{ [R-REC]}
 \end{array}$$

■ **Figure 6** Type rules for checking race freedom.

377     The above *race-freedom* property we propose is satisfied whenever the unfolding of all

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378 fixed points of a process satisfies the following:

- 379   ■ Branches of an external choice use distinct labels for their **immediately enabled** inputs  
(see [R-EXTCH]).
- 380   ■ For any external choice, the set of immediately enabled input labels in an external choice  
381   must be disjoint from the set of all output labels of **all but one** of the parallel components  
382   (the *participant condition*). This ensures one participant is listening to at most one other  
383   participant at a time.
- 384   ■ For parallel processes,  $P \parallel Q$ , the set of **all** input labels of  $P$  and the set of **all** input  
385   labels of  $Q$  are disjoint; and, similarly, the sets of all output labels of  $P$  and  $Q$  are disjoint  
386   (see [R-PAR]).

388   The above property is efficient to check, since it simply builds up the relevant sets of sets  
389   of labels. Note, a single thread always has a singleton set of outputs.

390   A critical example the participant condition rejects is the following process, which is of  
391   the race type indicated below.

392    $\vdash !\lambda_1 \parallel \text{rec}X. (?\lambda_1 + ?\lambda_2; X) \parallel \text{rec}Y. !\lambda_2; Y: \langle o: \{\{\lambda_1\}, \emptyset, \{\lambda_2\}\}, i: \{\{\lambda_1, \lambda_2\}\} \rangle$

393   The above example processes contains a race. Two parallel outputs with different labels  
394   contact a process ready to receive a message from either process and, if actions labelled  
395    $\lambda_1$  are played, the process deadlocks. The above example is forbidden by the participant  
396   condition since we have  $\{\lambda_1, \lambda_2\} \cap \{\lambda_1\} \neq \emptyset$  and  $\{\lambda_1, \lambda_2\} \cap \{\lambda_2\} \neq \emptyset$  but  $\{\lambda_1\} \neq \{\lambda_2\}$ .

397   **Deadlock freedom.** Deadlock freedom can be defined as follows (coinductively): at any  
398   point we can either make progress or we have successfully terminated.

399   ► **Definition 11** (deadlock freedom). *A network  $P$  is deadlock free whenever:*

- 400   ■ *either  $P \equiv 1$ , or there exists network  $Q$  such that  $P \rightarrow Q$ ;*
- 401   ■ *and, for all  $R$  such that  $P \rightarrow R$  we have  $R$  is deadlock free.*

402   The theory developed in this work guarantees deadlock freedom as in Def. 11.

403   ► **Theorem 12.** *Any race-free multiparty-compatible network satisfies deadlock freedom.*

404   The proof of this result [see Appendix] relies on Theorem 5 and builds on novel proof  
405   normalisation techniques developed for giving computational interpretations of formulae in  
406   extensions of linear logic [35, 36].

407   ► **Remark 13.** Note often deadlock freedom is referred to as “progress” which is an overloaded  
408   word in the literature. Deadlock freedom does not necessarily prevent starvation, as for  
409   notions such as lock freedom [37, 46]. Restricted variants of **Session** can be tightened to  
410   enforce stronger liveness properties — an observation deserving of attention in future work.

411   Soundness of the subtype system with respect to our multithreaded liberalisation of the  
412   substitution principle [25] is precisely formulated below, which is an immediate consequence  
413   of Theorem 5 and Theorem 12. Notice the flexible subtype system in this work, which permits  
414   networks consisting of parallel threads to be compared, allows a thread to be substituted by  
415   more than one thread, as motivated in Sec. 2.

416   ► **Corollary 14** (substitution principle). *Assume  $P$ ,  $Q$  and  $R$  are closed networks. If  $\vdash P: \mathsf{T}$ ,*  
417    *$\vdash Q: \mathsf{T}'$  and  $\mathsf{T} \leq \mathsf{T}'$ , then if  $\vdash Q \parallel R: \text{ok}$ , and  $P \parallel R$  is race free, then  $P \parallel R$  is deadlock free.*

418 **Proof.** Assume  $\vdash P: T$  and  $\vdash Q: T'$  without using [SUBSUMPTION], and also assume  $T \leq T'$ ,  
 419  $\vdash Q \parallel R: \text{ok}$  and  $P \parallel R$  is race free. By Theorem 9, there exists a type  $U$  such that  $\vdash Q \parallel R: U$   
 420 without using [SUBSUMPTION] and  $U \leq \text{ok}$ . By Lemma 15 there exists  $V$  such that  $U = T' \otimes V$   
 421 and  $\vdash P \parallel R: T' \otimes V$  without using [SUBSUMPTION]. By Theorem 5, we have  $T \otimes V \leq T' \otimes V$ ,  
 422 and hence, by Theorem 5 again,  $T \otimes V \leq \text{ok}$ . Thereby  $\vdash P \parallel R: \text{ok}$ , and hence, by race freedom  
 423 and Theorem 12, we have  $P \parallel R$  is deadlock free, as required.  $\blacktriangleleft$

