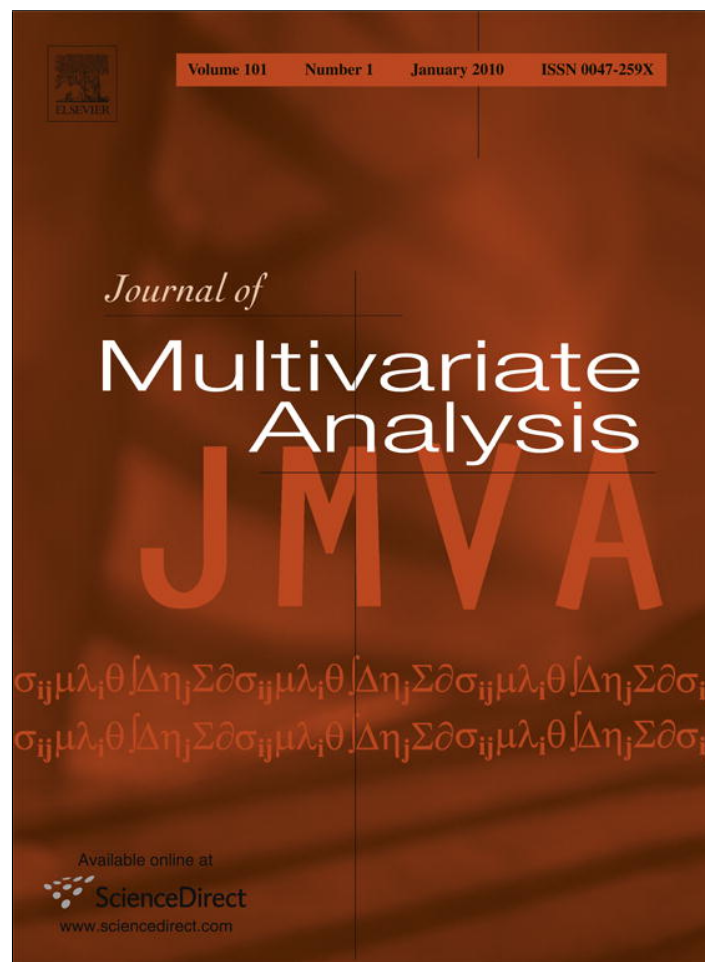


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journal homepage: [www.elsevier.com/locate/jmva](http://www.elsevier.com/locate/jmva)Representations of  $SO(3)$  and angular polyspectraD. Marinucci <sup>a,\*</sup>, G. Peccati <sup>b</sup><sup>a</sup> Dipartimento di Matematica, Università di Roma Tor Vergata, via della Ricerca Scientifica, 1, 00133 Roma, Italy<sup>b</sup> Centre de Recherche Mod'X, Université Paris Ouest Nanterre la Défense, 200, Avenue de la République, 92000 Nanterre, France

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## ABSTRACT

We characterize the angular polyspectra, of arbitrary order, associated with isotropic fields defined on the sphere  $S^2 = \{(x, y, z) : x^2 + y^2 + z^2 = 1\}$ . Our techniques rely heavily on group representation theory, and specifically on the properties of Wigner matrices and Clebsch–Gordan coefficients. The findings of the present paper constitute a basis upon which one can build formal procedures for the statistical analysis and the probabilistic modelization of the Cosmic Microwave Background radiation, which is currently a crucial topic of investigation in cosmology. We also outline an application to random data compression and “simulation” of Clebsch–Gordan coefficients.

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## 1. Introduction

The connection between probability theory and group representation theory has led to a long tradition of fruitful interactions. A well-known reference is provided by [1]; see e.g. [2, Section 40–41], [3–8], and the references therein, for other relevant contributions. In this paper we shall focus in particular on the connection between the probabilistic notion of *isotropy*, i.e. invariance in law under the action of a group, and the representation theory of the group itself. One instance of this connection is well-known, i.e. the celebrated Peter–Weyl Theorem, which allows the construction of spectral representations for isotropic random fields on homogeneous spaces of general compact groups, see [9] for a general construction and [10,11] for examples related, respectively, to the torus and the sphere. Our aim here is to use these representations in order to characterize random fields by means of a higher order spectral theory; in particular, one of our main goals will be to establish the link between the so-called *polyspectra* (or higher order spectra) and alternative (tensor product and direct sum) representations of the underlying isotropy group. In particular, we shall provide a general expression for higher order spectra of isotropic spherical random fields in terms of convolutions of Clebsch–Gordan or Wigner coefficients. The latter were introduced in Mathematics in the XIX century for the analysis of Algebraic Invariants; they have since then played a crucial role in the development of Quantum Physics in the XX century (see for instance [12] for a comprehensive reference); their role in Group Representation theory will be discussed below, while more details can be found for instance in [13].

Our analysis may have an intrinsic mathematical interest, but it is also strongly motivated by applications to Physics and Cosmology. Concerning the latter, the analysis of higher order spectra for isotropic spherical random fields is currently at the core of several research efforts which are related to the analysis of Cosmic Microwave Background (CMB) radiation

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data, see for instance [14,15] for a general introduction and [16–19] for some references on the bi- and trispectrum. A general characterization of the theoretical properties of higher order angular power spectra can yield several insights into the statistical analysis of the massive datasets that are or will be made available by satellite experiments such as *WMAP* or *Planck*. For instance, the current understanding of the behaviour of the bispectrum for some simple physical models has already led to many applications (see [20–22]), aiming at obtaining constraints on nonlinearity parameters of utmost physical significance; needless to say, a proper understanding of higher order spectra can lead to more efficient statistical procedures and better constraints, which may help to solve some of the important scientific issues at stake in CMB analysis (primarily a proper understanding of the Big Bang *inflationary* dynamics, which is tightly linked with the CMB nonlinear structure, see [15,23–25]).

The relevance of the current results need not be limited to cosmological applications. Indeed, the analysis of spherical random fields has currently led to remarkable developments in the Geophysical and Planetary Sciences, and even in Medical Imaging (see e.g. [26–28]). Moreover, we shall show below how the relationships established in this paper lead very naturally to some numerical algorithms for the estimation of Clebsch–Gordan and Wigner coefficients. The latter represent probability amplitudes of quantum interactions: as such, a rich literature in Mathematical Physics has been concerned with recipes for their numerical estimation. Our procedure lends itself to easy implementation and can be simply extended to very general compact groups, although in this paper we focus solely on  $SO(3)$ .

The plan of this paper is as follows: in Section 2 we introduce our general probabilistic setting and provide some preliminary notation and background material. In Section 3 we discuss basic facts on representation theory, while in Sections 4 and 5 we obtain our main results, including the aforementioned explicit characterization of polyspectra. These results are applied in Section 6 to derive explicit expressions in some important cases (such as  $\chi^2$  random fields). Section 7 is devoted to further issues that we see as the seeds for future research: they concern, in particular, the connection with the representation theory of the symmetric group, and the Monte Carlo estimation of Clebsch–Gordan coefficients.

In the subsequent sections, every random element is defined on an appropriate probability space  $(\Omega, \mathcal{F}, P)$ .

## 2. General setting

In this paper, we focus on real-valued, centered, square-integrable and isotropic random fields on the sphere  $S^2 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1\}$ . A centered and square integrable random field  $T$  on  $S^2$  is just a collection of random variables of the type  $T = \{T(x) : x \in S^2\}$  such that, for every  $x \in S^2$ ,  $ET(x) = 0$  and  $ET^2(x) < \infty$ . In the following, whenever we write that  $T$  is a field on  $S^2$ , we will implicitly assume that  $T$  is real-valued, centered and square-integrable. From now on, we shall distinguish between two notions of isotropy, which we name *strong isotropy* and *weak isotropy of order  $n$*  ( $n \geq 2$ ).

**Strong isotropy**– The field  $T$  is said to be *strongly isotropic* if, for every  $k \in \mathbb{N}$ , every  $x_1, \dots, x_k \in S^2$  and every  $g \in SO(3)$  (the group of rotations in  $\mathbb{R}^3$ ) we have

$$\{T(x_1), \dots, T(x_k)\} \stackrel{d}{=} \{T(gx_1), \dots, T(gx_k)\}, \tag{2.1}$$

where  $\stackrel{d}{=}$  denotes equality in distribution.

**Weak isotropy**– The field  $T$  is said to be  *$n$ -weakly isotropic* ( $n \geq 2$ ) if  $E|T(x)|^n < \infty$  for every  $x \in S^2$ , and if, for every  $x_1, \dots, x_n \in S^2$  and every  $g \in SO(3)$ ,

$$E[T(x_1) \times \dots \times T(x_n)] = E[T(gx_1) \times \dots \times T(gx_n)].$$

The following statement, whose proof is elementary, indicates some relations between the two notions of isotropy described above.

**Proposition 1.** 1. *A strongly isotropic field with finite moments of some order  $n \geq 2$  is also  $n$ -weakly isotropic.*  
 2. *Suppose that the field  $T$  is  $n$ -weakly isotropic for every  $n \geq 2$  (in particular,  $E|T(x)|^n < \infty$  for every  $n \geq 2$  and every  $x \in S^2$ ) and that, for every  $k \geq 1$  and every  $(x_1, \dots, x_k)$ , the law of the vector  $\{T(x_1), \dots, T(x_k)\}$  is determined by its moments. Then,  $T$  is also strongly isotropic.*

Now suppose that  $T$  is a strongly isotropic field, and denote by  $dx$  the Lebesgue measure on  $S^2$ . Since the variance  $ET(x)^2$  is finite and independent of  $x$  (by isotropy), one deduces immediately that

$$E \left[ \int_{S^2} T(x)^2 dx \right] < \infty,$$

from which one infers that the random path  $x \mapsto T(x)$  is a.s. square integrable with respect to the Lebesgue measure. Then, it is a standard result that the following spectral representation holds:

$$T(x) = \sum_{l=0}^{\infty} \sum_{m=-l}^l a_{lm} Y_{lm}(x), \quad \text{where } a_{lm} \triangleq \int_{S^2} T(x) \overline{Y_{lm}(x)} dx, \tag{2.2}$$

and where the complex-valued functions  $\{Y_{lm} : l \geq 0, m = -l, \dots, l\}$  are the so-called *spherical harmonics*, to be defined below. The spectral representation (2.2) must be understood in the  $L^2(\Omega \times S^2)$  sense, i.e.

$$\lim_{L \rightarrow \infty} E \left\| T - \sum_{l=0}^L \sum_{m=-l}^l a_{lm} Y_{lm} \right\|_{L^2(S^2)}^2 = 0,$$

where  $L^2(S^2)$  is the complex Hilbert space of functions on  $S^2$ , which are square-integrable with respect to  $dx$ . If, moreover, the trajectories of  $T(x)$  are a.s. continuous, then the representation (2.2) holds pointwise, i.e.

$$\lim_{L \rightarrow \infty} \left\{ T(x) - \sum_{l=0}^L \sum_{m=-l}^l a_{lm} Y_{lm}(x) \right\} = 0 \quad \text{for all } x \in S^2, \text{ a.s.-} P,$$

see for instance [29] or [8]. The spherical harmonics  $\{Y_{lm}\}_{m=-l, \dots, l}$  are the eigenfunctions of the Laplace-Beltrami operator on the sphere, denoted by  $\Delta_{S^2}$ , satisfying the relation  $\Delta_{S^2} Y_{lm} = -l(l+1)Y_{lm}$ . These functions can be represented by means of spherical coordinates  $x = (\theta, \varphi)$  as follows:

$$Y_{lm}(\theta, \varphi) = \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_{lm}(\cos \theta) \exp(im\varphi), \quad \text{for } m > 0,$$

$$Y_{lm}(\theta, \varphi) = (-1)^m \overline{Y_{l,-m}}(\theta, \varphi), \quad \text{for } m < 0, 0 \leq \theta \leq \pi, 0 \leq \varphi < 2\pi,$$

where  $P_{lm}(\cos \theta)$  denotes the associated Legendre polynomial of degree  $l, m$ , i.e.

$$P_{lm}(x) = (-1)^m (1-x^2)^{m/2} \frac{d^m}{dx^m} P_l(x), \quad P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2-1)^l, \quad m = 0, 1, 2, \dots, l, l = 0, 1, 2, 3, \dots$$

The random spherical harmonics coefficients  $\{a_{lm}\}$  appearing in (2.2) form a triangular array of zero-mean and square-integrable random variables, which are complex-valued for  $m \neq 0$  and such that  $E a_{lm} \overline{a_{l'm'}} = \delta_l^{l'} \delta_m^{m'} C_l$ , the bar denoting complex conjugation. Here, and for the rest of the paper, the symbol  $\delta_b^a$  is equal to one if  $a = b$  and zero otherwise. We also write  $C_l = E |a_{lm}|^2, l \geq 0$ , to indicate the *angular power spectrum* of  $T$  (we stress that the quantity  $C_l$  does not depend on  $m$  – see e.g. [30] for a proof of this fact). Observe that, by definition of the spherical harmonics,  $a_{lm} = (-1)^m \overline{a_{l,-m}}$ . Note also that a convenient route to derive (2.2) is by means of an appropriate version of the *stochastic Peter-Weyl theorem* – see for instance [31] or [9], as well as Section 3.1.

