

Some questions . . .

Disaggregation of bipolar-valued outranking relations

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MCO'08What is a **bipolar-valued** outranking relation?What data is **underlying** a bipolar-valued outranking relation?Can we **help** the decision maker to determine the parameters of the model?

Structure of the presentation

- Introduction
- Models for the bipolar-valued outranking relation
- Disaggregation of bipolar-valued outranking relation
- On the rank of a bipolar-valued outranking relation
- Illustrative examples
- Usefulness in MCDA: inference of model parameters

Introductory considerations

Notation and facts ...

- X is a finite set of n **alternatives**
- N is a finite set of p **criteria**
- $g_i(x)$ is the **performance** of alternative x on criterion i
- $w_i \in [0, 1]$, rational, is the **weight** associated with criterion i of N ,
s.t. $\sum_{i \in N} w_i = 1$
- q_i, p_i, wv_i and v_i are **thresholds** associated with each criterion i to model local or overall *at least as good as* preferences

Notation and facts ...

- $xSy \equiv$ "x **outranks** y"
- **Classically**: xSy is assumed to be validated if there is a **sufficient majority** of criteria which support an "at least as good as" preferential statement and there is no criterion which raises a **veto** against it
- $\tilde{S}(x, y) \in [-1, 1]$ is the **credibility of the validation** of the statement xSy
- \tilde{S} is called the **bipolar-valued** outranking relation

Goals

Primary objective
Disaggregate the bipolar-valued outranking relation to determine how the underlying data looks like

In other words:
 Given $\tilde{S}(x, y) \forall x \neq y \in X$, determine the **performances** of alternatives $g_i(x) \forall x \in X, \forall i \in N$, the **weights** $w_i \forall i \in N$ and the **thresholds** $q_i, p_i, wv_i, v_i \forall i \in N$.

- 3 different models:**
- \mathcal{M}_1 : Model with a single preference threshold
 - \mathcal{M}_2 : Model with two preference thresholds
 - \mathcal{M}_3 : Model with two preference and two veto thresholds

Goals

Secondary objective
Infer model parameters based on **a priori** knowledge provided by the decision maker

In other words:
 Given the **performances** $g_i(x) \forall x \in X \forall i \in N$ and some **a priori** info from the decision maker, determine the values of the thresholds and the weights

Usefulness in Multiple Criteria Decision Analysis (MCDA):
 Help to elicit the decision maker's **preferences** via questions on his domain of expertise

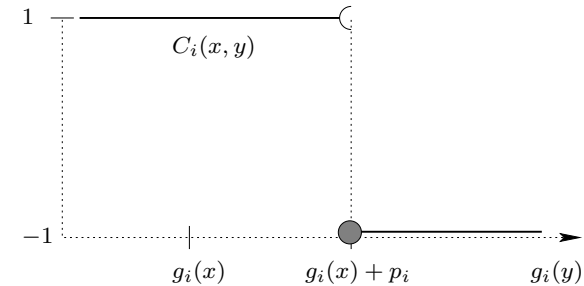
Different models for the outranking relation

\mathcal{M}_1 : Model with a single preference threshold

A local “at least as good as” situation between two alternatives x and y of X , for each criterion i of N is represented by the function $C_i : X \times X \rightarrow \{0, 1\}$ defined by:

$$C_i(x, y) = \begin{cases} 1 & \text{if } g_i(y) < g_i(x) + p_i; \\ -1 & \text{otherwise,} \end{cases}$$

where $p_i \in]0, 1[$ is a constant **preference threshold** associated with all the preference dimensions

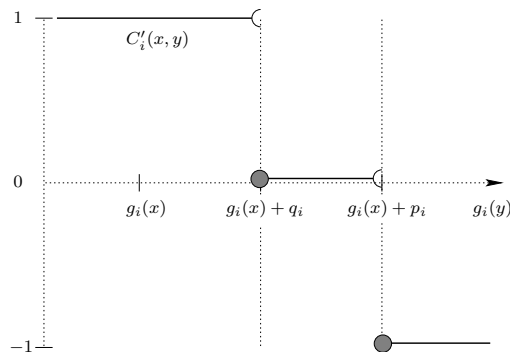


\mathcal{M}_2 : Model with two preference thresholds

A local “at least as good as” situation between two alternatives x and y of X , for each criterion i of N is represented by the function $C'_i : X \times X \rightarrow \{-1, 0, 1\}$ s.t.:

$$C'_i(x, y) = \begin{cases} 1 & \text{if } g_i(y) < g_i(x) + q_i; \\ -1 & \text{if } g_i(y) \geq g_i(x) + p_i; \\ 0 & \text{otherwise,} \end{cases}$$

where $q_i \in]0, p_i[$ is a constant **weak preference** threshold associated with all the preference dimensions.