424 **Importance of avoiding races.** The following example emphasises the importance of  
 425 checking races are avoided. Consider the multiparty compatible network  $1 \parallel !\lambda_1 \parallel (\lambda_1 + ?\lambda_2)$ .  
 426 Observe we have  $\vdash !\lambda_2 \parallel ?\lambda_2 : \text{ok}$  hence process 1 can be substituted by  $!\lambda_2 \parallel ?\lambda_2$  while  
 427 preserving multiparty compatibility. Now, if we remove the condition concerning races in  
 428 the substitution principle, after applying the above substitution in the network at the top of  
 429 the paragraph, we should have  $!\lambda_2 \parallel ?\lambda_2 \parallel !\lambda_1 \parallel (\lambda_1 + ?\lambda_2)$  is deadlock free. However, this  
 430 network is in fact not deadlock free, due to the presence of a race.

431 Note our race-freedom property does not require output labels in an internal choice  
 432 to be distinct. For example, the network  $(! \lambda_1; \lambda_2 \oplus ! \lambda_1; \lambda_3) \parallel ? \lambda_1; (? \lambda_2 + ? \lambda_3)$  is race free,  
 433 multiparty compatible and deadlock free. Note this is example would not be typeable using  
 434 established session type systems.

## 435 3.5 Typeable sessions for which there is no global type

436 Multiparty compatibility is defined independently from global types. Theories that rely  
437 on global types run into the problem that many reasonable protocols have no global type.  
438 Such problematic protocols typically feature branching under a recursion where different  
439 participants are contacted in each branch. The problem of typing protocols for which there  
440 is no established theory in which they can be assigned a global type has been explored in  
441 recent work [48].

442 To emphasise that `Session` can also be used to type multiparty sessions for which there is  
 443 no global type, we adapt one of the key examples from related work (Figure 4, (2) [48]). In  
 444 this recursive two-buyer protocol a buyer repeatedly asks another buyer to split the price.  
 445 Assume we have the following types.

- 446 ■  $T_A = !query; ?price; \mu t. T_1$  where  $T_1 = (!split; T_2 \vee !cancel; !no)$  and  $T_2 = (?yes; !buy \wedge$   
 447  $?no; t)$
  - 448 ■  $T_B = \mu t. T_3$  where  $T_3 = (?split; T_4 \wedge ?cancel)$  and  $T_4 = !yes \vee !no; t$
  - 449 ■  $T_S = ?query; !price; T_5$  where  $T_5 = ?buy \wedge ?no.$

450 Also assume we have sequents  $\Gamma = \mu t. T_1, T_5, T_B$  and  $\Gamma' = T_1\{\mu t. T_1/t\}, T_5, T_B$   
 451 (only the former is used in a [LEAF] axiom). The following proof can be used to establish  
 452  $T_A \otimes T_B \otimes T_S \leq \text{OK}$ , which can be used in a multiparty compatibility judgement. Notice we  
 453 use the admissible compound rule [INTR] to shorten the proof.

$\frac{[\Gamma' \parallel \Gamma] \text{ ok , ok , ok } \vdash}{[\Gamma' \parallel \Gamma] \text{ !buy , } T_5 , \text{ ok } \vdash} \text{ [INTR]}$	$\frac{[\Gamma' \parallel \Gamma] \text{ ok , ok , ok } \vdash}{[\Gamma' \parallel \Gamma] \text{ !no , } T_5 , \text{ ok } \vdash} \text{ [INTR]}$
$\frac{[\Gamma' \parallel \Gamma] \text{ !buy , } T_5 , \text{ ok } \vdash \quad [\Gamma' \parallel \Gamma] \mu t. T_1 , T_5 , T_B \vdash}{[\Gamma' \parallel \Gamma] T_2 \{ \mu t. T_1 / t \} , T_5 , T_4 \{ \mu t. T_3 / t \} \vdash} \text{ [LEAF]}$	$\frac{[\Gamma' \parallel \Gamma] \text{ ok , ok , ok } \vdash}{[\Gamma' \parallel \Gamma] \text{ !no , } T_5 , \text{ ok } \vdash} \text{ [INTR]}$
$\frac{[\Gamma' \parallel \Gamma] T_1 \{ \mu t. T_1 / t \} , T_5 , T_3 \{ \mu t. T_3 / t \} \vdash}{[\Gamma] T_1 \{ \mu t. T_1 / t \} , T_5 , T_B \vdash} \text{ [FIX-}\mu\text{]}$	$\frac{[\Gamma' \parallel \Gamma] \text{ ok , ok , ok } \vdash}{[\Gamma' \parallel \Gamma] \text{ !no , } T_5 , \text{ ok } \vdash} \text{ [INTR]}$
$\frac{[\Gamma] T_1 \{ \mu t. T_1 / t \} , T_5 , T_B \vdash \quad [\mu t. T_1 , T_5 , T_B \vdash]}{\mu t. T_1 , T_5 , T_B \vdash} \text{ [FIX-}\mu\text{]}$	
$\frac{?price ; \mu t. T_1 , !price ; T_5 , T_B \vdash}{T_A , T_S , T_B \vdash} \text{ [PREFIX]}$	