Observe that the representation (2.2) still holds for fields  $\{T(x)\}$  that are not necessarily isotropic, but such that the random path  $x \mapsto T(x)$  is  $P$ -a.s. square integrable with respect to the Lebesgue measure  $dx$ . Indeed, if the last property holds, then one has that,  $P$ -almost surely,

$$\lim_{L \rightarrow \infty} \int_{S^2} \left( T(x) - \sum_{l=0}^L \sum_{m=-l}^l a_{lm} Y_{lm}(x) \right)^2 dx = 0. \tag{2.3}$$

In this case, however, none of the previously stated properties on the array  $\{a_{lm}\}$  holds in general. By an argument similar to those displayed above, a sufficient condition to have that  $x \mapsto T(x)$  is  $P$ -a.s. Lebesgue-square integrable is that  $\sup_{x \in S^2} E T(x)^2 < \infty$ .

The next result, that we record for future reference, is proved in [30].

**Proposition 2.** *Let  $T$  be a centered, square-integrable and strongly isotropic random field. Let the coefficients  $\{a_{lm}\}$  be defined according to (2.2). Then, for every  $l, m$ , one has that  $E |a_{lm}|^2 < \infty$ . Moreover, for every  $l \geq 1$ , the coefficients  $\{a_{l0}, \dots, a_{ll}\}$  are independent if and only if they are Gaussian. If the vector  $\{a_{l0}, \dots, a_{ll}\}$  is Gaussian, one also has that  $\Re(a_{lm})$  and  $\Im(a_{lm})$  are independent and identically distributed for every fixed  $m = 1, \dots, l$  ( $\Re(z)$  and  $\Im(z)$  stand, respectively, for the real and imaginary parts of  $z$ ).*

The following result formalizes the fact that, in general, one cannot deduce strong isotropy from weak isotropy. The proof makes use of Proposition 1.

**Proposition 3.** *For every  $n \geq 2$ , there exists a  $n$ -weakly isotropic field  $T$  such that  $T$  is not strongly isotropic.*

**Proof.** Fix  $l \geq 1$ , and consider a vector

$$b_m, \quad m = -l, \dots, l,$$

of centered complex-valued random variables such that: (i)  $b_0$  is real, (ii)  $b_{-m} = (-1)^m \overline{b_m}$  ( $m = 1, \dots, l$ ), (iii) the vector  $\{b_0, \dots, b_l\}$  is not Gaussian and is composed of independent random variables, (iv) for every  $k = 1, \dots, n$ , the (possibly mixed) moments of order  $k$  of the variables  $\{b_0, \dots, b_l\}$  coincide with those of a vector  $\{a_0, \dots, a_l\}$  of independent, centered and complex-valued Gaussian random variables with common variance  $C_l$  and such that  $a_0$  is real and, for every  $m = 1, \dots, l$ ,

the real and imaginary parts of  $a_m$  are independent and identically distributed (the existence of a vector such as  $\{b_0, \dots, b_l\}$  is easily proved). Now define the two fields

$$T(x) = \sum_{m=-l}^l b_m Y_{lm}(x) \quad \text{and} \quad T^*(x) = \sum_{m=-l}^l a_m Y_{lm}(x).$$

By Proposition 2,  $T^*$  is strongly isotropic, and also  $n$ -weakly isotropic by Proposition 1. By construction, one also has that  $T$  is  $n$ -weakly isotropic. However,  $T$  cannot be strongly isotropic, since this would violate Proposition 2 (indeed, if  $T$  was isotropic, one would have an example of an isotropic field whose harmonic coefficients  $\{b_0, \dots, b_l\}$  are independent and non-Gaussian). ■

In what follows, we use the symbol  $A \otimes B$  to indicate the Kronecker product between two matrices  $A$  and  $B$ . Given  $n \geq 2$ , we denote by  $\Pi(n)$  the class of partitions of the set  $\{1, \dots, n\}$ . Given an element  $\pi \in \Pi(n)$ , we write  $\pi = \{b_1, \dots, b_k\}$  to indicate that the sets  $b_j \subseteq \{1, \dots, n\}, j = 1, \dots, k$ , are the blocks of  $\pi$ . The blocks of a partition are always listed according to the lexicographic order, that is: the block  $b_1$  always contains 1, the block  $b_2$  contains the least element of  $\{1, \dots, n\}$  not contained in  $b_1$ , and so on. Also the elements within each block  $b_j$  are written in increasing order. For instance, if a partition  $\pi$  of  $\{1, \dots, 5\}$  is composed of the blocks  $\{1, 3\}, \{5, 4\}$  and  $\{2\}$ , we will write  $\pi$  in the form  $\pi = \{\{1, 3\}, \{2\}, \{4, 5\}\}$ .

**Definition A.** (A1) Let the field  $T$  admit the representation (2.2), and suppose that, for some  $n \geq 2$ , one has that  $E |a_{lm}|^n < \infty$  for every  $l, m$ . Then,  $T$  is said to have finite spectral moments of order  $n$ .

(A2) Suppose that  $T$  has finite spectral moments of order  $n \geq 2$ , and, for  $l \geq 0$ , use the notation

$$a_l = (a_{l-1}, \dots, a_{l0}, \dots, a_{ll}). \tag{2.4}$$

The polyspectrum of order  $n - 1$ , associated with  $T$ , is given by the collection of vectors

$$S_{l_1 \dots l_n} = E [a_{l_1} \otimes a_{l_2} \otimes \dots \otimes a_{l_n}], \tag{2.5}$$

where  $0 \leq l_1, l_2, \dots, l_n$ . Note that the vector  $S_{l_1 \dots l_n}$  appearing in (2.5) has dimension  $(2l_1 + 1) \times \dots \times (2l_n + 1)$ .

(A3) Suppose that  $T$  has finite spectral moments of order  $n \geq 2$ . The (mixed) cumulant polyspectrum of order  $n - 1$ , associated with  $T$ , is given by the vectors

$$S_{l_1 \dots l_n}^c = \sum_{\pi = \{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! E [\otimes_{i \in b_1} a_{i_1}] \otimes \dots \otimes E [\otimes_{i \in b_k} a_{i_1}], \tag{2.6}$$

where  $0 \leq l_1, l_2, \dots, l_n$ , and, for every block  $b_j = \{i_1, \dots, i_p\}$ , we use the notation

$$E [\otimes_{i \in b_j} a_{i_1}] = E [a_{i_{1_1}} \otimes \dots \otimes a_{i_{1_p}}]$$

(recall that we always list the elements of  $b_j$  in such a way that  $i_1 \leq \dots \leq i_p$ ). Plainly, the vector  $S_{l_1 \dots l_n}^c$  in (2.6) has also dimension  $(2l_1 + 1) \times \dots \times (2l_n + 1)$ .

**Remark.** Suppose that  $T$  has finite spectral moments of order  $n \geq 2$ . Then, by selecting frequencies  $l_1 = l_2 = \dots = l_3 = l \geq 0$ , one obtains that

$$\underbrace{S_{l \dots l}^c}_{n \text{ times}} := S_{l \dots l}^c(n) = \sum_{\pi = \{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! E [(a_l)^{\otimes |b_1|}] \otimes \dots \otimes E [(a_l)^{\otimes |b_k|}] \tag{2.7}$$

where  $|b_j|$  stands for the size of the block  $b_j$ , and we use the notation

$$(a_l)^{\otimes |b_j|} = \underbrace{a_l \otimes \dots \otimes a_l}_{|b_j| \text{ times}}$$

### 3. Preliminary material

#### 3.1. Representation theory for SO(3)

We start by reviewing some background material on the special group of rotations SO(3), i.e. the space of  $3 \times 3$  real matrices  $A$  such that  $A'A = I_3$  (the three-dimensional identity matrix) and  $\det(A) = 1$ . We first recall that each element  $g \in \text{SO}(3)$  can be parametrized by the set  $(\varphi, \vartheta, \psi)$  of the so-called Euler angles ( $0 \leq \varphi < 2\pi, 0 \leq \vartheta \leq \pi, 0 \leq \psi < 2\pi$ ); indeed each rotation in  $\mathbb{R}^3$  can be realized sequentially as

$$A = A(g) = R(\psi, \vartheta, \varphi) = R_z(\varphi)R_x(\vartheta)R_z(\psi) \tag{3.8}$$

where  $R_z(\varphi), R_x(\vartheta), R_z(\psi) \in \text{SO}(3)$  can be expressed by means of the following general definitions, valid for every angle  $\alpha$ ,

$$R_z(\alpha) = \begin{pmatrix} \cos \alpha & -\sin \alpha & 0 \\ \sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad R_x(\alpha) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \alpha & -\sin \alpha \\ 0 & \sin \alpha & \cos \alpha \end{pmatrix}.$$

The representation (3.8) is unique except for  $\vartheta = 0$  or  $\vartheta = \pi$ , in which case only the sum  $\varphi + \psi$  is determined. In words, the rotation is realized by rotating first by  $\psi$  around the axis  $z$ , then rotating around the initial  $x$  axis by  $\vartheta$ , then rotating by  $\varphi$  around the initial  $z$  axis. It is clear that the last two rotations identify one point on the sphere, so the whole operation could be also interpreted as rotating by  $\psi$  the tangent plane at the North Pole, and then moving the latter to a location in  $S^2$ .

In these coordinates, a complete set of irreducible matrix representations for  $\text{SO}(3)$  is provided by the Wigner's  $D$  matrices  $D^l(\psi, \vartheta, \varphi) = \{D_{mn}^l(\psi, \vartheta, \varphi)\}_{m,n=-l,\dots,l}$ , of dimensions  $(2l+1) \times (2l+1)$  for  $l = 0, 1, 2, \dots$ ; we refer to classical textbooks, such as [13,2] or [1], for any unexplained definition or result concerning group representation theory. An analytic expression for the elements of Wigner's  $D$  matrices is provided by

$$D_{mn}^l(\psi, \vartheta, \varphi) = e^{-in\psi} d_{mn}^l(\vartheta) e^{im\varphi}, \quad m, n = -(2l+1), \dots, 2l+1$$

where the indices  $m, n$  indicate, respectively, columns and rows, and

$$d_{mn}^l(\vartheta) = (-1)^{l-n} [(l+m)!(l-m)!(l+n)!(l-n)!]^{1/2} \sum_k (-1)^k \frac{(\cos \frac{\vartheta}{2})^{m+n+2k} (\sin \frac{\vartheta}{2})^{2l-m-n-2k}}{k!(l-m-k)!(l-n-k)!(m+n+k)!},$$

and the sum runs over all  $k$  such that the factorials are non-negative; see [12, Chapter 4] for a huge collection of alternative expressions. Here we simply recall that the elements of  $D^l(\psi, \vartheta, \varphi)$  are related to the spherical harmonics by the relationship

$$D_{0m}^l(\varphi, \vartheta, \psi) = (-1)^m \sqrt{\frac{4\pi}{2l+1}} Y_{l-m}(\vartheta, \varphi) = \sqrt{\frac{4\pi}{2l+1}} Y_{lm}^*(\vartheta, \varphi). \tag{3.9}$$

In other words, the spherical harmonics correspond (up to a constant) to the elements of the “central” column in the Wigner's  $D$  matrix. Such matrices operate irreducibly and equivalently on  $(2l+1)$  spaces (the so-called isotypical spaces), each of them spanned by a different column  $n$  of the matrix representation itself. The elements of column  $n$  correspond to the so-called *spin  $n$*  spherical harmonics, which enjoy great importance in particle physics and in harmonic expansions for tensor valued random fields, see [32]. In this paper, we restrict our attention only to the usual  $n = 0$  spherical harmonics, which correspond to usual scalar functions.