\mathcal{M}_1 & \mathcal{M}_2

Bipolar-valued outranking relation

$$\tilde{S}'(x, y) = \sum_{i \in N} w_i C'_i(x, y) \quad \forall x \neq y \in X$$

Recall:

$\tilde{S}'(x, y) \in [-1, 1]$ represents the credibility of the validation of the outranking situation xSy

Meaning of \tilde{S}' :

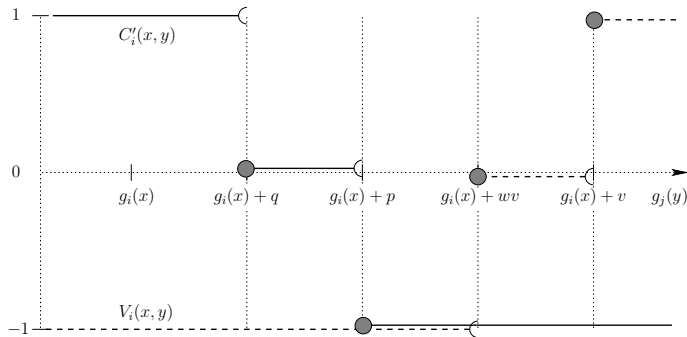
- $\tilde{S}'(x, y) = +1$ means that statement xSy is **clearly validated**.
- $\tilde{S}'(x, y) = -1$ means that statement xSy is **clearly not validated**.
- $\tilde{S}'(x, y) > 0$ means that statement xSy is **more validated than not validated**.
- $\tilde{S}'(x, y) < 0$ means that statement xSy is **more not validated than validated**.
- $\tilde{S}'(x, y) = 0$ means that statement xSy is **indeterminate**.

\mathcal{M}_3 : Model with two preference and two veto thresholds

A *local veto* situation for each criterion i of N is characterised by a veto function $V_i : X \times X \rightarrow \{-1, 0, 1\}$ s.t.:

$$V_i(x, y) = \begin{cases} 1 & \text{if } g_i(y) \geq g_i(x) + v_i; \\ -1 & \text{if } g_i(y) < g_i(x) + wv_i; \\ 0 & \text{otherwise,} \end{cases}$$

where $wv_i \in]p_i, 1[$ (resp. $v_i \in]wv_i, 1[$) is a constant **weak veto threshold** (resp. **veto threshold**) associated with all the preference dimensions



\mathcal{M}_3

Bipolar-valued outranking relation

$$\tilde{S}''(x, y) = \min \left\{ \sum_{i \in N} w_i C'_i(x, y), -V_1(x, y), \dots, -V_n(x, y) \right\}.$$

Note:

The min operator translates the **conjunction** between the overall concordance and the negated local veto indexes for each criterion

Disaggregation of the outranking relation

How?

Objective

Disaggregate the bipolar-valued outranking relation to determine how the underlying data looks like

How?

By **mathematical programming!**

\Rightarrow **Given** \tilde{S} , **determine** $g_i(x)$ ($\forall i \in N, \forall x \in X$), w_i ($\forall i \in N$) and $q_i, p_i, wv_i, v_i \forall i \in N$.