455 In the above example, it is possible that processes typed with  $T_A$  and  $T_B$  negotiate forever and  
 456 a process typed with  $T_S$ , after reaching a state typed by  $T_5$ , waits forever. Such starvation is  
 457 permitted by our classic notion of progress in Def. 11, i.e., deadlock freedom.

## 4 Related Work and Future Work

459 A closely related line of work studies the problem of synthesising a “coherent” global type  
 460 for multi-party compatible types [43]. The approach in the current paper can be used to  
 461 expose the structural proof theoretic content of a closely related system proposed for such  
 462 a synthesis problem [38]. There is much work providing notions of semantic subtyping for  
 463 session types [7, 5, 45], whose resulting systems can be interpreted proof theoretically using  
 464 subsystems and variants of **Session** (at least for the first-order fragment without delegation).

465 It could be valuable to explore connections between **Session**, which follows a processes-as-  
 466 formulas approach, and a variety of Curry-Howard inspired systems. There are intersection  
 467 type systems, satisfying subject expansion, that completely characterise deadlock freedom  
 468 for a fragment of the asynchronous  $\pi$ -calculus where a name can only be used as an input  
 469 channel by the process that created the name [16]. Process in that work are quite different  
 470 from those in our session calculus, since, in this work, we neither consider channel passing  
 471 (delegation) nor asynchrony, while they do not consider choice. Challenges concerning duality  
 472 of binary sessions in the presence of delegation and recursion are explored through a linear  
 473  $\lambda$ -calculus typed using explicit least and greatest fixedpoints rather than equi-recursion [40].  
 474 Regarding circular proofs, Derakhshan and Pfenning propose a calculus for binary sessions  
 475 with delegation in a Curry-Howard style [22]. In their work, they propose a locally checkable  
 476 condition that guarantees a well-typed session will always terminate either in an empty  
 477 configuration or a configuration attempting to communicate along external channels.

478 In future work, it would be valuable to investigate variants of the rules, notably a focussed  
 479 variant of **Session** [3, 4]. In a focussed system, rules such as **JOIN** are treated *asynchronously*,  
 480 meaning that we can immediately apply the rule without backtracking; whereas rules such  
 481 as **MEET** are *synchronous*, meaning that, in general, backtracking may be required during  
 482 proof search. The important observation is that, for race-free sessions there will only be one  
 483 way to apply synchronous rules, thereby eliminating the need to backtrack in the search for  
 484 a proof, i.e., proof search can be conducted deterministically. The ability to search for proofs  
 485 in this uniform manner is connected with goal-directed search in logic programming [42].

486 The system designed in this work preserves deadlock freedom for race-free processes,  
 487 as established in Theorem 12; but does not guarantee stronger livelock freedom properties  
 488 (sometimes referred to as lock freedom) [37, 46, 49]. Livelock freedom strengthens deadlock  
 489 freedom by ensuring that no parties are starved of resources; however, there are many subtle  
 490 variations on precisely how livelock freedom is defined. Hence we push the investigation of  
 491 refinements of **Session** that can guarantee notions livelock freedom to future work.

492 To illustrate the above point, we observe some more unexpected properties of **Session**.  
 493 Observe, the process  $\mu X.\lambda_1; X \parallel \lambda_2 \parallel \mu Y.\lambda_1; Y$  is race-free and multiparty compatible, and  
 494 hence deadlock free. However, it has a hanging input  $\lambda_2$  that never receives a message,  
 495 hence it is not livelock free in any sense. Using a proof of the multiparty compatibility  
 496 of the above process, we can also establish subtype judgement  $\mu t.\lambda_1; t \otimes \lambda_2 \leq \mu t.\lambda_1; t$ .  
 497 This subtype judgements allows inactive parallel components to be typed using the subtype  
 498 system, as long as they rest of the system is deadlock free. Thus the current formulation of  
 499 **Session** guarantees no property stronger than deadlock freedom.