**Remark.** By exploiting relation (3.9), it is not difficult to show that the usual spectral representation for random fields on the sphere, as given in (2.2), is just the stochastic Peter–Weyl Theorem on the quotient space  $S^2 = \text{SO}(3)/\text{SO}(2)$ . Indeed, by the stochastic Peter–Weyl Theorem (see e.g. [9]) we obtain, for any square integrable and isotropic random field  $\{T(g) : g \in \text{SO}(3)\}$ ,

$$T(g) = T(\varphi, \vartheta, \psi) = \sum_l \sum_{m,n} a_{lmn} \sqrt{\frac{2l+1}{8\pi^2}} D_{mn}^l(\varphi, \vartheta, \psi),$$

where  $dg$  is the Haar (uniform) measure on  $\text{SO}(3)$  with total mass  $8\pi^2$ . Now if we consider the restriction of  $T(g)$  to  $S^2 = \text{SO}(3)/\text{SO}(2)$ , denoted by  $T_{S^2}(\varphi, \vartheta)$ , we deduce that

$$\begin{aligned} a_{lmn} &= \int_{\text{SO}(3)} T_{S^2}(g) \sqrt{\frac{2l+1}{8\pi^2}} \overline{D_{mn}^l}(g) dg \\ &= \int_{S^2} T_{S^2}(\varphi, \vartheta) \left\{ \int_0^{2\pi} e^{in\psi} d\psi \right\} \sqrt{\frac{2l+1}{8\pi^2}} d_{mn}^l(\vartheta) e^{-im\varphi} \sin \vartheta d\varphi d\vartheta, \\ &= \int_{S^2} T_{S^2}(\varphi, \vartheta) \delta_n^0(2\pi) \sqrt{\frac{2l+1}{8\pi^2}} d_{mn}^l(\vartheta) e^{-im\varphi} \sin \vartheta d\varphi d\vartheta, \end{aligned}$$

the second equality following from the fact that  $T_{S^2}(g)$  is constant with respect to  $\psi$ . We can thus conclude that

$$a_{lmn} = \begin{cases} 0 & \text{for } n \neq 0 \\ \sqrt{2\pi} a_{lm} & \text{for } n = 0, \end{cases}$$

where the array  $\{a_{lm}\}$  is defined by (2.2).

### 3.2. The Clebsch–Gordan matrices

It follows from standard representation theory that we can exploit the family  $\{D^l\}_{l=0,1,2,\dots}$  to build alternative (reducible) representations, either by taking the tensor product family  $\{D^{l_1} \otimes D^{l_2}\}_{l_1, l_2}$ , or by considering direct sums  $\left\{\bigoplus_{l=|l_2-l_1|}^{l_2+l_1} D^l\right\}_{l_1, l_2}$ . These representations have dimensions

$$(2l_1 + 1)(2l_2 + 1) \times (2l_1 + 1)(2l_2 + 1)$$

and are unitarily equivalent, whence there exists a unitary matrix  $C_{l_1 l_2}$  such that

$$\{D^{l_1} \otimes D^{l_2}\} = C_{l_1 l_2} \left\{ \bigoplus_{l=|l_2-l_1|}^{l_2+l_1} D^l \right\} C_{l_1 l_2}^* \tag{3.10}$$

The matrix  $C_{l_1 l_2}$  is a  $\{(2l_1 + 1)(2l_2 + 1) \times (2l_1 + 1)(2l_2 + 1)\}$  block matrix, whose blocks, of dimensions  $(2l_2 + 1) \times (2l_1 + 1)$ , are customarily denoted by  $C_{l_1(m_1)l_2}^l$ ,  $m_1 = -l_1, \dots, l_1$ ; the elements of such a block are indexed by  $m_2$  (over rows) and  $m$  (over columns; note that  $m = -(2l + 1), \dots, 2l + 1$ ). More precisely,

$$C_{l_1 l_2} = [C_{l_1(m_1)l_2}^l]_{m_1=-l_1, \dots, l_1; l=|l_2-l_1|, \dots, l_2+l_1} \tag{3.11}$$

$$C_{l_1(m_1)l_2}^l = \{C_{l_1 m_1 l_2 m_2}^{lm}\}_{m_2=-l_2, \dots, l_2; m=-l, \dots, l} \tag{3.12}$$

**Remark.** The fact that the two matrices  $D^{l_1} \otimes D^{l_2}$  and  $\bigoplus_{l=|l_2-l_1|}^{l_2+l_1} D^l$  have the same dimension follows from the elementary relation (valid for any integers  $l_1, l_2 \geq 0$ ):

$$\sum_{l=|l_2-l_1|}^{l_1+l_2} (2l + 1) = (2l_1 + 1)(2l_2 + 1). \tag{3.13}$$

By induction, one also obtains that, for every  $n \geq 3$ ,

$$\sum_{\lambda_1=|l_2-l_1|}^{l_1+l_2} \sum_{\lambda_2=|l_3-\lambda_1|}^{\lambda_1+l_3} \dots \sum_{\lambda_{n-1}=|l_n-\lambda_{n-2}|}^{\lambda_{n-2}+l_n} (2\lambda_{n-1} + 1) = \prod_{j=1}^n (2l_j + 1), \tag{3.14}$$

for any integers  $l_1, \dots, l_n \geq 0$  (relation (3.14) is needed in Section 5.2).

The *Clebsch–Gordan coefficients* for  $SO(3)$  are then defined as the collection  $\{C_{l_1 m_1 l_2 m_2}^{lm}\}$  of the elements of the unitary matrices  $C_{l_1 l_2}$ . These coefficients were introduced in Mathematics in the XIX century, as motivated by the analysis of invariants in Algebraic Geometry; in the 20th century, they have gained an enormous importance in the quantum theory of angular momentum, where  $C_{l_1 m_1 l_2 m_2}^{lm}$  represents the *probability amplitude* that two particles with total angular momentum  $l_1, l_2$  and momentum projection on the  $z$ -axis  $m_1$  and  $m_2$  are coupled to form a system with total angular momentum  $l$  and projection  $m$  (see e.g. [33]). Their use in the analysis of isotropic random fields is much more recent, see for instance [16] and the references therein.

**Remark (More on the Structure of the Clebsch–Gordan Matrices).** To ease the reading of the subsequent discussion, we provide an alternative way of building a Clebsch–Gordan matrix  $C_{l_1 l_2}$ , starting from any enumeration of its entries. Fix integers  $l_1, l_2 \geq 0$  such that  $l_1 \leq l_2$  (this is just for notational convenience), and consider the Clebsch–Gordan coefficients  $\{C_{l_1 m_1 l_2 m_2}^{lm}\}$  given in (3.11)–(3.12). According to the above discussion, we know that: (i)  $-l_i \leq m_i \leq l_i$  for  $i = 1, 2$ , (ii)  $l_2 - l_1 \leq l \leq l_1 + l_2$ , (iii)  $-l \leq m \leq l$ , and (iv) the symbols  $(l_1, m_1, l_2, m_2)$  label rows, whereas the pairs  $(l, m)$  are attached to columns. Now introduce the total order  $\prec_c$  on the “column pairs”  $(l, m)$ , by setting that  $(l, m) \prec_c (l', m')$ , whenever either  $l < l'$  or  $l = l'$  and  $m < m'$ . Analogously, introduce a total order  $\prec_r$  over the “row symbols”  $(l_1, m_1, l_2, m_2)$ , by setting that  $(l_1, m_1, l_2, m_2) \prec_r (l'_1, m'_1, l'_2, m'_2)$ , if either  $m_1 < m'_1$ , or  $m_1 = m'_1$  and  $m_2 < m'_2$  (recall that  $l_1$  and  $l_2$  are fixed). One can check that the set of column pairs (resp. row symbols) can now be written as a *saturated chain*<sup>1</sup> with respect to  $\prec_c$  (resp.  $\prec_r$ ) with a least element given by  $(l_2 - l_1, -(l_2 - l_1))$  (resp.  $(l_1, -l_1, l_2, -l_2)$ ) and a maximal element given by  $(l_2 + l_1, l_2 + l_1)$

<sup>1</sup> Given a finite set  $A = \{a_j : j = 1, \dots, N\}$  and an order  $\prec$  on  $A$ , one says that  $A$  is a *saturated chain* with respect to  $\prec$  if there exists a permutation  $\pi$  of  $\{1, \dots, N\}$  such that

$$a_{\pi(1)} \prec a_{\pi(2)} \prec \dots \prec a_{\pi(N-1)} \prec a_{\pi(N)}.$$

In this case,  $a_{\pi(1)}$  and  $a_{\pi(N)}$  are called, respectively, the least and the maximal elements of the chain (see [34, p. 99]).

(resp.  $(l_1, l_1, l_2, l_2)$ ). Then, (A) dispose the columns from west to east, increasingly according to  $\prec_c$ , (B) dispose the rows from north to south, increasingly according to  $\prec_r$ . For instance, by setting  $l_1 = 0$  and  $l_2 \geq 1$ , one obtains that  $C_{l_1 l_2}$  is the  $(2l_2 + 1) \times (2l_2 + 1)$  square matrix  $\{C_{00l_2 m_2}^{l_2 m_2}\}$  with column indices  $m = -(2l_2 + 1), \dots, (2l_2 + 1)$  and row indices  $m_2 = -(2l_2 + 1), \dots, (2l_2 + 1)$  (from the subsequent discussion, one also deduces that, in general,  $C_{00l_2 m_2}^{lm} = \delta_l^{l_2} \delta_m^{m_2}$ ). By selecting  $l_1 = l_2 = 1$ , one sees that  $C_{11}$  is the  $9 \times 9$  matrix with elements  $C_{1m_1 1m_2}^{lm}$  (for  $m_1, m_2 = -1, 0, 1; l = 0, 1, 2, m = -l, \dots, l$ ) arranged as follows:

$$\begin{pmatrix} C_{1,-1;1,-1}^{0,0} & C_{1,-1;1,-1}^{1,-1} & C_{1,-1;1,-1}^{10} & C_{1,-1;1,-1}^{11} & C_{1,-1;1,-1}^{2,-2} & C_{1,-1;1,-1}^{2,-1} & C_{1,-1;1,-1}^{2,0} & C_{1,-1;1,-1}^{2,1} & C_{1,-1;1,-1}^{2,2} \\ C_{1,-1;1,0}^{0,0} & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ C_{1,-1;1,1}^{0,0} & \dots & \dots & C_{1,-1;1,1}^{11} & \dots & \dots & \dots & \dots & \dots \\ C_{1,0;1,-1}^{0,0} & \dots & \dots & \dots & \dots & \dots & C_{1,0;1,-1}^{2,0} & \dots & \dots \\ C_{1,0;1,0}^{0,0} & \dots & \dots & \dots & C_{1,0;1,0}^{2,-2} & \dots & \dots & \dots & \dots \\ C_{1,0;1,1}^{0,0} & \dots & \dots & \dots & \dots & \dots & \dots & C_{1,0;1,1}^{2,1} & \dots \\ C_{1,1;1,-1}^{0,0} & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ C_{1,1;1,0}^{0,0} & \dots & \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ C_{1,1;1,1}^{0,0} & C_{1,1;1,1}^{1,-1} & C_{1,1;1,1}^{1,0} & C_{1,1;1,1}^{1,1} & C_{1,1;1,1}^{2,-2} & C_{1,1;1,1}^{2,-1} & C_{1,1;1,1}^{2,0} & C_{1,1;1,1}^{2,1} & C_{1,1;1,1}^{2,2} \end{pmatrix}.$$

Explicit expressions for the Clebsch–Gordan coefficients of  $SO(3)$  are known, but they are in general hardly manageable. We have for instance (see [12], expression 8.2.1.5)

$$C_{l_1 m_1 l_2 m_2}^{l_3 - m_3} := (-1)^{l_1 + l_3 + m_2} \sqrt{2l_3 + 1} \left[ \frac{(l_1 + l_2 - l_3)! (l_1 - l_2 + l_3)! (l_1 - l_2 + l_3)!}{(l_1 + l_2 + l_3 + 1)!} \right]^{1/2} \\ \times \left[ \frac{(l_3 + m_3)! (l_3 - m_3)!}{(l_1 + m_1)! (l_1 - m_1)! (l_2 + m_2)! (l_2 - m_2)!} \right]^{1/2} \\ \times \sum_z \frac{(-1)^z (l_2 + l_3 + m_1 - z)! (l_1 - m_1 + z)!}{z! (l_2 + l_3 - l_1 - z)! (l_3 + m_3 - z)! (l_1 - l_2 - m_3 + z)!},$$

where the summation runs over all  $z$ 's such that the factorials are non-negative. This expression becomes much neater for  $m_1 = m_2 = m_3 = 0$ , where we have

$$C_{l_1 0 l_2 0}^{l_3 0} = \begin{cases} 0, & \text{for } l_1 + l_2 + l_3 \text{ odd} \\ (-1)^{\frac{l_1 + l_2 - l_3}{2}} \frac{\sqrt{2l_3 + 1} [(l_1 + l_2 + l_3)/2]!}{[(l_1 + l_2 - l_3)/2]! [(l_1 - l_2 + l_3)/2]! [(-l_1 + l_2 + l_3)/2]!} \\ \times \left\{ \frac{(l_1 + l_2 - l_3)! (l_1 - l_2 + l_3)! (-l_1 + l_2 + l_3)!}{(l_1 + l_2 + l_3 + 1)!} \right\}^{1/2}, & \text{for } l_1 + l_2 + l_3 \text{ even.} \end{cases}$$