Disaggregation of \mathcal{M}_1 by mathematical programming

Minimise the number of **active** criteria

| | | |
|-------------------------------|---|---|
| MIP1: | | |
| <i>Variables:</i> | | |
| $g_i(x), w_i \in [0, 1]$ | $\forall i \in N, \forall x \in X$ | |
| $W_j, C_i(x, y) \in \{0, 1\}$ | $\forall i \in N, \forall x \neq y \in X$ | |
| $w'_i \in [-1, 1]$ | $\forall i \in N$ | |
| $p_i \in]\gamma, 1]$ | $\forall i \in N$ | |
| <i>Parameters:</i> | | |
| $\tilde{S}(x, y) \in [0, 1]$ | $\forall x \neq y \in X$ | |
| $\delta \in]0, 1[$ | | |
| $\gamma \in]\delta, 1[$ | | |
| <i>Objective function:</i> | | |
| min | $\sum_{i=1}^n W_j$ | |
| <i>Constraints:</i> | | |
| s.t. | $\sum_{i=1}^n w_i = 1$ | |
| | $w_i \leq W_j$ | $\forall i \in N$ |
| | $-w_i \leq w'_i(x, y)$ | $\forall x \neq y \in X, \forall i \in N$ |
| | $w'_i(x, y) \leq w_i$ | $\forall x \neq y \in X, \forall i \in N$ |
| | $w_j + C_i(x, y) - 1 \leq w'_i(x, y)$ | $\forall x \neq y \in X, \forall i \in N$ |
| | $w'_i(x, y) \leq -w_j + C_i(x, y) + 1$ | $\forall x \neq y \in X, \forall i \in N$ |
| | $\sum_{i=1}^n w'_i(x, y) = \tilde{S}(x, y)$ | $\forall x \neq y \in X$ (b) |
| | $-2(1 - C_i(x, y)) + \delta \leq g_i(x) - g_i(y) + p_i$ | $\forall x \neq y \in X, \forall i \in N$ |
| | $g_i(x) - g_i(y) + p_i \leq 2C_i(x, y)$ | $\forall x \neq y \in X, \forall i \in N$ |
| | $p_i \geq \gamma$ | $\forall i \in N$ |

Disaggregation of \mathcal{M}_1 by mathematical programming

Minimise the number of **active** criteria

OK, but what if there are some slight **errors** in the given \tilde{S} ?

Disaggregation of \mathcal{M}_1 by mathematical programming

Minimise the number of **active** criteria

If no solution exists:

- The selected maximal number n of criteria is too **small**
- The model with a constant preference threshold (\mathcal{M}_1) is **too poor** to represent the given \tilde{S}
- ...

Disaggregation of \mathcal{M}_1 by mathematical programming

Minimise the maximal **gap** between the given and the calculated \tilde{S}

| | | |
|-------------------------------|---|--------------------------|
| MIP1bis: | | |
| <i>Variables:</i> | | |
| $\epsilon \geq 0$ | | |
| $g_i(x), w_i \in [0, 1]$ | $\forall i \in N, \forall x \in X$ | |
| $W_j, C_i(x, y) \in \{0, 1\}$ | $\forall i \in N, \forall x \neq y \in X$ | |
| $w'_i \in [-1, 1]$ | $\forall i \in N$ | |
| $p_i \in]\gamma, 1]$ | $\forall i \in N$ | |
| <i>Parameters:</i> | | |
| $\tilde{S}(x, y) \in [0, 1]$ | $\forall x \neq y \in X$ | |
| $\delta \in]0, 1[$ | | |
| $\gamma \in]\delta, 1[$ | | |
| <i>Objective function:</i> | | |
| min | ϵ | |
| <i>Constraints:</i> | | |
| s.t. | $\sum_{i=1}^n w_i = 1$ | |
| | ... | |
| | $\sum_{i=1}^n w'_i(x, y) \leq \tilde{S}(x, y) + \epsilon$ | $\forall x \neq y \in X$ |
| | $\sum_{i=1}^n w'_i(x, y) \geq \tilde{S}(x, y) - \epsilon$ | $\forall x \neq y \in X$ |
| | ... | |

Disaggregation of \mathcal{M}_1 by mathematical programming

Minimise the maximal **gap** between the given and the calculated \tilde{S}

Motivations:

- By construction, $\tilde{S}(x, y)$ is **rational** in $[-1, 1]$
- If the decimal expansion of a rational number $r \in [-1, 1]$ is **periodic**, then r is hardly representable as a float
- Consequently, the value stored for $\tilde{S}(x, y)$ might be an **approximation**
- In such a case, **MIP1** might have **no solution**

Discussion:

