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Asset Pricing Models with Underlying Time-varying Lévy Processes Bachelier World Congress 2016, New York

Xuecan CUI Jang SCHILTZ University of Luxembourg

July 15th, 2016

^{*}Research funded by Fonds National de la Recherche Luxembourg (FNR)



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Time-varying Jump Diffusion Framework

Time-varying volatility: Empirical studies on the statistical properties of realized and/or implied volatilities have given rise to various stochastic volatility models in the literature, such as the Heston model, CEV models and also stochastic volatility models with jumps etc.

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Time-varying Jump Diffusion Framework

- Time-varying volatility: Empirical studies on the statistical properties of realized and/or implied volatilities have given rise to various stochastic volatility models in the literature, such as the Heston model, CEV models and also stochastic volatility models with jumps etc.
- Existence of jumps is empirically supported: Carr and Wu (2003), Pan (2002).

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- Existence of jumps is empirically supported: Carr and Wu (2003), Pan (2002).
- Jump intensity is time-varying: Christoffersen et al (2012).

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 Previous studies rely on a specific model structure for volatility and jumps (e.g. Santa-Clara and Yan 2010).

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- Previous studies rely on a specific model structure for volatility and jumps (e.g. Santa-Clara and Yan 2010).
- We introduce a general non-parametric time-varying jump diffusion framework as a natural generalisation of the results from literature (Bollerslev, Todorov and Xu, 2015 JFE).

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- Theoretical part: We assume a time-varying Lévy process, with time-varying drift, volatility and jump intensity parameters, to model the jump diffusion economy. We study an equilibrium asset and option pricing model in this economy.

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- Theoretical part: We assume a time-varying Lévy process, with time-varying drift, volatility and jump intensity parameters, to model the jump diffusion economy. We study an equilibrium asset and option pricing model in this economy.
- Empirical part: Under this general framework, we decompose S&P500 index into time-varying processes of drift, volatility and jump, using the Hodrick-Prescott filter and a particle filter.

Model Build-up

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Stock Market

• An investment of S_t in the *stock market* is governed by:

$$\frac{dS_t}{S_{t-}} = \mu(t)dt + \sigma(t)dB_t + (e^x - 1)dN_t - \lambda(t)E(e^x - 1)dt, (1)$$

where S_{t^-} is the value of S_t before a possible jump occurs; $\mu(t)$ and $\sigma(t)$ are the *rate of return* and the *volatility* of the investment.

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where S_{t^-} is the value of S_t before a possible jump occurs; $\mu(t)$ and $\sigma(t)$ are the *rate of return* and the *volatility* of the investment.

The jump part is assumed to be a Poisson process, with jump intensity $\lambda(t)$ and jump size x which follows an arbitrary distribution.

Money Market Account

• We further assume that there is a market for instantaneous borrowing and lending at a *risk-free rate* r(t). The *money market account*, M_t , follows

$$\frac{dM_t}{M_t} = r(t)dt. (2)$$

The risk-free rate, r(t), will be derived from the general equilibrium later, as a part of the solution.

Representative Investor

■ Maximize the expected utility function of life time consumption

$$\max_{c_t} E_t \int_t^T p(t) U(c_t) dt,$$

where c_t is the rate of consumption at time t, U(c) the utility function with U'>0, U''<0, and $p(t)\geq 0$, $0\leq t\leq T$ the time preference function.

Assume constant relative risk aversion (CRRA) utility function.

Representative Investor

Maximize the expected utility function of life time consumption

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Assume constant relative risk aversion (CRRA) utility function.

$$U(c) = \begin{cases} \frac{c^{1-\gamma}}{1-\gamma} & \gamma > 0, \gamma \neq 1, \\ \ln c, & \gamma = 1, \end{cases}$$

where the constant γ is the *relative risk aversion coefficient*, $\gamma = -cU''/U'$.

Summary

Total Wealth

■ The total wealth of the representative investor at time *t*:

$$W_t = W_{1t} + W_{2t}$$

where $W_{1t} = \omega W_t$ is invested in the stock market, and $W_{2t} = (1 - \omega)W_t$ is invested in the money market.

Summary

Total Wealth

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 ω is called the wealth ratio.

Summary

Representative Investor's Optimal Control Problem:

$$\max_{c_t,\omega} E_t \int_t^T p(t)U(c_t)dt, \tag{3}$$

subject to

$$\begin{split} \frac{dW_t}{W_t} &= \omega \frac{dS_t}{S_{t^-}} + (1 - \omega) \frac{dM_t}{M_t} - \frac{c_t}{W_t} dt \\ &= [r(t) + \omega \mu(t) - \omega r(t) - \omega \lambda(t) E(e^x - 1) - \frac{c_t}{W_t}] dt + \omega \sigma(t) dB_t \\ &+ \omega (e^x - 1) dN_t, \end{split}$$

where $\phi(t) = \mu(t) - r(t)$ is the equity premium.