The coefficients, moreover, enjoy a nice set of symmetry and orthogonality properties, playing a crucial role in our results to follow. From unitary equivalence we have the two relations:

$$\sum_{m_1, m_2} C_{l_1 m_1 l_2 m_2}^{lm} C_{l_1 m_1' l_2 m_2'}^{l'm'} = \delta_l^{l'} \delta_m^{m'}, \tag{3.15}$$

$$\sum_{l, m} C_{l_1 m_1 l_2 m_2}^{lm} C_{l_1 m_1' l_2 m_2'}^{lm} = \delta_{m_1}^{m_1'} \delta_{m_2}^{m_2'}, \tag{3.16}$$

in particular, (3.15) is a consequence of the orthogonality of row vectors, whereas (3.16) comes from the orthogonality of columns. Other properties are better expressed in terms of the Wigner's coefficients, which are related to the Clebsch–Gordan coefficients by the identities (see [12], Chapter 8)

$$\begin{pmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & -m_3 \end{pmatrix} = (-1)^{l_3 + m_3} \frac{1}{\sqrt{2l_3 + 1}} C_{l_1 - m_1 l_2 - m_2}^{l_3 m_3} \tag{3.17}$$

$$C_{l_1 m_1 l_2 m_2}^{l_3 m_3} = (-1)^{l_1 - l_2 + m_3} \sqrt{2l_3 + 1} \begin{pmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & -m_3 \end{pmatrix}. \tag{3.18}$$

The Wigner's  $3j$  (and, consequently, the Clebsch–Gordan) coefficients are real-valued, they are different from zero only if  $m_1 + m_2 + m_3 = 0$  and  $l_i \leq l_j + l_k$  for all  $i, j, k = 1, 2, 3$  (triangle conditions), and they satisfy the symmetry conditions

$$\begin{pmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & m_3 \end{pmatrix} = (-1)^{l_1 + l_2 + l_3} \begin{pmatrix} l_1 & l_2 & l_3 \\ -m_1 & -m_2 & -m_3 \end{pmatrix},$$



$$\begin{pmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & m_3 \end{pmatrix} = (-1)^{\text{sign}(\pi)} \begin{pmatrix} l_{\pi(1)} & l_{\pi(2)} & l_{\pi(3)} \\ m_2 & m_3 & m_1 \end{pmatrix},$$

where  $\pi$  is a permutation of  $\{1, 2, 3\}$ , and  $\text{sign}(\pi)$  denotes the sign of  $\pi$ . It follows also that for  $m_1 = m_2 = m_3 = 0$ , the coefficients  $C_{l_1 0 l_2 0}^{l_3 0}$  are different from zero only when the sum  $l_1 + l_2 + l_3$  is even. Later in the paper, we shall also need the so-called Wigner's  $6j$  coefficients, which are defined by

$$\begin{Bmatrix} a & b & e \\ c & d & f \end{Bmatrix} := \sum_{\substack{\alpha, \beta, \gamma \\ \varepsilon, \delta, \phi}} (-1)^{e+f+\varepsilon+\phi} \begin{pmatrix} a & b & e \\ \alpha & \beta & \varepsilon \end{pmatrix} \begin{pmatrix} c & d & e \\ \gamma & \delta & -\varepsilon \end{pmatrix} \begin{pmatrix} a & d & f \\ \alpha & \delta & -\phi \end{pmatrix} \begin{pmatrix} c & b & f \\ \gamma & \beta & \phi \end{pmatrix}, \tag{3.19}$$

see [12], chapter 9 for analytic expressions and a full set of properties; we simply recall here that the Wigner's  $6j$  coefficients can themselves be given an important interpretation in terms of group representations, namely they relate different *coupling schemes* in the decomposition of tensor product into direct sum representations, see [35] for further details.

For future reference, we also recall some further standard properties of Kronecker (tensor) products and direct sums of matrices: we have

$$\bigoplus_{i=1}^n (A_i B_i) = \left( \bigoplus_{i=1}^n A_i \right) \left( \bigoplus_{i=1}^n B_i \right), \tag{3.20}$$

$$\left( \bigoplus_{i=1}^n A_i \right) \otimes B = \bigoplus_{i=1}^n (A_i \otimes B) \tag{3.21}$$

and, provided all matrix products are well-defined,

$$(AB \otimes C) = (A \otimes I_n) (B \otimes C). \tag{3.22}$$

Here,  $\bigoplus_{i=1}^n A_i$  is defined as the block diagonal matrix  $\text{diag} \{A_1, \dots, A_n\}$  if  $A_i$  is a set of square matrices of order  $r_i \times r_i$ , whereas it is defined as the stacked column vector of order  $(\sum_{i=1}^n r_i) \times 1$  if the  $A_i$  are  $r_i \times 1$  column vectors.

#### 4. Characterization of polyspectra

##### 4.1. Four general statements

The following result is well-known. As it is crucial in our arguments to follow and we failed to locate any explicit reference, we shall provide a short proof for the sake of completeness. Note that, in the sequel, we use the symbol  $a_l$  to indicate the  $(2l + 1)$ -dimensional complex-valued random vector defined in (2.4).

**Lemma 4.** *Let  $T$  be a strongly isotropic field on  $S^2$ , and let the harmonic coefficients  $\{a_{lm}\}$  be defined according to (2.2). Then, for every  $l \geq 0$  and every  $g \in \text{SO}(3)$ , we have*

$$D^l(g) a_l \stackrel{d}{=} a_l, \quad l = 0, 1, 2, \dots \tag{4.23}$$

The equality (4.23) must be understood in the sense of finite-dimensional distributions for sequences of random vectors, that is, (4.23) takes place if, and only if, for every  $k \geq 1$  and every  $0 \leq l_1 < l_2 < \dots < l_k$ ,

$$\{D^{l_1}(g) a_{l_1}, \dots, D^{l_k}(g) a_{l_k}\} \stackrel{d}{=} \{a_{l_1}, \dots, a_{l_k}\}. \tag{4.24}$$

**Proof.** We provide the proof of (4.24) only when  $k = 1$  and  $l_1 = l \geq 1$ . The general case is obtained analogously. By strong isotropy, we have that, for every  $l \geq 1$ , every  $g \in \text{SO}(3)$  and every  $x_1, \dots, x_n \in S^2$ , the equality (2.1) takes place. Now, (2.1) can be rewritten as follows:

$$\begin{aligned} & \left\{ \sum_l \sum_m a_{lm} Y_{lm}(x_1), \dots, \sum_l \sum_m a_{lm} Y_{lm}(x_n) \right\} \stackrel{d}{=} \left\{ \sum_l \sum_m a_{lm} Y_{lm}(gx_1), \dots, \sum_l \sum_m a_{lm} Y_{lm}(gx_n) \right\} \\ & = \left\{ \sum_l \sum_m a_{lm} \sum_{m'} D_{m'm}^l(g) Y_{lm'}(x_1), \dots, \sum_l \sum_m a_{lm} \sum_{m'} D_{m'm}^l(g) Y_{lm'}(x_n) \right\} \\ & = \left\{ \sum_l \sum_{m'} \tilde{a}_{lm'} Y_{lm'}(x_1), \dots, \sum_l \sum_{m'} \tilde{a}_{lm'} Y_{lm'}(x_n) \right\}, \end{aligned} \tag{4.25}$$

where we write

$$\tilde{a}_{lm'} \triangleq \sum_m a_{lm} D_{m'm}^l(g), \tag{4.26}$$

and we have used

$$\{Y_{lm}(gx_1), \dots, Y_{lm}(gx_n)\} \equiv \left\{ \sum_{m'} D_{m'm}^l(g) Y_{lm'}(x_1), \dots, \sum_{m'} D_{m'm}^l(g) Y_{lm'}(x_n) \right\} \tag{4.27}$$

which follows from the group representation property and the identity (3.9). To conclude, just observe that (4.25) implies that

$$\tilde{a}_{lm'} = \int_{S^2} T(gx) \overline{Y_{lm'}(x)} dx, \quad m' = -l, \dots, l,$$

yielding that, due to strong isotropy and with obvious notation,  $\tilde{a}_l \stackrel{d}{=} a_l$ . The conclusion follows from the fact that, thanks to (4.26),

$$\tilde{a}_l = D^l(g) a_l. \quad \blacksquare$$

The next theorem connects the invariance properties of the vectors  $\{a_l\}$  to the representations of  $SO(3)$ . We need first to establish some notation. For every  $0 \leq l_1, l_2, \dots, l_n$ , we shall write

$$\Delta_{l_1 \dots l_n} \triangleq \int_{SO(3)} \{D^{l_1}(g) \otimes D^{l_2}(g) \otimes \dots \otimes D^{l_n}(g)\} dg, \tag{4.28}$$

$$\Delta_{l_1 \dots l_n}(g) \triangleq D^{l_1}(g) \otimes D^{l_2}(g) \otimes \dots \otimes D^{l_n}(g), \quad g \in SO(3), \tag{4.29}$$

and use the symbol  $S_{l_1 \dots l_n}$  (whenever is well-defined), as given in formula (2.5). We stress that  $\Delta_{l_1 \dots l_n}$  and  $\Delta_{l_1 \dots l_n}(g)$  are square matrices with  $(2l_1 + 1) \times \dots \times (2l_n + 1)$  rows and  $S_{l_1 \dots l_n}$  is a column vector with  $(2l_1 + 1) \times \dots \times (2l_n + 1)$  elements. The following result applies to an arbitrary  $n \geq 2$ : see [16] for some related results in the case  $n = 3, 4$ .

**Proposition 5.** *Let  $T$  be a strongly isotropic field with moments of order  $n \geq 2$ . Then, for every  $0 \leq l_1, l_2, \dots, l_n$  and every fixed  $g^* \in SO(3)$*

$$\Delta_{l_1 \dots l_n} S_{l_1 \dots l_n} = S_{l_1 \dots l_n} \tag{4.30}$$

$$\Delta_{l_1 \dots l_n}(g^*) S_{l_1 \dots l_n} = S_{l_1 \dots l_n}. \tag{4.31}$$

On the other hand, fix  $n \geq 2$  and assume that  $T(x)$  is not necessarily an isotropic random field on the sphere s.t.  $\sup_x (E |T(x)|^n) < \infty$ . Then  $T(\cdot)$  is  $P$ -almost surely Lebesgue square integrable and the  $n$ th order spectral moments of  $T$  exist and are finite. If, moreover, (4.30) holds for every  $0 \leq l_1 \leq \dots \leq l_n$ , then one has that, for every  $g \in SO(3)$ ,

$$E [D^{l_1}(g) a_{l_1} \otimes \dots \otimes D^{l_n}(g) a_{l_n}] = E [a_{l_1} \otimes \dots \otimes a_{l_n}], \tag{4.32}$$

and  $T$  is  $n$ -weakly isotropic.

**Proof.** By strong isotropy and Lemma 4, one has

$$E \{D^{l_1}(g) a_{l_1} \otimes \dots \otimes D^{l_n}(g) a_{l_n}\} = E \{a_{l_1} \otimes \dots \otimes a_{l_n}\} \quad \text{for all } g \in SO(3), l_1, \dots, l_n \in \mathbb{N}^n.$$

Now assume that  $g$  is sampled randomly (and independently of the  $\{a_l\}$ ) according to some probability measure, say  $P_0$ , on  $SO(3)$ . From the property (3.22) of tensor products and trivial manipulations, we obtain (with obvious notation and by independence)

$$\begin{aligned} E \{D^{l_1}(\cdot) a_{l_1} \otimes \dots \otimes D^{l_n}(\cdot) a_{l_n}\} &= E \{[D^{l_1}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot)] [a_{l_1} \otimes \dots \otimes a_{l_n}]\} \\ &= E_0 \{D^{l_1}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot)\} E \{a_{l_1} \otimes \dots \otimes a_{l_n}\}. \end{aligned}$$

Now, if one chooses  $P_0$  to be equal to the Haar (uniform) measure on  $SO(3)$ , one has that

$$E_0 \{D^{l_1}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot)\} = \Delta_{l_1 \dots l_n},$$

thus giving (4.30). On the other hand, if one chooses  $P_0$  to be equal to the Dirac mass at some  $g^* \in SO(3)$ , one has that

$$E_0 \{D^{l_1}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot)\} = \Delta_{l_1 \dots l_n}(g^*),$$

which shows that (4.31) is satisfied.