- If $\varepsilon = 0$, then there exist $g_i(x)$ ($\forall i \in N, \forall x \in X$) and associated weights w_i ($\forall i \in N$) and thresholds $q_i, p_i, wv_i, v_i \forall i \in N$ generating \tilde{S} via \mathcal{M}_1
- Else there exists no solution to the problem via the selected representation, and the output of **MIP1bis** is an approximation of \tilde{S} by \mathcal{M}_1

Disaggregation of \mathcal{M}_2 and \mathcal{M}_3

Similar as \mathcal{M}_1 via mixed integer programs by minimising ε

| MIP2: | |
|--------------------------------|--|
| Variables: | |
| $\varepsilon \geq 0$ | |
| $g_i(x) \in [0, 1]$ | $\forall i \in N, \forall x \in X$ |
| $w_i \in]0, 1[$ | $\forall i \in N$ |
| $\alpha_i(x, y) \in \{0, 1\}$ | $\forall i \in N, \forall x \neq y \in X$ |
| $\beta_i(x, y) \in \{0, 1\}$ | $\forall i \in N, \forall x \neq y \in X$ |
| $\alpha'_i(x, y) \in \{0, 1\}$ | $\forall i \in N, \forall x \neq y \in X$ |
| $\beta'_i(x, y) \in \{0, 1\}$ | $\forall i \in N, \forall x \neq y \in X$ |
| $w''_i(x, y) \in [-1, 1]$ | $\forall i \in N, \forall x \neq y \in X$ |
| $z_i(x, y) \in \{0, 1\}$ | $\forall i \in N \cup \{0\}, \forall x \neq y \in X$ |
| $q_i \in]\gamma, p_i[$ | $\forall i \in N$ |
| $p_i \in]q_i, wv_i[$ | $\forall i \in N$ |
| $wv_i \in]p_i, v_i[$ | $\forall i \in N$ |
| $v_i \in]wv_i, 1[$ | $\forall i \in N$ |
| Parameters: | |
| $\tilde{S}''(x, y) \in [0, 1]$ | $\forall x \neq y \in X$ |
| $\delta \in]0, 1[$ | |
| $\gamma \in]\delta, 1[$ | |
| Objective function: | |
| min ε | |
| Constraints: | |
| : | |
| : | |

On the rank of the outranking relation

On the rank of a bipolar-valued outranking relation

Definition

The **rank** of a bipolar-valued outranking relation is given by the minimal number of criteria necessary to construct it via the selected model.

Practical determination:

- **MIP1**: the objective function gives the rank of \tilde{S} .
- **MIP1bis, MIP2, MIP3**:
 - $n := 0$;
 - do {
 - $n++$;
 - solve the optimisation problem;
 - } while $\varepsilon > 0$;
 - **rank** = n ;

Note: The algorithm might never stop, if \tilde{S} cannot be constructed by the chosen model

Illustrative examples

Illustration

MIP1 & MIP1bis ($\delta = 0.001, \gamma = 0.1, n = 5$):

| | | | | | | | | |
|---------------|-------|-------|--------|-------|-------|-------|-------|-------|
| \tilde{S}_1 | a | b | c | | g_1 | g_2 | g_3 | g_4 |
| a | . | 0.258 | -0.186 | | 1.000 | 0.000 | 0.100 | 0.000 |
| b | 0.334 | . | 0.556 | | 0.500 | 0.000 | 0.000 | 1.000 |
| c | 0.778 | 0.036 | . | | 0.000 | 0.000 | 0.200 | 0.100 |
| | | | | w_i | 0.111 | 0.296 | 0.222 | 0.371 |
| | | | | p_i | 0.500 | 1.000 | 0.100 | 0.100 |

MIP1: there exists an optimal solution for 4 criteria

MIP1bis:

- for $n \geq 4$: optimal solution with $\varepsilon = 0$
- for $n < 4$: optimal solutions with $\varepsilon > 0$

$\Rightarrow \text{rank}(\tilde{S}_1) = 4$ under \mathcal{M}_1

Illustration

MIP2 & MIP3 ($q = 0.1, p = 0.2, wv = 0.6$ and $v = 0.8, \delta = 0.001, n = 5$):

| | | | | | | |
|---------------|--------|-------|--------|-------|-------|-------|
| \tilde{S}_2 | a | b | c | | g_1 | g_2 |
| a | . | 0.258 | -0.186 | | 0.290 | 0.000 |
| b | 0.334 | . | 0.556 | | 0.100 | 0.100 |
| c | -1.000 | 0.036 | . | | 0.000 | 0.01 |
| | | | | w_i | 0.704 | 0.296 |
| | | | | q_i | 0.100 | 0.100 |
| | | | | p_i | 0.200 | 0.200 |