Representative Investor's Optimal Control Problem:

$$\max_{c_t,\omega} E_t \int_t^T p(t) U(c_t) dt, \tag{3}$$

subject to

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where $\phi(t) = \mu(t) - r(t)$ is the equity premium.

■ Market Clearing: Because there is only one investor in the economy, he has to put all the wealth into the stock market. The general equilibrium occurs at $\omega=1$, under which the market is cleared.

Equity Premium

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Equity Premium

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 In the production economy with jump diffusion and one representative investor with CRRA utility function, the equilibrium equity premium is given by

$$\phi(t)=\phi_{\sigma}(t)+\phi_{J}(t),$$
 where $\phi_{\sigma}(t)=\gamma\sigma(t)^{2}$ -diffusion risk premium $\phi_{J}(t)=\lambda(t)E[(1-e^{-\gamma x})(e^{x}-1)]$ -jump risk premium

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 In the production economy with jump diffusion and one representative investor with CRRA utility function, the equilibrium equity premium is given by

$$\phi(t)=\phi_{\sigma}(t)+\phi_{J}(t),$$
 where $\phi_{\sigma}(t)=\gamma\sigma(t)^{2}$ -diffusion risk premium
$$\phi_{J}(t)=\lambda(t)E[(1-e^{-\gamma x})(e^{x}-1)]$$
 -jump risk premium

■ The risk-free rate is a time-varying function:

$$r(t) = \mu(t) - \phi(t) = \mu(t) - \phi_{\sigma}(t) - \phi_{J}(t).$$

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■ The pricing kernel is given by

$$\frac{d\pi_t}{\pi_t} = -r(t)dt - \gamma\sigma(t)dB_t + (e^y - 1)dN_t - \lambda(t)E(e^y - 1)dt,$$

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$$\frac{d\pi_t}{\pi_t} = -r(t)dt - \gamma\sigma(t)dB_t + (e^y - 1)dN_t - \lambda(t)E(e^y - 1)dt,$$

or equivalently, after integration

$$\frac{\pi_T}{\pi_t} = \exp\{-\int_t^T \gamma \sigma(s) dB_s - \int_t^T [r(s) + \frac{1}{2} \gamma^2 \sigma^2(s)] ds - E(e^y - 1) \int_t^T \lambda(s) ds + \sum_{i=1}^{N_t, T} y_i\}.$$

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■ The random variable y modeling the jump size in the logarithm of the pricing kernel, satisfies $E[(e^y - e^{-\gamma x})(e^x - 1)] = 0$.

European Call

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The price of a European call, $c(S_t, t)$, in the jump diffusion economy satisfies

$$\begin{split} \frac{\partial c(S_t,t)}{\partial t} + \frac{1}{2}\sigma^2(t)S_t^2 \frac{\partial^2 c(S_t,t)}{\partial S^2} + [r(t) - \lambda^Q(t)E^Q(e^x - 1)]S_t \frac{\partial c(S_t,t)}{\partial S} \\ - r(t)c(S_t,t) + \lambda^Q(t)\{E^Q[c(S_te^x,t)] - c(S_t,t)\} = 0, \end{split}$$

with final condition

$$c(S_T,T)=\max(S_T-K,0),$$

where $\lambda^{Q}(t) \equiv \lambda(t)E(e^{y})$: jump intensity in the risk-neutral measure Q, defined by $E^{Q}[f(x)] := \frac{E[e^{y}f(x)]}{E(e^{y})}$, for any function f(x).

Proposition

Pricing formula of a European call option:

$$c(S_t, t) = \sum_{n=0}^{+\infty} e^{-\int_t^T \lambda^Q(s)ds} \frac{\left(\int_t^T \lambda^Q(s)ds\right)^n}{n!} E_n^Q[c^{BS}(Se^X e^{-E^Q(e^X-1)\int_t^T \lambda^Q(s)ds}, t)],$$

where $c^{BS}(S,t)$ is the Black-Scholes formula price for the European call option and

$$X = \sum_{i=1}^{n} x_i.$$

Empirical Part

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Decompose the S&P500 Index into time-varying components, using

- the Hodrick-Prescott Filter
- a particle filter (Sequential Monte Carlo Method)

Hodrick-Prescott Filter

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Summary

■ The Hodrick-Prescott filters was first proposed in Whittaker (1923), then popularized in economics by Hodrick and Prescott (1997).