500 For a more subtle example outside the scope of established session type systems, consider

501 the types  $T = \mu t.(!\lambda_1; t \vee !\lambda_2; !\lambda_3)$  and  $U = \mu t.(?\lambda_1; t \wedge ?\lambda_2)$ . We have  $T \otimes U \leq !\lambda_3$  thus a  
 502 thread that sends  $\lambda_2$  can be replaced by two threads that may choose to talk internally on  
 503  $\lambda_1$  forever, although there is always the possibility of a branching taken where  $\lambda_3$  is sent.  
 504 This subtype judgement does preserve some notions of livelock freedom (it is always possible  
 505 for everyone to eventually act [46]), but not stronger notions of livelock freedom (always  
 506 everyone must act eventually [37]). An objective for future work would be to explain how  
 507 Session can be refined by restricting circular proofs so that they preserve a strong form of  
 508 livelock freedom. The key idea is to check that at all threads in a network act at least once  
 509 in every unfolding of a recursion, thereby rejecting both subtype judgements above.

510 **5 Conclusion**

511 The proof calculus Session, introduced in Fig. 3, showcases tools of structural proof theory,  
 512 i.e., analytic calculi satisfying cut elimination (Theorem 5), which can be used in the design  
 513 of rich multiparty session type systems. Session defines an algorithmic subtype system  
 514 (Definition 4), the transitivity of which follows from cut elimination (Corollary 6). The  
 515 subtype system admits a more flexible substitution principle (Corollary 14) than standard.  
 516 This flexibility enables subtyping to be used directly to decide multiparty compatibility  
 517 (Definition 8) and also opens up fresh problems that can be tackled using subtyping, not  
 518 limited to scenarios where extra parallelism is introduced, as illustrated in Sec. 2.

519 Race freedom may be guaranteed by naming participants; however, for extra flexibility we  
 520 propose a type system for race freedom (Definition 10). From these definitions, we establish  
 521 our main result (Theorem 12) guaranteeing deadlock freedom for networks that are both  
 522 multiparty compatible and race free. In this line of work, global types are optional, allowing  
 523 networks for which no global type exists to be typed.

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## 662 A Proof of Theorem 12: well-typed networks are deadlock free

663 We require the following standard lemmas, which follow by structural induction.

664 ▶ **Lemma 15** (inversion lemma). *In the following, we do not use the subsumption rule.*

- 665 ■ *If  $\vdash P \parallel Q : T$ , there exists  $U$  and  $V$  such that  $T = U \otimes V$  and  $\vdash P : U$  and  $\vdash Q : V$ .*
- 666 ■ *If  $\vdash \bigoplus_{i \in I} !\lambda_i; P_i : T$ , there exists  $T_i$  such that  $T = \bigvee_{i \in I} !\lambda_i; T_i$  and  $\vdash P_i : T_i$ .*
- 667 ■ *If  $\vdash \Sigma_{i \in I} ?\lambda_i; P_i : T$ , there exists  $T_i$  such that  $T = \bigwedge_{i \in I} ?\lambda_i; T_i$  and  $\vdash P_i : T_i$ .*
- 668 ■ *If  $\vdash \text{rec}X.P : T$ , there exists  $U$  and  $t$  such that  $T = \mu t. U$  and  $X : t \vdash P : U$ .*
- 669 ■ *If  $\vdash 1 : T$  then  $T = \text{ok}$ .*

670 ▶ **Lemma 16.** *If  $\vdash \text{rec}X.P : \mu t. T$  then  $\vdash P\{X.P/X\} : T\{\mu t. T/t\}$ .*

671 We also require that race freedom is preserved by the reduction system. This is effectively  
672 a subject reduction theorem for the race free property.

673 ▶ **Lemma 17** (race freedom). *If  $P$  is race free and  $P \rightarrow Q$ , then  $Q$  is race free.*

674 The following condition follows from inverting the type system for race freedom.

675 ▶ **Lemma 18.** *If  $P \parallel Q$  is race free and  $\vdash P : T$  and  $\vdash Q : U$ , then if  $\pi$  appears in  $T$ , then  $\pi$   
676 does not appear in  $U$ .*

677 Since we employ a reduction semantics, we require that the rules of the structural  
678 congruence preserve multiparty compatibility.

679 ▶ **Lemma 19.** *If  $\vdash P : \text{ok}$  and  $P \equiv Q$ , then  $\vdash Q : \text{ok}$ .*

680 We also require a subject reduction result, where proofs that  $T \leq \text{ok}$  and race freedom  
681 play the role that a global type normally plays in such proofs. Note we avoid the term session  
682 fidelity since fidelity is typically expressed in terms of global types [32].