MIP2: for $n = 5$: opt. sol. with $\varepsilon = 0.593$

MIP3:

- for $n \geq 4$: optimal solution with $\varepsilon = 0$
- for $n < 4$: optimal solution with $\varepsilon > 0$

$\Rightarrow \text{rank}(\tilde{S}_2) = 4$ under \mathcal{M}_3

| | | | | |
|-------------|-------|-------|-------|-------|
| MIP3 | g_1 | g_2 | g_3 | g_4 |
| a | 0.600 | 0.690 | 0.000 | 0.420 |
| b | 1.000 | 0.000 | 0.200 | 0.210 |
| c | 0.800 | 0.890 | 0.100 | 0.000 |
| w_i | 0.186 | 0.222 | 0.370 | 0.222 |
| q_i | 0.100 | 0.100 | 0.100 | 0.100 |
| p_i | 0.200 | 0.200 | 0.210 | 0.220 |
| wv_i | 0.410 | 0.900 | 0.310 | 0.320 |
| v_i | 0.510 | 1.000 | 0.410 | 0.420 |

Note: Veto between c and a on criterion 4 ($\tilde{S}(c, a) = -1$)

On the inference of model parameters

Usefulness in MCDA: inference of model parameters

In real-world decision problems involving multiple criteria:

- Performances $g_i(x)$ ($\forall i \in N, \forall x \in X$) are **known**
- Weights and thresholds are usually **unknown**

Objective

Show how these parameters can be determined from **a priori** knowledge provided by the decision maker

A priori information

In our context, the **a priori** preferences of the decision maker could take the form of:

- a partial weak order over the credibilities of the validation of outrankings;
- a partial weak order over the importances of some criteria;
- quantitative intuitions about some credibilities of the validation of outrankings;
- quantitative intuitions about the importance of some criteria;
- quantitative intuitions about some thresholds;
- subsets of criteria important enough for the validation of an outranking situation;
- subsets of criteria not important enough for the validation of an outranking situation;
- etc.

A priori information: constraints

- the validation of wSx is strictly more credible than that of ySz can be translated as $\tilde{S}(w, x) - \tilde{S}(y, z) \geq \delta$;
- the validation of wSx is similar to that of ySz can be translated as $-\delta \leq \tilde{S}(w, x) - \tilde{S}(y, z) \leq \delta$;
- the importance of criterion i is strictly higher than that of j can be translated as $w_i - w_j \geq \delta$;
- the importance of criterion i is similar to that of j can be translated as $-\delta \leq w_i - w_j \leq \delta$;

where $w, x, y, z \in X, i, j \in N$ and δ is a non negative separation parameter.

A priori information: constraints

- a quantitative intuition about the credibility of the validation of xSy can be translated as $\eta_{(x,y)} \leq \tilde{S}(x, y) \leq \theta_{(x,y)}$, where $\eta_{(x,y)} \leq \theta_{(x,y)} \in [-1, 1]$ are to be fixed by the DM;
- a quantitative intuition about the importance of criterion i can be translated as $\eta_{w_i} \leq w_i \leq \theta_{w_i}$, where $\eta_{w_i} \leq \theta_{w_i} \in [0, 1]$ are to be fixed by the DM;
- a quantitative intuition about the preference threshold p_i of criterion i can be translated as $\eta_{p_i} \leq p_i \leq \theta_{p_i}$, where $\eta_{p_i} \leq \theta_{p_i} \in [0, 1]$ are to be fixed by the DM;
- the fact that the subset $M \subset N$ of criteria is sufficient (resp. not sufficient) to validate an outranking statement can be translated as $\sum_{i \in M} w_i \geq \eta_M$ (resp. $\sum_{i \in M} w_i \leq -\eta_M$), where $\eta_M \in [0, 1]$ is a parameter of *concordant coalition* which is to be fixed by the DM.