Now let  $T$  satisfy the assumptions of the second part of the statement for some  $n \geq 2$ . We recall first that the representation (2.2) continues to hold, in a pathwise sense. To see that the  $n$ th order joint moments of the harmonic coefficients  $a_{lm}$  are finite it is enough to use Jensen's inequality, along with a standard version of the Fubini theorem, to obtain that

$$\begin{aligned} E |a_{lm}|^n &= E \left| \int_{S^2} T(x) \overline{Y_{lm}(x)} dx \right|^n \leq E \int_{S^2} |T(x)|^n |Y_{lm}(x)|^n dx \\ &\leq \left\{ \sup_{x \in S^2} |Y_{lm}(x)|^n \right\} \left\{ \sup_{x \in S^2} E |T(x)|^n \right\} \\ &\leq \left( \frac{2l+1}{4\pi} \right)^{n/2} \left\{ \sup_{x \in S^2} E |T(x)|^n \right\} < \infty. \end{aligned}$$

It is then straightforward that, if  $S_{l_1 \dots l_n}$  satisfies (4.30), one also has that for any fixed  $\bar{g} \in \text{SO}(3)$

$$\begin{aligned} E \left\{ [D^{l_1}(\bar{g}) \otimes \dots \otimes D^{l_n}(\bar{g})] [a_{l_1} \otimes \dots \otimes a_{l_n}] \right\} &= [D^{l_1}(\bar{g}) \otimes \dots \otimes D^{l_n}(\bar{g})] E [a_{l_1} \otimes \dots \otimes a_{l_n}] \\ &= [D^{l_1}(\bar{g}) \otimes \dots \otimes D^{l_n}(\bar{g})] \Delta_{l_1 \dots l_n} S_{l_1 \dots l_n} \\ &= \left\{ [D^{l_1}(\bar{g}) \otimes \dots \otimes D^{l_n}(\bar{g})] \int_{\text{SO}(3)} \{D^{l_1}(g) \otimes \dots \otimes D^{l_n}(g)\} dg \right\} S_{l_1 \dots l_n} \\ &= \left\{ \int_{\text{SO}(3)} \{D^{l_1}(\bar{g}g) \otimes D^{l_2}(\bar{g}g) \otimes \dots \otimes D^{l_n}(\bar{g}g)\} dg \right\} S_{l_1 \dots l_n} \\ &= \Delta_{l_1 \dots l_n} S_{l_1 \dots l_n} = E \{a_{l_1} \otimes \dots \otimes a_{l_n}\}, \end{aligned}$$

which proves the  $n$ -th spectral moment is invariant to rotations. The fact that  $T$  is  $n$ -weakly isotropic is a consequence of the spectral representation (2.2). ■

Note that relation (4.30) can be rephrased by saying that, for a strongly isotropic field, the joint moment vector  $E \{a_{l_1} \otimes a_{l_2} \otimes \dots \otimes a_{l_n}\}$  must be an eigenvector of the matrix (4.28) for every  $n \geq 2$  and every  $0 \leq l_1 \leq \dots \leq l_n$ . A similar characterization holds for cumulants polyspectra. Recall the notation  $S_{l_1 \dots l_n}^c$  introduced in (2.6).

**Proposition 6.** *Let  $T$  be a strongly isotropic field with moments of order  $n \geq 2$ . Then, for every  $0 \leq l_1, l_2, \dots, l_n$  and every fixed  $g^* \in \text{SO}(3)$ ,*

$$\Delta_{l_1 \dots l_n} S_{l_1 \dots l_n}^c = S_{l_1 \dots l_n}^c \tag{4.33}$$

$$\Delta_{l_1 \dots l_n} (g^*) S_{l_1 \dots l_n}^c = S_{l_1 \dots l_n}^c. \tag{4.34}$$

On the other hand, fix  $n \geq 2$  and assume that  $T(x)$  is not necessarily an isotropic random field on the sphere s.t.  $\sup_x (E |T(x)|^n) < \infty$ . Then  $T(\cdot)$  is  $P$ -almost surely Lebesgue square integrable and the  $n$ th order spectral moments of  $T$  exist and are finite. If, moreover, (4.33) holds for every  $0 \leq l_1 \leq \dots \leq l_n$ , then one has that, for every  $g \in \text{SO}(3)$ , relation (4.32) holds, and  $T$  is  $n$ -weakly isotropic.

**Proof.** For every  $x_1, \dots, x_n \in S^2$ , write  $\text{Cum} \{T(x_1), \dots, T(x_n)\}$  the joint cumulant of the random variables  $T(x_1), \dots, T(x_n)$ . By using isotropy, one has that, for every  $g \in \text{SO}(3)$ ,

$$\text{Cum} \{T(x_1), \dots, T(x_n)\} = \text{Cum} \{T(gx_1), \dots, T(gx_n)\}. \tag{4.35}$$

Hence, by using the well-known multilinearity properties of cumulants, one deduces that (with obvious notation)

$$\begin{aligned} \text{Cum} \{T(x_1), \dots, T(x_n)\} &= \sum_{l_1 m_1, \dots, l_n m_n} \text{Cum} \{a_{l_1 m_1}, \dots, a_{l_n m_n}\} Y_{l_1 m_1}(x_1) \dots Y_{l_n m_n}(x_n) \\ &= \sum_{l_1 m_1, \dots, l_n m_n} \text{Cum} \{a_{l_1 m_1}, \dots, a_{l_n m_n}\} Y_{l_1 m_1}(gx_1) \dots Y_{l_n m_n}(gx_n), \end{aligned} \tag{4.36}$$

and relations (4.33)–(4.34) are deduced by rewriting (4.36) by means of the identity

$$\{Y_{l_1 m_1}(gx_1), \dots, Y_{l_n m_n}(gx_n)\} \equiv \left\{ \sum_{m'} D_{m' m}^{l_1}(g) Y_{l_1 m'}(x_1), \dots, \sum_{m'} D_{m' m}^{l_n}(g) Y_{l_n m'}(x_n) \right\}.$$

The second part of the statement is proved by arguments analogous to the ones used in the proof of Proposition 5. ■

We now present an alternative (and more involved) characterization of the cumulant polyspectra associated with an isotropic field. Given  $n \geq 2$  and a partition  $\pi = \{b_1, \dots, b_k\} \in \Pi(n)$ , we build a permutation  $v^\pi = (v^\pi(1), \dots, v^\pi(n)) \in \mathfrak{S}_n$  as follows: (i) write the partition

$$\pi = \{b_1, \dots, b_k\} = \{(i_1^1, \dots, i_{|b_1|}^1), \dots, (i_1^k, \dots, i_{|b_k|}^k)\} \tag{4.37}$$

(where  $|b_j| \geq 1$  stands for the size of  $b_j$ ) by means of the convention outlined in Section 2 (that is, order the blocks and the elements within each block according to the lexicographic order); (ii) define  $v^\pi = \mathfrak{S}_n$  by simply removing the brackets in (4.37), that is, set

$$v^\pi = (v^\pi(1), \dots, v^\pi(n)) = (i_1^1, \dots, i_{|b_1|}^1, i_1^2, \dots, i_{|b_2|}^2, \dots, i_1^k, \dots, i_{|b_k|}^k).$$

For instance, if a partition  $\pi$  of  $\{1, \dots, 6\}$  is composed of the blocks  $\{1, 3\}$ ,  $\{6, 4\}$  and  $\{2, 5\}$ , one first writes  $\pi$  in the form  $\pi = \{\{1, 3\}, \{2, 5\}, \{4, 6\}\}$ , and then defines  $v^\pi = (v^\pi(1), \dots, v^\pi(6)) = (1, 3, 2, 5, 4, 6)$ . Given  $n \geq 2, 0 \leq l_1 \leq \dots \leq l_n$ , and  $\pi \in \Pi(n)$ , we define the matrix

$$\Delta_{l_1 \dots l_n}^\pi \triangleq \int_{\text{SO}(3)} \{D^{l_{v^\pi(1)}}(g) \otimes D^{l_{v^\pi(2)}}(g) \otimes \dots \otimes D^{l_{v^\pi(n)}}(g)\} dg, \tag{4.38}$$

obtained from the matrix  $\Delta_{l_1 \dots l_n}$  in (4.28), by permuting the indexes  $l_i$  according to  $v^\pi$ . Plainly, if  $v^\pi$  is equal to the identity permutation, then  $\Delta_{l_1 \dots l_n}^\pi = \Delta_{l_1 \dots l_n}$ . We also set, for every fixed  $g \in \text{SO}(3)$ ,

$$\Delta_{l_1 \dots l_n}^\pi(g) \triangleq D^{l_{v^\pi(1)}}(g) \otimes D^{l_{v^\pi(2)}}(g) \otimes \dots \otimes D^{l_{v^\pi(n)}}(g).$$

**Proposition 7.** *Let  $T$  be a strongly isotropic field with finite moments of order  $n \geq 2$ . For  $0 \leq l_1, l_2, \dots, l_n$ , define  $S_{l_1 \dots l_n}^c$  according to (2.6). Then, for every  $0 \leq l_1, l_2, \dots, l_n$ , and every  $g \in \text{SO}(3)$*

$$S_{l_1 \dots l_n}^c = \sum_{\pi=\{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! \Delta_{l_1 \dots l_n}^\pi E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}] \tag{4.39}$$

$$= \sum_{\pi=\{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! \Delta_{l_1 \dots l_n}^\pi(g) E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}]. \tag{4.40}$$

On the other hand, fix  $n \geq 2$  and assume that  $T(x)$  is a (not necessarily isotropic) random field on the sphere s.t.  $\sup_x (E|T(x)|^n) < \infty$ . Then, the  $n$ th order spectral moments and cumulants of  $T$  exist and are finite. If moreover (4.40) holds for every  $0 \leq l_1, l_2, \dots, l_n$  and every  $g \in \text{SO}(3)$ , then one has that  $T$  is  $n$ -weakly isotropic.

**Proof.** Fix  $\pi = \{b_1, \dots, b_k\} \in \Pi(n)$ . By strong isotropy and Lemma 4, one has that, for a fixed  $g^* \in \text{SO}(3)$ , the quantity

$$E[\otimes_{i \in b_1} D^{l_i}(g) a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} D^{l_i}(g) a_{l_i}] = \Delta_{l_1 \dots l_n}^\pi(g^*) E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}]$$

does not depend on  $g^*$ , so that

$$\begin{aligned} E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}] &= \Delta_{l_1 \dots l_n}^\pi(g^*) E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}] \\ &= \int_{\text{SO}(3)} \Delta_{l_1 \dots l_n}^\pi(g) E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}] dg \\ &= \Delta_{l_1 \dots l_n}^\pi E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}]. \end{aligned}$$

To prove the second part of the statement, suppose that  $T(x)$  verifies  $\sup_x (E|T(x)|^n) < \infty$ , and that its associated harmonic coefficients verify (4.40). Then, for every fixed rotation  $g^* \in \text{SO}(3)$ ,

$$\begin{aligned} &\sum_{\pi=\{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! E[\otimes_{i \in b_1} D^{l_i}(g^*) a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} D^{l_i}(g^*) a_{l_i}] \\ &= \sum_{\pi=\{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! [D^{l_{v^\pi(1)}}(g^*) \otimes \dots \otimes D^{l_{v^\pi(n)}}(g^*)] E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}] \\ &= \sum_{\pi=\{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! \times \Delta_{l_1 \dots l_n}^\pi(g^*) E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}] \\ &= \sum_{\pi=\{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! E[\otimes_{i \in b_1} a_{l_i}] \otimes \dots \otimes E[\otimes_{i \in b_k} a_{l_i}]. \end{aligned}$$

By the definition of cumulants, this last equality gives that

$$E[D^{l_1}(g^*) a_{l_1} \otimes \dots \otimes D^{l_n}(g^*) a_{l_n}] = E[a_{l_1} \otimes \dots \otimes a_{l_n}].$$

Since  $g^*$  is arbitrary, the  $n$ -weak isotropy follows from (2.2). ■

**Remark.** By combining (4.33) and (4.39) we obtain for instance that the  $n$ th cumulant polyspectrum of an isotropic field verifies the identity

$$S_{l_1 \dots l_n}^c = \Delta_{l_1 \dots l_n} S_{l_1 \dots l_n}^c = \sum_{\pi = \{b_1, \dots, b_k\} \in \Pi(n)} (-1)^{k-1} (k-1)! \Delta_{l_1 \dots l_n}^\pi E \left[ \otimes_{i \in b_1} a_{i \cdot} \right] \otimes \dots \otimes E \left[ \otimes_{i \in b_k} a_{i \cdot} \right].$$

**5. Angular polyspectra and the structure of  $\Delta_{l_1 \dots l_n}$**

5.1. Spectra of strongly isotropic fields

Our aim in this section is to investigate more deeply the structure of the matrix  $\Delta_{l_1 \dots l_n}$  appearing in (4.28), in order to derive an explicit characterization for the angular polyspectra. As a preliminary example, we deal with the case  $n = 2$ .