683 ▶ **Lemma 20** (subject reduction). *If  $\vdash P : \text{ok}$ , and  $P$  is race free, then for all  $Q$  such that  
684  $P \rightarrow Q$ , we have  $\vdash Q : \text{ok}$ .*

685 **Proof.** If there exists a reduction, we can apply the structural congruence to a process  
686 to reach one of the following forms. By Lemma 19, the use of the structural congruence  
687 preserves multiparty compatibility.

688 **Case of internal choice.** Assume we have  $\vdash \bigoplus_{i \in I} !\lambda_i; P_i \parallel Q : \text{ok}$ . By Theorem 9, for  
689 some  $T$ , we have  $\vdash \bigoplus_{i \in I} !\lambda_i; P_i \parallel Q : T$ , without using subsumption, and  $T \leq \text{ok}$ . Consider the  
690 transition  $\bigoplus_{i \in I} !\lambda_i; P_i \parallel Q \rightarrow !\lambda_k; P_k \parallel Q$ , where  $k \in I$ .

691 By Lemma 15, we have there exists  $U_i$  and  $V$  such that  $T = \bigvee_{i \in I} !\lambda_i; U_i \otimes V$  and  $\vdash P_i : U_i$ ,  
692 for all  $i$ , and  $\vdash Q : V$ . Therefore  $\vdash !\lambda_k; P_k \parallel Q : !\lambda_i; U_i \otimes V$ .

693 Now, since  $\bigvee_{i \in I} !\lambda_i; U_i$ ,  $V \vdash$  is provable and so is  $\bigwedge_{i \in I} ?\lambda_i; \overline{U_i}$ ,  $! \lambda_k; U_k \vdash$ , by Theorem 5,  
694  $! \lambda_k; U_k$ ,  $V \vdash$  holds. Hence  $! \lambda_k; U_k \otimes V \leq \text{ok}$ , as required.

695 **Case of external choice.** Assume we have  $\vdash \Sigma_{i \in I} ?\lambda_i; P_i \parallel !\lambda_k; Q \parallel R : \text{ok}$ , where  $k \in I$  and  
696  $\Sigma_{i \in I} ?\lambda_i; P_i \parallel !\lambda_k; Q \parallel R$  is race free. Consider transition  $\Sigma_{i \in I} ?\lambda_i; P_i \parallel !\lambda_k; Q \parallel R \rightarrow P_k \parallel Q \parallel R$ .

697 By Theorem 9, for some  $T$ , we have that  $\vdash \Sigma_{i \in I} ?\lambda_i; P_i \parallel !\lambda_k; Q \parallel R : T$  holds without using  
698 subsumption, and  $T \leq \text{ok}$ . By Lemma 15 we have there exists  $U_i$ ,  $V$  and  $W$  such that we have  
699  $T = \bigwedge_{i \in I} ?\lambda_i; U_i \otimes !\lambda_k; V \otimes W$  and  $\vdash P_i : U_i$ , for all  $i$ , and  $\vdash Q : V$  and  $\vdash R : W$ . Therefore we  
700 have  $\vdash P_k \parallel Q \parallel R : U_k \otimes V \otimes W$  holds.

701 Now, consider the proof of  $\bigwedge_{i \in I} ?\lambda_i; U_i$ ,  $! \lambda_k; V$ ,  $W \vdash$ . Since we have the type judgements  
702  $\vdash \Sigma_{i \in I} ?\lambda_i; P_i \parallel !\lambda_k; Q : \bigwedge_{i \in I} ?\lambda_i; U_i \otimes !\lambda_k; V$  and  $\vdash R : W$  and  $\Sigma_{i \in I} ?\lambda_i; P_i \parallel !\lambda_k; Q \parallel R$  is race  
703 free, by Lemma 18, neither  $! \lambda_i$  nor  $? \lambda_k$  appear in  $W$ . Hence there are only two possibilities,  
704 for **every branch of the proof tree**:

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- 705 1. Either we eventually reach an application of rule [PREFIX], possibly via an application of  
 706 [MEET] as follows:

$$\begin{array}{c}
 \vdots \\
 \frac{[\Theta] \vdash U_k, V, \Gamma \vdash}{[\Theta] ?\lambda_k; U_k, !\lambda_k; V, \Gamma \vdash} \text{[PREFIX]} \\
 \vdots \\
 \frac{[\Theta'] ?\lambda_k; U_k, !\lambda_k; V, \Gamma' \vdash}{[\Theta'] \bigwedge_{i \in I} ?\lambda_i; U_i, !\lambda_k; V, \Gamma' \vdash} \text{[MEET]} \\
 \vdots
 \end{array}$$

708 Note, by race freedom, if  $\lambda_j = \lambda_k$  then  $j = k$ , hence only one branch can be selected in  
 709 rule [MEET] to enable the rule [PREFIX]. Hence the above application of rule [INTR] is  
 710 deterministic.