¹Ravn and Uhlig (2002)

Hodrick-Prescott Filter

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Summary

 The Hodrick-Prescott filters was first proposed in Whittaker (1923), then popularized in economics by Hodrick and Prescott (1997).

The method serves to decompose the time series $y_t = ln(S_t)$ into a trend component τ_t , and a cyclical component c_t :

$$y_t = \tau_t + c_t$$
, for $t = 1, ..., T$.



Hodrick-Prescott Filter

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Summary

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The method serves to decompose the time series $y_t = ln(S_t)$ into a trend component τ_t , and a cyclical component c_t :

$$y_t = \tau_t + c_t$$
, for $t = 1, ..., T$.

■ Condition: For a given a, τ_t satisfies

$$\min_{\tau} (\sum_{t=1}^{T} (y_t - \tau_t)^2 + a \sum_{t=2}^{T-1} [(\tau_{t+1} - \tau_t) - (\tau_t - \tau_{t-1})]^2),$$

where a = 129600 for monthly data¹.



¹Ravn and Uhlig (2002)

Extract Drift

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Summary

Data:

- S&P500 index, daily, 1985 2014.
- In each month, we use the 5% to 95% quantile of $In(S_t)$, compute the mean as a monthly data input for HP filter.

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Data:

- S&P500 index, daily, 1985 2014.
- In each month, we use the 5% to 95% quantile of $In(S_t)$, compute the mean as a monthly data input for HP filter.

As a result, we decompose the stock index into a time-varying trend component \mathcal{T} and a component \mathcal{C} :

$$In(S_t) = T + C.$$

T is a monthly drift, C the remaining process of volatility plus jumps.

Time-varying Drift

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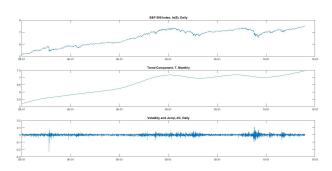


Figure 1.

	mean $(\times 10^{-5})$	volatility	skewness	kurtosis
$\Delta \ln(S)$	31.9	0.0115	-1.3044	31.8
ΔC	1.91	0.0117	-1.2229	30.1

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Summar

By taking the difference of the time-varying trend (ΔT) , we can observe that:

- Regime Switching: Before 2000, stock return was positive. However, after 2000 we can observe that it fluctuates around zero.
- Volatility/Jump Clustering: In negative return periods, there exists jumps and volatility clustering. By contrast, in positive return period, volatility/jump process is much less volatile.

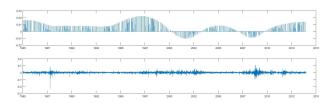


Figure 2.



Filtering Problems

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Summary

 For filtering problem, the data is generated by the state space model, which consists of the observation and state evolution equations,

- Observation equation: $y_t = f(x_t, \epsilon_t^y)$
- State evolution: $x_{t+1} = g(x_t, \epsilon_{t+1}^x)$,

where ϵ_{t+1}^{y} is the observation error or "noise", and ϵ_{t+1}^{x} are state shocks.

Filtering Problems

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• State evolution: $x_{t+1} = g(x_t, \epsilon_{t+1}^x)$,

where ϵ_{t+1}^{y} is the observation error or "noise", and ϵ_{t+1}^{x} are state shocks.

Particle filters belong to statistical filtering methods, which usually refer to an algorithm for extracting a latent state variable (e.g. volatility) from noisy observations (e.g. stock price/return) using a statistical model.

Particle Filters

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 Particle filters use a sampling approach with a set of particles to represent the posterior density of a latent state space (Johannes, Polson and Stroud 2009, RFS).

Particle Filters

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- Particle filters use a sampling approach with a set of particles to represent the posterior density of a latent state space (Johannes, Polson and Stroud 2009, RFS).
- They are simulation-based estimation methods, which include a set of algorithms that estimate the posterior density by directly implementing the Bayesian recursion equations.

Particle Filters

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- Particle filters use a sampling approach with a set of particles to represent the posterior density of a latent state space (Johannes, Polson and Stroud 2009, RFS).
- They are simulation-based estimation methods, which include a set of algorithms that estimate the posterior density by directly implementing the Bayesian recursion equations.
- The state space model used in particle filters can be non-linear and the initial state and noise distributions can take any form required.

SIR Algorithm

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Summary

■ The Sampling Importance Resampling (SIR) algorithm is a classical particle filtering algorithm developed by Gordon, Salmond, and Smith (1993).