**Proposition 8.** For integers  $l_1, l_2 \geq 0$ , one has that

$$\Delta_{l_1 l_2} = \int_{SO(3)} \{D^{l_1}(g) \otimes D^{l_2}(g)\} dg = \delta_{l_1}^{l_2} C_{l_1, l_2}^{00} (C_{l_1, l_2}^{00})', \tag{5.41}$$

that is: if  $l_1 \neq l_2$ , then  $\Delta_{l_1 l_2}$  is a  $(2l_1 + 1)(2l_2 + 1) \times (2l_1 + 1)(2l_2 + 1)$  zero matrix; if  $l_1 = l_2$ , then  $\Delta_{l_1 l_2} = \Delta_{l_1 l_1}$  is given by  $C_{l_1, l_1}^{00} (C_{l_1, l_1}^{00})'$ .

**Proof.** Using the equivalence of the two representations  $D^{l_1}(g) \otimes D^{l_2}(g)$  and  $\bigoplus_{\lambda=|l_2-l_1|}^{l_2+l_1} D^\lambda(g)$ , as well as the definition of the Clebsch–Gordan matrices, we obtain that

$$\int_{SO(3)} \{D^{l_1}(g) \otimes D^{l_2}(g)\} dg = C_{l_1 l_2} \left[ \int_{SO(3)} \left\{ \bigoplus_{\lambda=|l_2-l_1|}^{l_2+l_1} D^\lambda(g) \right\} dg \right] C_{l_1 l_2}^* \tag{5.42}$$

Now, if  $l_1 \neq l_2$ , then the RHS of (5.42) is equal to the zero matrix since, as a consequence of the Peter–Weyl theorem and for  $\lambda \neq 0$ , the entries of  $D^\lambda(\cdot)$  are orthogonal to the constants. If  $l_1 = l_2$ , then the integrated matrix on the RHS of (5.42) becomes  $\int_{SO(3)} \{\bigoplus_{\lambda=0}^{2l_1} D^\lambda(g)\} dg$ , that is, a  $(2l_1 + 1)^2 \times (2l_1 + 1)^2$  matrix which is zero everywhere, except for the entry in the top-left corner, which is equal to one (since  $\int_{SO(3)} dg = 1$ ). The proof is concluded by checking that

$$C_{l_1 l_1} \left[ \int_{SO(3)} \left\{ \bigoplus_{\lambda=0}^{2l_1} D^\lambda(g) \right\} dg \right] C_{l_1 l_1}^* = C_{l_1, l_1}^{00} (C_{l_1, l_1}^{00})'. \quad \blacksquare$$

**Remark.** Recall that  $C_{l_1, l_2}^{00}$  is a column vector of dimension  $(2l_1 + 1)(2l_2 + 1)$ , corresponding to the first column of the matrix  $C_{l_1 l_2}$ . Also, according e.g. to [12, formula 8.5.1.1], one has that

$$C_{l_1, l_2}^{00} = \left\{ \frac{(-1)^{m_1}}{2l_1 + 1} \delta_{l_1}^{l_2} \delta_{m_1}^{-m_2} \right\}_{m_1 = -l_1, \dots, l_1; m_2 = -l_2, \dots, l_2}.$$

Proposition 8 provides a characterization of the spectrum of a strongly isotropic field.

**Corollary 9.** Let  $T$  be a strongly isotropic field with second moments, and let the vectors of the harmonic coefficients  $\{a_i\}$  be defined according to (2.2). Then, for any integers  $l_1, l_2 \geq 0$ , one has that

$$E \{a_{l_1 \cdot} \otimes a_{l_2 \cdot}\} = \left\{ \frac{(-1)^{m_1}}{2l_1 + 1} \delta_{l_1}^{l_2} \delta_{m_1}^{-m_2} C_{l_1} \right\} \tag{5.43}$$

for some  $C_{l_1} \geq 0$  depending uniquely on  $l_1$ .

**Proof.** According to (4.30), one has that

$$E \{a_{l_1 \cdot} \otimes a_{l_2 \cdot}\} = \delta_{l_1}^{l_2} C_{l_1, l_2}^{00} (C_{l_1, l_2}^{00})' E \{a_{l_1 \cdot} \otimes a_{l_2 \cdot}\},$$

implying that  $E \{a_{l_1 \cdot} \otimes a_{l_2 \cdot}\}$  is (a) equal to the zero vector for  $l_1 \neq l_2$ , and (b) of the form  $C_{l_1} \times C_{l_1, l_2}^{00}$ , for some constant  $C_{l_1}$ , when  $l_1 = l_2$ . To see that  $C_{l_1}$  cannot be negative, just observe that  $a_{l_1 0}$  is real-valued for every  $l_1 \geq 0$ , so that (5.43) yields that

$$C_{l_1} = (2l_1 + 1) \times E \{a_{l_1 0}^2\}. \quad \blacksquare$$

In the subsequent two subsections, we shall obtain, for every  $n \geq 3$ , a characterization of  $\Delta_{l_1, \dots, l_n}$  and  $E\{a_{l_1} \otimes \dots \otimes a_{l_n}\}$ , respectively analogous to (5.41) and (5.43).

5.2. The structure of  $\Delta_{l_1, \dots, l_n}$

We first need to establish some further notation.

**Definition B.** Fix  $n \geq 3$ . For integers  $l_1, \dots, l_n \geq 0$ , we define  $C_{l_1, \dots, l_n}$  to be the unitary matrix, of dimension

$$\prod_{j=1}^n (2l_j + 1) \times \prod_{j=1}^n (2l_j + 1),$$

connecting the following two equivalent representations of  $SO(3)$

$$D^{l_1}(\cdot) \otimes D^{l_2}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot) \tag{5.44}$$

and

$$\bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} \bigoplus_{\lambda_2=|l_3-\lambda_1|}^{l_3+\lambda_1} \dots \bigoplus_{\lambda_{n-1}=|l_n-\lambda_{n-2}|}^{l_n+\lambda_{n-2}} D^{\lambda_{n-1}}(\cdot). \tag{5.45}$$

**Remarks.** (1) Fix  $l_1, \dots, l_n \geq 0$ , as well as  $g \in SO(3)$ . Then, the matrix

$$\bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} \bigoplus_{\lambda_2=|l_3-\lambda_1|}^{l_3+\lambda_1} \dots \bigoplus_{\lambda_{n-1}=|l_n-\lambda_{n-2}|}^{l_n+\lambda_{n-2}} D^{\lambda_{n-1}}(g) \tag{5.46}$$

is a block-diagonal matrix, obtained as follows. (a) Consider vectors of integers  $(\lambda_1, \dots, \lambda_{n-1})$  satisfying the relations  $|l_2 - l_1| \leq \lambda_1 \leq l_1 + l_2$ , and  $|l_{k+1} - \lambda_{k-1}| \leq \lambda_k \leq l_{k+1} + \lambda_{k-1}$ , for  $k = 2, \dots, n - 1$ . (b) Introduce a (total) order  $<_0$  on the collection of these vectors by saying that

$$(\lambda_1, \dots, \lambda_{n-1}) <_0 (\lambda'_1, \dots, \lambda'_{n-1}), \tag{5.47}$$

whenever either  $\lambda_1 < \lambda'_1$ , or there exists  $k = 2, \dots, n - 2$  such that  $\lambda_j = \lambda'_j$  for every  $j = 1, \dots, k$ , and  $\lambda_{k+1} < \lambda'_{k+1}$ . (c) Associate to each vector  $(\lambda_1, \dots, \lambda_{n-1})$  the matrix  $D^{\lambda_{n-1}}(g)$ . (d) Construct a block-diagonal matrix by disposing the matrices  $D^{\lambda_{n-1}}(g)$  from the top-left corner to the bottom-right corner, in increasing order with respect to  $<_0$ . As an example, consider the case where  $n = 3$  and  $l_1 = l_2 = l_3 = 1$ . Here, the vectors  $(\lambda_1, \lambda_2)$  involved in the direct sum (5.45) are (in increasing order with respect to  $<_0$ )

$$(0, 1), (1, 0), (1, 1), (1, 2), (2, 1), (2, 2) \text{ and } (2, 3),$$

and the matrix (5.46) is therefore given by

$$\begin{pmatrix} D^1(g) & \dots & \dots & \dots & \dots & \dots & \dots \\ \dots & 1 & \dots & \dots & \dots & \dots & \dots \\ \dots & \dots & D^1(g) & \dots & \dots & \dots & \dots \\ \dots & \dots & \dots & D^2(g) & \dots & \dots & \dots \\ \dots & \dots & \dots & \dots & D^1(g) & \dots & \dots \\ \dots & \dots & \dots & \dots & \dots & D^2(g) & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots & D^3(g) \end{pmatrix} \tag{5.48}$$

where the dots indicate zero entries, and we have used the fact that  $D^0(g) \equiv 1$ .

(2) The fact that the representation (5.45) has dimension  $\prod_{j=1}^n (2l_j + 1)$  is a direct consequence of formula (3.14).

(3) The fact that the two representations (5.44) and (5.45) are equivalent can be proved by iteration. Indeed, by standard representation theory, (5.44) is equivalent to

$$\bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} D^{\lambda_1}(\cdot) \otimes D^{l_3}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot),$$

which is in turn equivalent to

$$\bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} \bigoplus_{\lambda_2=|l_3-\lambda_1|}^{l_3+\lambda_1} D^{\lambda_2}(\cdot) \otimes D^{l_4}(\cdot) \otimes \dots \otimes D^{l_n}(\cdot).$$

By iterating the same procedure until all tensor products have disappeared (that is, by successively replacing the tensor product  $D^{\lambda_k}(\cdot) \otimes D^{k+2}(\cdot)$  with  $\bigoplus_{\lambda_{k+1}=|\lambda_k+2-\lambda_k|}^{k+2+\lambda_k} D^{\lambda_2}(\cdot)$  for  $k = 2, \dots, n - 1$ ), one obtains the desired conclusion.

For every  $n \geq 3$  and every  $l_1, \dots, l_n \geq 0$ , the elements of the matrix  $C_{l_1 \dots l_n}$ , introduced in Definition B, can be written in the form  $C_{l_1 m_1 \dots l_n m_n}^{\lambda_1 \dots \lambda_{n-1}, \mu_{n-1}}$ . The indices  $(m_1, \dots, m_n)$  are such that  $-l_i \leq m_i \leq l_i$  ( $i = 1, \dots, n$ ) and label rows; on the other hand, the indices  $(\lambda_1 \dots \lambda_{n-1}, \mu_{n-1})$  label columns, and verify the relations  $|l_2 - l_1| \leq \lambda_1 \leq l_1 + l_2$ ,  $|l_{k+1} - \lambda_{k-1}| \leq \lambda_k \leq l_{k+1} + \lambda_{k-1}$  ( $k = 2, \dots, n - 1$ ) and  $-\lambda_{n-1} \leq \mu_{n-1} \leq \lambda_{n-1}$ . It is well known (see e.g. [12]) that the quantity  $C_{l_1 m_1 \dots l_n m_n}^{\lambda_1 \dots \lambda_{n-1}, \mu_{n-1}}$  can be represented as a convolution of the Clebsch–Gordan coefficients introduced in Section 3.2, namely:

$$\begin{aligned} C_{l_1 m_1 \dots l_n m_n}^{\lambda_1 \dots \lambda_{n-1}, \mu_{n-1}} &= C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-2}, \mu_{n-2}} C_{l_{n-2} m_{n-2}}^{\lambda_{n-1}, \mu_{n-1}} \\ &= \sum_{\mu_{n-2}} \left\{ \sum_{\mu_1 \dots \mu_{n-3}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \dots C_{\lambda_{n-3} \mu_{n-3} l_{n-1} m_{n-1}}^{\lambda_{n-2} \mu_{n-2}} \right\} C_{l_{n-2} m_{n-2} l_n m_n}^{\lambda_{n-1}, \mu_{n-1}} \\ &= \sum_{\mu_1 \dots \mu_{n-2}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \dots C_{\lambda_{n-3} \mu_{n-3} l_{n-1} m_{n-1}}^{\lambda_{n-2} \mu_{n-2}} C_{l_{n-2} m_{n-2} l_n m_n}^{\lambda_{n-1}, \mu_{n-1}}. \end{aligned}$$

**Remark.** Given an enumeration of the coefficients  $C_{l_1 m_1 \dots l_n m_n}^{\lambda_1 \dots \lambda_{n-1}, \mu_{n-1}}$ , the matrix  $C_{l_1 \dots l_n}$  can be built (analogously to the case of the Clebsch–Gordan matrices of Section 3.2) by disposing rows (from top to bottom) and columns (from left to right) increasingly according to two separate total orders. The order  $\prec_r$  on the symbols  $(m_1, \dots, m_n)$  is obtained by setting that  $(m_1, \dots, m_n) \prec_r (m'_1, \dots, m'_n)$  whenever either  $m_1 < m'_1$ , or there exists  $k = 2, \dots, n - 1$  such that  $m_j = m'_j$  for every  $j = 1, \dots, k$ , and  $m_{k+1} < m'_{k+1}$ . The order  $\prec_c$  on the symbols  $(\lambda_1 \dots \lambda_{n-1}, \mu_{n-1})$  is obtained by setting that  $(\lambda_1 \dots \lambda_{n-1}, \mu_{n-1}) \prec_c (\lambda'_1 \dots \lambda'_{n-1}, \mu'_{n-1})$  whenever either  $(\lambda_1, \dots, \lambda_{n-1}) \prec_c (\lambda'_1, \dots, \lambda'_{n-1})$ , as defined in (5.47), or  $\lambda_i = \lambda'_i$  for every  $i = 1, \dots, n - 1$  and  $\mu_{n-1} < \mu'_{n-1}$ .