MIP3-MCDA:

Variables:

$$\begin{aligned} \varepsilon &\geq 0 \\ w_i &\in]0, 1[& \forall i \in N \\ q_i &\in]0, p_i[& \forall i \in N \\ p_i &\in]q_i, 1[& \forall i \in N \\ ww_i &\in]p_i, 1[& \forall i \in N \\ v_i &\in]ww_i, 1[& \forall i \in N \\ \tilde{S}''(x, y) &\in [0, 1] & \forall x \neq y \in X \\ \dots & \end{aligned}$$

Parameters:

$$\begin{aligned} g_i(x) &\in [0, 1] & \forall i \in N, \forall x \in X \\ \delta &\in]0, q[\end{aligned}$$

Objective function:

min ε

MIP3 (some of them linearised)

Constraints of a priori information (informal):

$$\begin{aligned} \tilde{S}(w, x) - \tilde{S}(y, z) &\geq \delta & \text{for some pairs of alternatives} \\ -\delta &\leq \tilde{S}(w, x) - \tilde{S}(y, z) \leq \delta & \text{for some pairs of alternatives} \\ w_i - w_j &\geq \delta & \text{for some pairs of weights} \\ -\delta &\leq w_i - w_j \leq \delta & \text{for some pairs of weights} \\ \eta_{(x,y)} &\leq \tilde{S}(x, y) \leq \theta_{(x,y)} & \text{for some pairs of alternatives} \\ \eta w_i &\leq w_i \leq \theta w_i & \text{for some weights} \\ \eta p_i &\leq p_i \leq \theta p_i & \text{for some thresholds and some weights} \\ \sum_{i \in M} w_i &\geq \eta M & \text{for some subsets } M \text{ of weights} \\ \sum_{i \in M} w_i &\leq -\eta M & \text{for some subsets } M \text{ of weights} \end{aligned}$$

Illustration

Starting point:

| | g_1 | g_2 | g_3 | g_4 |
|----------|-------|-------|-------|-------|
| <i>a</i> | 0.000 | 0.000 | 0.000 | 1.000 |
| <i>b</i> | 0.400 | 0.100 | 0.090 | 0.590 |
| <i>c</i> | 0.200 | 0.290 | 0.000 | 0.000 |

Unknown:

- $w_i \quad \forall i \in N$
- $q_i, p_i, ww_i, v_i \quad \forall i \in N$

A priori preferences:

| \tilde{S}_3 | <i>a</i> | <i>b</i> | <i>c</i> |
|---------------|----------------|-------------------|-----------------|
| <i>a</i> | . | $\in]0, 0.5]$ | $\in [-0.5, 0[$ |
| <i>b</i> | $\in]0, 0.5]$ | . | $\in]0.5, 1]$ |
| <i>c</i> | $= -1$ | $\in [-0.1, 0.1]$ | . |

Illustration

Output of MIP3-MCDA:

| \tilde{S}_3 | <i>a</i> | <i>b</i> | <i>c</i> |
|---------------|----------|----------|----------|
| <i>a</i> | . | 0.500 | -0.010 |
| <i>b</i> | 0.500 | . | 1.000 |
| <i>c</i> | -1.000 | 0.000 | . |

Table: \tilde{S}_3

| | g_1 | g_2 | g_3 | g_4 |
|--------|-------|-------|-------|-------|
| w_i | 0.120 | 0.380 | 0.250 | 0.250 |
| q_i | 0.970 | 0.270 | 0.000 | 0.000 |
| p_i | 0.980 | 0.280 | 0.090 | 0.410 |
| ww_i | 0.990 | 0.290 | 0.990 | 0.590 |
| v_i | 1.000 | 0.300 | 1.000 | 0.600 |

Table: Model parameters for \tilde{S}_3 via \mathcal{M}_3

A few words on the implementation

Note: $\tilde{S}_3(c, a) = -1$ (resp $\tilde{S}_3(c, b) = 0$) results from a veto (resp. weak veto) situation on criterion 4.

On the implementation

- Implemented in the **GNU MathProg** programming language
- Simple examples of this presentation have been solved on a standard desktop computer with **Glpsol**
- Harder examples are solved with **ILOG CPLEX 11.0.0**
- **Very** time consuming!

That's all folks