SIR Algorithm

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- The Sampling Importance Resampling (SIR) algorithm is a classical particle filtering algorithm developed by Gordon, Salmond, and Smith (1993).
- SIR includes two steps: given samples from $p^N(x_t|y^t)$,
 - S1. Propagation: for i = 1, ..., N, draw $x_{t+1}^{(i)} \sim p(x_{t+1}|x_t^{(i)})$.
 - S2. Resampling: for i = 1, ..., N, draw $z^{(i)} \sim Mult_N(w_{t+1}^{(1)}, ..., w_{t+1}^{(N)})$, with importance sampling weights $w_{t+1}^{(i)} = \frac{p(y_{t+1}|x_{t+1}^{(i)})}{\sum_{l=1}^{N} p(y_{t+1}|x_{t+1}^{(l)})}$, and set $x_{t+1}^{(i)} = x_{t+1}^{z^{(i)}}$.



State Variable of Volatility

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As a state space model (for volatility) is necessary to implement particle filters, we assume that following dynamics for the stochastic variance:

$$d\nu_t = k(\theta - \nu_t)dt + \sigma_\nu \sqrt{\nu_t}dB_t^\nu,$$

where ν_t is a mean-reverting stochastic process. B_t^{ν} is a Brownian motion correlated with B_t , with correlation coefficient ρ .

Filter out Volatility

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 Based on the result from HP filter, we further apply SIR to decompose the time-varying volatility and jump (component C).

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- Based on the result from HP filter, we further apply SIR to decompose the time-varying volatility and jump (component C).
- We start with particle filters under stochastic volatility (SV) model without jumps, then we apply particle filters under stochastic volatility and jump (SVJ) model.

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- Based on the result from HP filter, we further apply SIR to decompose the time-varying volatility and jump (component C).
- We start with particle filters under stochastic volatility (SV) model without jumps, then we apply particle filters under stochastic volatility and jump (SVJ) model.
- The parameters used for the particle filters are taken from Eraker, Johannes and Polson (2003).

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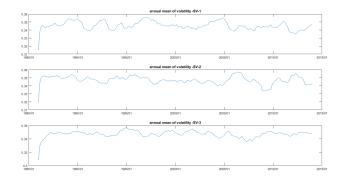
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- We run particle filters under SV model three times. Estimated volatilities stay around 0.34-0.35. However, the pattern of the volatility processes varies each time.
- Note that the hump shape on the left sides are caused by an adaptation period (around 200 initial data points) needed by the algorithm.



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Following Eraker, Johannes and Polson (2003), we assume a jump intensity of $\lambda=0.006$, meaning 1 to 2 jumps per year; the jump size follows a normal distribution.

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- Following Eraker, Johannes and Polson (2003), we assume a jump intensity of $\lambda=0.006$, meaning 1 to 2 jumps per year; the jump size follows a normal distribution.
- With the SVJ model, filtered volatilities decrease to 0.2-0.25, as jumps account for some of the excess variance.

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- Following Eraker, Johannes and Polson (2003), we assume a jump intensity of $\lambda=0.006$, meaning 1 to 2 jumps per year; the jump size follows a normal distribution.
- With the SVJ model, filtered volatilities decrease to 0.2-0.25, as jumps account for some of the excess variance.
- We detect a high possibility of jumps around 1987-1988, and some other infrequent jumps. Overall jumps are rare in this model. We observe high level of volatilities when the probability of a jump occurring is high.

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Asset Pricing Model with Time-varying Lévy

Decomposing S&P500 index

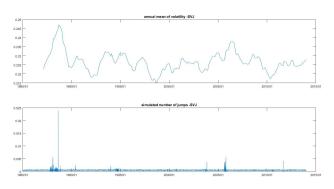


Figure 4. Filtered volatility and jump processes under SVJ model

Future Research

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Summarv

■ The decomposition of the time-varying component of drift, volatility and jumps from S&P500 index using HP filter and particle filter is still a preliminary result.

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- The decomposition of the time-varying component of drift, volatility and jumps from S&P500 index using HP filter and particle filter is still a preliminary result.
- Here we studied the SVJ model only with fixed jump intensity; another possibility is to consider the jump intensity as a time-varying function, for example a function of time-varying drift or volatility, or some other possible exogenous determinant.

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- Here we studied the SVJ model only with fixed jump intensity; another possibility is to consider the jump intensity as a time-varying function, for example a function of time-varying drift or volatility, or some other possible exogenous determinant.
- It will be interesting to use option data jointly with return data in the filtering methods.

Main References

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Summary

Thank you!