One has also the following (useful) alternative representation of generalized Clebsch–Gordan matrices.

**Proposition 10.** For every  $n \geq 3$  and every  $l_1, \dots, l_n \geq 0$ , one can represent the matrix  $C_{l_1 \dots l_n}$ , as follows

$$C_{l_1 \dots l_n} = \{C_{l_1 l_2 l_3 \dots l_{n-1}} \otimes I_{2l_n+1}\} \left\{ \left( \bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} \dots \bigoplus_{\lambda_{n-2}=|l_n-\lambda_{n-3}|}^{l_n+\lambda_{n-3}} C_{\lambda_{n-2} l_n} \right) \right\},$$

where  $I_m$  indicates a  $m \times m$  identity matrix. Also, one has that

$$\begin{aligned} C_{l_1 \dots l_n} &= (C_{l_1 l_2} \otimes I_{2l_3+1} \otimes \dots \otimes I_{2l_n+1}) \times \left[ \left( \bigoplus_{\lambda=|l_2-l_1|}^{l_2+l_1} C_{\lambda l_3} \right) \otimes \dots \otimes I_{2l_n+1} \right] \\ &\times \dots \times \left[ \left( \bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} \dots \bigoplus_{\lambda_{n-2}=|l_n-\lambda_{n-3}|}^{l_n+\lambda_{n-3}} C_{\lambda_{n-2} l_n} \right) \right], \end{aligned}$$

where  $\times$  stands for the usual product between matrices.

**Definition C.** For every  $n \geq 3$  and every  $l_1, \dots, l_n \geq 0$ , we define  $E_{l_1 \dots l_n}$  to be the  $\prod_{j=1}^n (2l_j + 1) \times \prod_{j=1}^n (2l_j + 1)$  square matrix

$$E_{l_1 \dots l_n} := \bigoplus_{\lambda_1=|l_2-l_1|}^{l_2+l_1} \dots \bigoplus_{\lambda_{n-1}=|l_n-\lambda_{n-2}|}^{l_n+\lambda_{n-2}} \delta_{\lambda_{n-1}}^0 I_{2\lambda_{n-1}+1}. \tag{5.49}$$

In other words,  $E_{l_1 \dots l_n}$  is the diagonal matrix built from the matrix (5.46), by replacing every block of the type  $D^{\lambda_{n-1}}(g)$ , with  $\lambda_{n-1} > 0$ , with a  $(2\lambda_{n-1} + 1) \times (2\lambda_{n-1} + 1)$  zero matrix, and by letting the  $1 \times 1$  blocks  $D^0(g) = 1$  unchanged. For instance, by setting  $n = 3$  and  $l_1 = l_2 = l_3 = 1$  (and by using (5.48)) one obtains a  $27 \times 27$  matrix  $E_{111}$  whose entries are all zero, except for the fourth element (starting from the top-left corner) of the main diagonal.

The following result states that the matrix  $\Delta_{l_1 \dots l_n}$  can be diagonalized in terms of  $C_{l_1 \dots l_n}$  and  $E_{l_1 \dots l_n}$ .

**Proposition 11.** The matrix  $\Delta_{l_1 \dots l_n}$  can be diagonalized as

$$\Delta_{l_1 \dots l_n} = C_{l_1 \dots l_n} E_{l_1 \dots l_n} C_{l_1 \dots l_n}^*, \tag{5.50}$$

where  $E_{l_1 \dots l_n}$  is the matrix introduced in Definition C.

**Proof.** One has that

$$\begin{aligned} \Delta_{l_1 \dots l_n} &= \int_{\text{SO}(3)} D^{l_1}(g) \otimes D^{l_2}(g) \otimes \dots \otimes D^{l_n}(g) \, dg \\ &= \int_{\text{SO}(3)} \left[ C_{l_1 \dots l_n} \begin{matrix} l_2+l_1 & l_3+\lambda_1 & \dots & l_n+\lambda_{n-2} \\ \oplus & \oplus & & \oplus \\ \lambda_1=|l_2-l_1| & \lambda_2=|l_3-\lambda_1| & & \lambda_{n-1}=|l_n-\lambda_{n-2}| \end{matrix} D^{\lambda_{n-1}}(g) C_{l_1 \dots l_n}^* \right] dg. \end{aligned} \tag{5.51}$$

By linearity and by the definition of the integral of a matrix-valued function, one has that the last line of (5.51) equals

$$C_{l_1 \dots l_n} \left[ \begin{matrix} l_2+l_1 & l_3+\lambda_1 & \dots & l_n+\lambda_{n-2} \\ \oplus & \oplus & & \oplus \\ \lambda_1=|l_2-l_1| & \lambda_2=|l_3-\lambda_1| & & \lambda_{n-1}=|l_n-\lambda_{n-2}| \end{matrix} \int_{\text{SO}(3)} D^{\lambda_{n-1}}(g) \, dg \right] C_{l_1 \dots l_n}^*.$$

Now observe that, if  $\lambda_{n-1} > 0$ , then  $\int_{\text{SO}(3)} D^{\lambda_{n-1}}(g) \, dg$  equals a  $(2\lambda_{n-1} + 1) \times (2\lambda_{n-1} + 1)$  zero matrix, whereas  $\int_{\text{SO}(3)} D^0(g) \, dg = \int_{\text{SO}(3)} 1 \, dg = 1$ . The conclusion is obtained by resorting to the definition of  $E_{l_1 \dots l_n}$  given in (5.49). ■

### 5.3. Existence and characterization of reduced polyspectra of arbitrary orders

Combining the previous Proposition with 5, we obtain the main result of this paper.

**Theorem 12.** *If a random field is strongly isotropic with finite moments of order  $n \geq 3$ , then for every  $l_1, \dots, l_n$  there exists two arrays  $P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3})$  and  $P_{l_1 \dots l_n}^C(\lambda_1, \dots, \lambda_{n-3})$ , with  $|l_2 - l_1| \leq \lambda_1 \leq l_2 + l_1, |l_3 - \lambda_1| \leq \lambda_2 \leq l_3 + \lambda_1, \dots, |l_{n-2} - \lambda_{n-4}| \leq \lambda_{n-3} \leq l_{n-2} + \lambda_{n-4}$ , such that*

$$Ea_{l_1 m_1} \dots a_{l_n m_n} = (-1)^{m_n} \sum_{\lambda_1=l_2-l_1}^{l_2+l_1} \dots \sum_{\lambda_{n-3}} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3} l_n - m_n} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) \tag{5.52}$$

$$\text{Cum} \{a_{l_1 m_1}, \dots, a_{l_n m_n}\} = (-1)^{m_n} \sum_{\lambda_1=l_2-l_1}^{l_2+l_1} \dots \sum_{\lambda_{n-3}} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3} l_n - m_n} P_{l_1 \dots l_n}^C(\lambda_1, \dots, \lambda_{n-3}) \tag{5.53}$$

$$C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3} l_n - m_n} = \sum_{\mu_1} \dots \sum_{\mu_{n-3}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \dots C_{\lambda_{n-3} \mu_{n-3} l_{n-1} m_{n-1}}^{l_n - m_n}. \tag{5.54}$$

**Remark.** For a fixed  $n \geq 2$ , the real-valued arrays  $\{P_{l_1 \dots l_n}(\cdot) : l_1, \dots, l_n \geq 0\}$  and  $\{P_{l_1 \dots l_n}^C(\cdot) : l_1, \dots, l_n \geq 0\}$  are, respectively, the *reduced polyspectrum of order  $n - 1$*  and the *reduced cumulant polyspectrum of order  $n - 1$*  associated with the underlying strongly isotropic random field.

**Proof of Theorem 12.** We shall prove only (5.52), since the proof of (5.53) is entirely analogous. By Propositions 5 and 11, if the random field is isotropic, then

$$S_{l_1 \dots l_n} = C_{l_1 \dots l_n} E_{l_1 \dots l_n} C_{l_1 \dots l_n}^* S_{l_1 \dots l_n},$$

that is, because  $C_{l_1 \dots l_n}$  is unitary

$$C_{l_1 \dots l_n}^* S_{l_1 \dots l_n} = E_{l_1 \dots l_n} C_{l_1 \dots l_n}^* S_{l_1 \dots l_n}.$$

It follows that  $S_{l_1 \dots l_n}$  is a solution if and only if the column vector  $C_{l_1 \dots l_n}^* S_{l_1 \dots l_n}$  has zeroes corresponding to the zeroes of  $E_{l_1 \dots l_n}$ , whereas the elements corresponding to unity can be arbitrary. In view of the orthonormality properties of  $C_{l_1 \dots l_n}^*$ , this condition is met if, and only if,  $S_{l_1 \dots l_n}$  is a linear combination of the columns in the matrix  $C_{l_1 \dots l_n}^*$  corresponding to non-zero elements of the diagonal  $E_{l_1 \dots l_n}$ . These linear combinations can be written explicitly as

$$\begin{aligned} &\sum_{\lambda_1=l_2-l_1}^{l_2-l_1} \sum_{\lambda_2=l_3-\lambda_1}^{l_3+\lambda_1} \dots \sum_{\lambda_{n-1}=l_n-\lambda_{n-2}}^{l_n+\lambda_{n-2}} C_{l_1 m_1 \dots l_n m_n}^{\lambda_1 \dots \lambda_{n-2} l_n m_n} \tilde{P}_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}, \lambda_{n-2}) \delta_l^0 \\ &= \sum_{\lambda_1=l_2-l_1}^{l_2-l_1} \sum_{\lambda_2=l_3-\lambda_1}^{l_3+\lambda_1} \dots \sum_{\lambda_{n-1}=l_n-\lambda_{n-2}}^{l_n+\lambda_{n-2}} \left\{ \sum_{\mu_1 \dots \mu_{n-2}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \dots C_{\lambda_{n-2} \mu_{n-2} l_n m_n}^{l_n} \delta_l^0 \right\} \tilde{P}_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}, \lambda_{n-2}) \\ &= \sum_{\lambda_1=l_2-l_1}^{l_2-l_1} \sum_{\lambda_2=l_3-\lambda_1}^{l_3+\lambda_1} \dots \sum_{\lambda_{n-1}=l_n-\lambda_{n-2}}^{l_n+\lambda_{n-2}} \left\{ \sum_{\mu_1 \dots \mu_{n-2}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \dots C_{\lambda_{n-2} \mu_{n-2} l_n m_n}^{00} \right\} \tilde{P}_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}, \lambda_{n-2}). \end{aligned}$$



Recalling again that

$$C_{l_1 m_1 l_2 m_2}^{0m} = \frac{(-1)^{m_1}}{2l_1 + 1} \delta_{l_1}^{l_2} \delta_{m_1}^{-m_2} \delta_m^0,$$

(see [12], 8.5.1.1), we obtain that

$$\begin{aligned} &= \sum_{\lambda_1=l_2-l_1}^{l_2-l_1} \sum_{\lambda_2=l_3-\lambda_1}^{l_3+\lambda_1} \cdots \sum_{\lambda_{n-1}=l_n-\lambda_{n-2}}^{l_n+\lambda_{n-2}} \left\{ \sum_{\mu_1 \cdots \mu_{n-2}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \cdots \frac{(-1)^{m_n}}{2l_n + 1} \delta_{\lambda_{n-2}}^{l_n} \delta_{\mu_{n-2}}^{-m_n} \right\} \times \tilde{P}_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}, \lambda_{n-2}) \\ &= \sum_{\lambda_1=l_2-l_1}^{l_2-l_1} \sum_{\lambda_2=l_3-\lambda_1}^{l_3+\lambda_1} \cdots \sum_{\lambda_{n-1}=l_n-\lambda_{n-2}}^{l_n+\lambda_{n-2}} \left\{ \sum_{\mu_1 \cdots \mu_{n-2}} C_{l_1 m_1 l_2 m_2}^{\lambda_1 \mu_1} C_{\lambda_1 \mu_1 l_3 m_3}^{\lambda_2 \mu_2} \cdots C_{\lambda_{n-3} \mu_{n-3} l_{n-1} m_{n-1}}^{l_n - m_n} (-1)^{m_n} \right\} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) \\ &= \sum_{\lambda_1=l_2-l_1}^{l_2-l_1} \sum_{\lambda_2=l_3-\lambda_1}^{l_3+\lambda_1} \cdots \sum_{\lambda_{n-1}=l_n-\lambda_{n-2}}^{l_n+\lambda_{n-2}} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3} l_n - m_n} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}), \end{aligned}$$

where we have set

$$P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) := \frac{1}{2l_n + 1} \tilde{P}_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}, l_n).$$

All there is left to show is that the coefficients of this linear combination are necessarily real. To see this, it is sufficient to specialize the previous discussion to the case where  $m_1 = m_2 = \dots = m_n = 0$ , and to observe that, in this case

$$E a_{l_1 0} \dots a_{l_n 0} = \sum_{\lambda_1} \cdots \sum_{\lambda_{n-3}} C_{l_1 0 \dots l_{n-1} 0}^{\lambda_1 \dots \lambda_{n-3} l_n 0} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3})$$

is real by definition (note indeed that the columns of  $C_{l_1 \dots l_n}$  are linearly independent). ■

Let us illustrate the previous results by some more examples.