- 711 2. Alternatively, on some path no [PREFIX] is ever applied to type  $!\lambda_k; V$  and there is a  
 712 [LEAF] axiom of the following form, with an corresponding ancestor [FIX- $\mu$ ] rule as  
 713 follows:

$$\begin{array}{c}
 \frac{[\Theta' \parallel !\lambda_k; V, \mu t. W', \Gamma] !\lambda_k; V, \mu t. W', \Gamma \vdash}{\vdots} \text{[LEAF]} \\
 \frac{[\Theta \parallel !\lambda_k; V, \mu t. W', \Gamma] !\lambda_k; V, W' \left\{ \frac{\mu t. W'}{t} \right\}, \Gamma \vdash}{[\Theta] !\lambda_k; V, \mu t. W', \Gamma \vdash} \text{[FIX-}\mu\text{]}
 \end{array}$$

715 In this case, by the participant condition in the race free condition, each  $\lambda_j$  such that  
 716  $j \in I$  can only match an output in the type  $!\lambda_k; V$ . Hence there must also be no [PREFIX]  
 717 applied to any  $\lambda_i$  in  $\bigwedge_{i \in I} ?\lambda_i; U_i$  between the [LEAF] and the corresponding [FIX- $\mu$ ]. Hence  
 718 either  $\bigwedge_{i \in I} ?\lambda_i; U_i$  appears in  $\Gamma$ , or there is some  $j \in I$  such that  $? \lambda_j; U_j$  for  $j \in I$  appears  
 719 in  $\Gamma$ .

720 In paths in the proof satisfying the first case above, simply remove the relevant instance  
 721 of the rule [INTR] below the rule in the proof, replace  $\bigwedge_{i \in I} ?\lambda_i; U_i$  and  $!\lambda_k; V$  with  $U_k$  and  $V$ .

722 In paths in the proof satisfying the second case above where both  $\bigwedge_{i \in I} ?\lambda_i; U_i$  and  $!\lambda_k; V$   
 723 are never touched, simply replacing these formulae with  $U_k$  and  $V$  everywhere in the given  
 724 path. In cases where  $? \lambda_j; U_j$  appears in  $\Gamma$ , there must be an instance of rule [JOIN] below the  
 725 rule [FIX- $\mu$ ] that introduced  $\Gamma$  or the following form.

$$\begin{array}{c}
 [\Theta''] !\lambda_k; V, ?\lambda_j; U_j, \Gamma'' \vdash \\
 \frac{[\Theta''] !\lambda_k; V, \bigwedge_{i \in I} ?\lambda_i; U_i, \Gamma'' \vdash}{}
 \end{array}$$

727 Since, by the participant condition, we know that in this path we never apply [PREFIX] to  
 728  $\lambda_j$ , we can safely remove the above rule instances from the proof and replace  $? \lambda_j; U_j$  with  $U_k$   
 729 along that path.

730 After applying the above proof transformation, we obtain a proof of  $U_k, V, W \vdash$ . Hence  
 731  $U_k \otimes V \otimes W \leq \text{ok}$  as required.

732 **Case of fixed points.** Assume  $\vdash \text{rec}X.P \parallel Q : \text{ok}$  holds. By Theorem 9, for some  $T$ , we  
 733 have  $\vdash \text{rec}X.P \parallel Q : T$ , without using subsumption, and  $T \leq \text{ok}$ . Consider the transition  
 734  $\text{rec}X.P \parallel Q \longrightarrow P \{ \text{rec}X.P / X \} \parallel Q$ .

735 By Lemma 15, we have there exist types  $U$  and  $V$  and type variable  $t$  such that  $T =$   
 736  $\mu t.U \otimes V$  and  $\vdash \text{rec } X.P : \mu t.U$  and  $\vdash Q : V$ . Now, by Lemma 16,  $\vdash P\{\text{rec } X.P/X\} : U\{\mu t.U/t\}$ .  
 737 Therefore, we have  $\vdash P\{\text{rec } X.P/X\} \parallel Q : U\{\mu t.U/t\} \otimes V$ .

738 Now, since  $\vdash \mu t.U, V$  is provable and  $\mu t.U, U\{\mu t.U/t\} \vdash$  is provable, by Theorem 5, we  
 739 have  $U\{\mu t.U/t\}, V \vdash$  is provable. Hence  $U\{\mu t.U/t\} \otimes V \leq \text{ok}$ , as required.  $\blacktriangleleft$

740  $\blacktriangleright$  **Theorem 21** (Theorem 12). *Any race-free multiparty-compatible network is deadlock free.*

741 **Proof.** Assume  $\vdash P : \text{ok}$  holds and  $P$  is race free. Consider the form of  $P$ . Either  $P$  has a  
 742 fixed point or internal choice at the head of a process, hence is ready to act. Hence, there  
 743 exists  $Q$  such that  $P \rightarrow Q$ . Otherwise we have a process equivalent to the following form.

$$744 \quad !\lambda_1;Q_1 \parallel \dots \parallel !\lambda_m;Q_m \parallel \Sigma_{i \in I_1} ?\lambda_i^1;R_i^1 \parallel \dots \parallel \Sigma_{i \in I_n} ?\lambda_i^n;R_i^n \parallel 1 \parallel \dots \parallel 1$$

745 There are two cases to consider as follows.

746 In the first case,  $m = n = 0$ ; hence we have  $P = 1 \parallel \dots \parallel 1$ . Therefore,  $P \equiv 1$  and hence  
 747 the processes is successfully terminated.

748 Otherwise, observe, by Theorem 9, there exists  $T$  such that  $\vdash P : T$  without using  
 749 subsumption and  $T \leq \text{ok}$ . Also, observe, by Theorem 15, there exists  $U_i$  and  $V_i^i$  such that  
 750  $T = !\lambda_1;U_1 \otimes \dots \otimes !\lambda_m;U_m \otimes \bigwedge_{i \in I_1} ?\lambda_i^1;V_i^1 \parallel \dots \otimes \bigwedge_{i \in I_n} ?\lambda_i^n;V_i^n \otimes \text{ok} \otimes \dots \otimes \text{ok}$  and  $\vdash Q_k : U_k$   
 751 and  $\vdash R_j^\ell : V_j^\ell$ , for all  $j, k$  and  $\ell$ .

752 In the proof of  $T \vdash$ , there must be at least one application of the rule [PREFIX]. Due to the  
 753 absence of  $\exists$  in  $T$ , the only other rules that may be applied before the bottommost instances  
 754 of rule [PREFIX] are the rules [PAR] and [MEET]. In order to apply the rule [PREFIX], there  
 755 exists  $j, k$  and  $\ell$  such  $j \in I_\ell$  and  $\lambda_k = \lambda_j^\ell$ , allowing a proof tree of the following form.

$$\frac{\begin{array}{c} [\Theta] T_k, U_i^\ell, \Gamma \vdash \\ \hline [\Theta] !\lambda_k; T_k, ?\lambda_j^\ell; U_j^\ell, \Gamma \vdash \end{array}}{\vdots} \\ \frac{\begin{array}{c} [\Theta] !\lambda_k; T_k, ?\lambda_j^\ell; U_j^\ell, \Gamma \vdash \\ \hline [\Theta] !\lambda_k; T_k, \bigwedge_{i \in I_\ell} ?\lambda_i^\ell; U_i^\ell, \Gamma \vdash \end{array}}{\vdots} \\ \frac{}{T \vdash}$$

757 Thus, simply due to the existence of such a matching pair of inputs and outputs, we have a  
 758 transition of the form.

$$759 \quad \begin{array}{c} !\lambda_1;Q_1 \parallel \dots \parallel !\lambda_k;Q_k \parallel \dots \parallel !\lambda_m;Q_m \\ \parallel \Sigma_{i \in I_1} ?\lambda_i^1;R_i^1 \parallel \dots \parallel \Sigma_{i \in I_\ell} ?\lambda_i^\ell;R_i^\ell \parallel \dots \parallel \Sigma_{i \in I_n} ?\lambda_i^n;R_i^n \parallel 1 \parallel \dots \parallel 1 \end{array} \rightarrow \begin{array}{c} !\lambda_1;Q_1 \parallel \dots \parallel Q_k \parallel \dots \parallel !\lambda_m;Q_m \\ \parallel \Sigma_{i \in I_1} ?\lambda_i^1;R_i^1 \parallel \dots \parallel R_j^\ell \parallel \dots \parallel \Sigma_{i \in I_n} ?\lambda_i^n;R_i^n \parallel 1 \parallel \dots \parallel 1 \end{array}$$

760 Thus we certainly have that either  $P \equiv 1$  or there exists  $Q$  such that  $P \rightarrow Q$ .

761 Finally, by Lemma 20, since  $R$  is race free, we have that for all  $R$  such that  $P \rightarrow R$ ,  
 762  $\vdash R : \text{ok}$  and furthermore, by Lemma 17,  $R$  is race free, as required. Hence, deadlock freedom  
 763 is established by coinduction.  $\blacktriangleleft$

764 **B The Precise Relationship to Linear Logic**

765 For a self-contained presentation, we summarise the related non-commutative logic [15] on  
 766 which this work builds, formulated in the calculus of structures [28]. We adjust the syntax  
 767 to match the body of the paper. The rules of MAV [34] are presented as in Fig. 7, where the  
 768 calculus of structures allows rules to be applied in any context  $\mathcal{C}\{\cdot\}$  and the structural  
 congruence  $\equiv$  can be applied at any point in a proof.

$$\begin{array}{c}
 \frac{\mathcal{C}\{\text{ ok}\} \vdash}{\text{ok} \vdash} \text{ success} \quad \frac{\mathcal{C}\{\text{ ok}\} \vdash}{\mathcal{C}\{\text{ !} \lambda \otimes ? \lambda\} \vdash} \text{ atomic interaction} \\
 \\ 
 \frac{\mathcal{C}\{\text{ (T} \otimes V) ; (U \otimes W)\} \vdash}{\mathcal{C}\{\text{ (T ; U)} \otimes (V ; W)\} \vdash} \text{ seq} \quad \frac{\mathcal{C}\{\text{ T} \wp (U \otimes V)\} \vdash}{\mathcal{C}\{\text{ (T} \wp U) \otimes V\} \vdash} \text{ switch} \\
 \\ 
 \frac{\mathcal{C}\{\text{ (T} \vee V) ; (U \vee W)\} \vdash}{\mathcal{C}\{\text{ (T ; U)} \vee (V ; W)\} \vdash} \text{ medial} \quad \frac{\mathcal{C}\{\text{ (T} \otimes U) \vee (T \otimes V)\} \vdash}{\mathcal{C}\{\text{ T} \otimes (U \vee V)\} \vdash} \text{ external} \\
 \\ 
 \frac{\mathcal{C}\{\text{ T}\} \vdash}{\mathcal{C}\{\text{ T} \wedge U\} \vdash} \text{ left} \quad \frac{\mathcal{C}\{\text{ U}\} \vdash}{\mathcal{C}\{\text{ T} \wedge U\} \vdash} \text{ right} \quad \frac{\mathcal{C}\{\text{ ok}\} \vdash}{\mathcal{C}\{\text{ ok} \vee \text{ ok}\} \vdash} \text{ tidy} \\
 \\ 
 (T \wp U) \wp V \equiv T \wp (U \wp V) \quad \text{ok} ; T \equiv T \quad (T \otimes U) \otimes V \equiv T \otimes (U \otimes V) \\
 T \wp \text{ok} \equiv T \quad T ; \text{ok} \equiv T \quad T \otimes \text{ok} \equiv T \\
 T \wp U \equiv U \wp T \quad (T ; U) ; V \equiv T ; (U ; V) \quad T \otimes U \equiv U \otimes T
 \end{array}$$

770 **Figure 7** Inference and structural rules for proof system MAV (formalising provability of duals).

771 We extend the notion of a co-type to local types with sequential composition.

$$\begin{array}{cccc}
 \overline{(T \wedge U)} = \overline{T} \vee \overline{U} & \overline{(T \vee U)} = \overline{T} \wedge \overline{U} & \overline{T} \wp \overline{U} = \overline{T} \otimes \overline{U} & \overline{T} \otimes \overline{U} = \overline{T} \wp \overline{U} \\
 \\ 
 \overline{(T ; U)} = \overline{T} ; \overline{U} & \overline{\text{ok}} = \text{ok} & \overline{! \lambda} = ? \lambda & \overline{? \lambda} = ! \lambda
 \end{array}$$

772 Notice the only difference compared to the co-type transformation for Session (Def. 2) is  
 773 that any type may appear to the left of sequential composition, not only an atomic send or  
 774 receive action. The following result generalises *cut elimination* to the calculus of structures.

775 **Theorem 22** (Horne 2015 [34]). *In the system in Fig. 7, if  $\mathcal{C}\{\overline{T} \wp T\} \vdash$  holds then we  
 776 can construct a proof of  $\mathcal{C}\{\text{ ok}\} \vdash$ .*

777 The related work [15, 34], from which the above is extracted, clarifies that, as for Session in  
 778 the body of this paper, MAV defines a rich notion of multiparty subtyping and compatibility.

779 The following result formally relating MAV and Session is a corollary of cut elimination  
 780 (each direction of the implication follows from cut elimination in one of the two systems).

781 **Corollary 23.** *If  $T$  is a session type, as in Def. 1 but without fixed points, then  $T \vdash$  in  
 782 Session if and only if  $T \vdash$  in System MAV.*

783 Finally, observe that MAV is a conservative extension of linear logic with mix and, the above  
 784 corollary proves the finite fragment of Session is also a fragment of MAV.