**Examples.** For  $n = 3$ , Theorem 12 implies that, under isotropy

$$E a_{l_1 m_1} a_{l_2 m_2} a_{l_3 m_3} = (-1)^{m_3} C_{l_1 m_1 l_2 m_2}^{l_3 - m_3} P_{l_1 l_2 l_3}.$$

From this last relation, we can recover the so-called reduced bispectrum, noted  $b_{l_1 l_2 l_3}$ , defined for instance in [16,18,19], which satisfies indeed the relationship

$$P_{l_1 l_2 l_3} = b_{l_1 l_2 l_3} C_{l_1 0 l_2 0}^{l_3 0} \sqrt{\frac{(2l_1 + 1)(2l_2 + 1)}{(2l_3 + 1)4\pi}}.$$

For  $n = 4$  (i.e. the trispectrum, [16]) we obtain the expression

$$\begin{aligned} E a_{l_1 m_1} a_{l_2 m_2} a_{l_3 m_3} a_{l_4 m_4} &= (-1)^{m_4} \sum_{\lambda=|l_2-l_1|}^{l_2+l_1} C_{l_1 m_1 l_2 m_2 l_3 m_3}^{\lambda l_4 - m_4} P_{l_1 l_2 l_3 l_4}(\lambda) \\ &= \sum_{\lambda=|l_2-l_1|}^{l_2+l_1} \sum_{\mu=-\lambda}^{\lambda} C_{l_1 m_1 l_2 m_2}^{\lambda \mu} C_{\lambda \mu l_3 m_3}^{l_4 - m_4} P_{l_1 l_2 l_3 l_4}(\lambda). \end{aligned}$$

The next result gives a further probabilistic characterization of the reduced bispectrum.

**Proposition 13.** Fix  $n \geq 2$ . A real-valued array  $\{A_{l_1 \dots l_n}(\cdot) : l_1, \dots, l_n \geq 0\}$  is the reduced polyspectrum of order  $n - 1$  (resp. the reduced cumulant polyspectrum of order  $n - 1$ ) of some strongly isotropic random field if, and only if, there exists a sequence  $\{X_l : l \geq 0\}$  of zero-mean real-valued random variables such that

$$\sum_{l \geq 0} (2l + 1) E [X_l^2] < +\infty$$

and, for every  $l_1, \dots, l_n \geq 0$

$$E (X_{l_1} \cdots X_{l_n}) = \sum_{\lambda_1=l_2-l_1}^{l_2+l_1} \cdots \sum_{\lambda_{n-3}} C_{l_1 0 \dots l_{n-1} 0}^{\lambda_1 \dots \lambda_{n-3} l_n 0} A_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) \tag{5.55}$$

resp.

$$\text{Cum} \{X_{l_1}, \dots, X_{l_n}\} = \sum_{\lambda_1=l_2-l_1}^{l_2+l_1} \dots \sum_{\lambda_{n-3}} C_{l_1 0 \dots l_{n-1} 0}^{\lambda_1 \dots \lambda_{n-3} l_n 0} A_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}). \tag{5.56}$$

**Proof.** We shall only prove (5.55). For the necessity, it is enough to take  $X_l = a_{l0}$ , where  $a_{l0}$  is the harmonic coefficient of index  $(l, 0)$  associated with a strongly isotropic field with moments of all orders. For the sufficiency, we consider first the (anisotropic) random field

$$Z(x) = \sum_{l \geq 0} X_l Y_{l0}(x).$$

Then, by taking  $T(x) = Z(gx)$ , where  $g$  is sampled randomly with the uniform Haar measure on  $SO(3)$ , one obtains a random field with the desired characteristics. ■

There are two very important issues that are left open by Theorem 12. As a first issue, it seems natural to look for characterizations of the reduced polyspectra  $P_{l_1 \dots l_n}$ , at least under natural models of physical interest. As a second point, we note that the explicit expressions provided in Theorem 12 depend on the ordering  $l_1, \dots, l_n$  we chose for the decomposition of  $\Delta_{l_1 \dots l_n}$ . In the next two sections, we try to address these (and other) points.

### 6. Some explicit examples

In this section we provide explicit computations for the reduced polyspectra  $P_{l_1 \dots l_n}$  ( $n \geq 2$ ), or  $P_{l_1 \dots l_n}^C$ , for some models of physical interest. Of course, the Gaussian isotropic fields can be easily dealt with. Indeed, in this case one has that  $P_{l_1 \dots l_n}^C = 0$  for all  $n \geq 3$ . In what follows, we shall therefore be concerned with polyspectra of Gaussian subordinated isotropic fields, that is, random fields that can be written as a deterministic and non-linear function of some collection of Gaussian isotropic fields. In general, this class of random fields allow for a clear-cut mathematical treatment, whilst covering a great array of empirically relevant circumstances.

#### 6.1. A simple physical model

The general Gaussian-subordinated model has the form

$$T = \sum_{j=1}^q f_j H_j \left( T_G / \sqrt{E(T_G^2)} \right) = f_1 T_G + f_2 (T_G^2 / E(T_G^2) - 1) + \dots, \tag{6.57}$$

where  $f_j$  is a real constant,  $H_j(\cdot)$  denotes the  $j$ th Hermite polynomial (see e.g. [36]), and  $T_G$  is a Gaussian, zero-mean isotropic random field. Note that we have implicitly defined the sequence of Hermite polynomials in such a way that  $H_1(x) = x$ ,  $H_2(x) = x^2 - 1$ ,  $H_3(x) = x^3 - 3x$ , and so on. In this section, when no further specification is needed, the spectral decomposition of the underlying Gaussian field  $T_G$  is written

$$T_G = \sum_{lm} a_{lm} Y_{lm}.$$

We shall sometimes use the following notation

$$T = \sum_{lm} \tilde{a}_{lm} Y_{lm} = \sum_{j=1}^q f_j a_{lm}(j) Y_{lm}, \tag{6.58}$$

$$a_{lm}(j) = \int_{S^2} H_j \left( T_G(x) / \sqrt{E(T_G^2)} \right) \overline{Y_{lm}(x)} dx, \tag{6.59}$$

$$\tilde{a}_{lm} = \sum_{j=1}^q a_{lm}(j). \tag{6.60}$$

For instance, models of Cosmic Microwave Background radiation are currently dominated by assumptions such as the Sachs–Wolfe model with the so-called Bardeen’s potential (see e.g. [24] or [15]). The latter can be written down explicitly as

$$T = T_G + f_{NL} (T_G^2 - E T_G^2), \tag{6.61}$$

where  $f_{NL}$  is a nonlinearity parameter which depends upon physical constants in the associated “slow-roll” inflationary model (see e.g. [24]). Note that (6.61) can be written in the form (6.57), by setting  $f_1 = 1, f_2 = f_{NL} \times E(T_G^2)$  and  $f_j = 0$ , for  $j \geq 3$ .

The value of the constant  $f_{NL} \times E(T_G^2)$  is expected to be very small, namely of the order  $10^{-4}$  [24]. To simplify the discussion, we now assume that  $ET_G^2 = 1$ . In this case, by using (6.58)–(6.60), one has that

$$\begin{aligned} \tilde{a}_{lm} &= a_{lm} + f_{NL} a_{lm}(2), \\ a_{lm}(2) &= \int_{S^2} T^2 \bar{Y}_{lm} dx = \int_{S^2} \sum_{\ell_1 \ell_2} \sum_{m_1 m_2} a_{\ell_1 m_1} a_{\ell_2 m_2} Y_{\ell_1 m_1} Y_{\ell_2 m_2} \bar{Y}_{lm} dx \\ &= \sum_{\ell_1 \ell_2} \sum_{m_1 m_2} a_{\ell_1 m_1} a_{\ell_2 m_2} \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)}{(2l + 1)4\pi}} C_{\ell_1 0 \ell_2 0}^{l0} C_{\ell_1 m_1 \ell_2 m_2}^{lm}. \end{aligned}$$

It follows that

$$\tilde{C}_l := E|\tilde{a}_{lm}|^2 = C_l + 2f_{NL}^2 \sum_{l_1 l_2} C_{l_1} C_{l_2} \frac{(2l_1 + 1)(2l_2 + 1)}{4\pi(2l + 1)} (C_{l_1 0 l_2 0}^{l0})^2,$$

so that

$$\begin{aligned} \text{Var}(T) &= \sum_l \frac{2l + 1}{4\pi} \tilde{C}_l = \sum_l \frac{2l + 1}{4\pi} C_l + 2f_{NL}^2 \sum_{l_1 l_2} C_{l_1} C_{l_2} \frac{(2l_1 + 1)(2l_2 + 1)}{(4\pi)^2} \sum_l (C_{l_1 0 l_2 0}^{l0})^2 \\ &= \sum_l \frac{2l + 1}{4\pi} C_l + 2f_{NL}^2 \left\{ \sum_{l_1} C_{l_1} \frac{(2l_1 + 1)}{4\pi} \right\}^2 = \text{Var}(T_G) + f_{NL}^2 \text{Var}(H_2(T_G)), \end{aligned}$$

as expected, due to the orthogonality properties of Hermite polynomials. For the bispectrum, we obtain therefore

$$\begin{aligned} E\tilde{a}_{l_1 m_1} \tilde{a}_{l_2 m_2} \tilde{a}_{l_3 m_3} &= E\{(a_{l_1 m_1} + f_2 a_{l_1 m_1}(2))(a_{l_2 m_2} + f_2 a_{l_2 m_2}(2))(a_{l_3 m_3} + f_2 a_{l_3 m_3}(2))\} \\ &= f_2 E a_{l_1 m_1}(2) a_{l_2 m_2} a_{l_3 m_3} + f_2 E a_{l_1 m_1} a_{l_2 m_2}(2) a_{l_3 m_3} \\ &\quad + f_2 E a_{l_1 m_1} a_{l_2 m_2} a_{l_3 m_3}(2) + f_2^3 E a_{l_1 m_1}(2) a_{l_2 m_2}(2) a_{l_3 m_3}(2) \\ &= (-1)^{m_3} C_{l_1 m_1 l_2 m_2}^{l_3 - m_3} P_{l_1 l_2 l_3}, \end{aligned}$$

where

$$P_{l_1 l_2 l_3} = 6f_2 \sqrt{\frac{(2l_1 + 1)(2l_2 + 1)}{(2l_3 + 1)4\pi}} C_{l_1 0 l_2 0}^{l_3 0} \{C_{l_1} C_{l_2} + C_{l_1} C_{l_3} + C_{l_2} C_{l_3}\} \tag{6.62}$$

$$+ f_2^3 \sum_{\ell_1 \ell_2 \ell_3} C_{\ell_1 0 \ell_2 0}^{l_1 0} C_{\ell_1 0 \ell_3 0}^{l_1 0} C_{\ell_2 0 \ell_3 0}^{l_3 0} \frac{(2\ell_1 + 1)(2\ell_2 + 1)(2\ell_3 + 1)}{\sqrt{(4\pi)^3}} \frac{8(-1)^{l_3}}{\sqrt{2l_3 + 1}} \begin{Bmatrix} \ell_1 & \ell_2 & \ell_3 \\ l_3 & l_2 & l_1 \end{Bmatrix} \{C_{\ell_1} C_{\ell_2} C_{\ell_3}\}. \tag{6.63}$$

The lack of symmetry with respect to the  $l_3$  term is only apparent and can be easily dispensed with by permuting the multipoles in  $C_{l_1 m_1 l_2 m_2}^{l_3 m_3}$  or using expression (3.18). Formula (6.62) is consistent with the cosmological literature, where (6.63) is considered a higher order term and hence neglected (see again [16]).

### 6.2. The connection with higher order moments

We now provide a simple result, connecting the reduced polyspectrum with the higher order moments of the associated spherical random field.

**Proposition 14.** *The following identity holds for every isotropic field with finite moments of order  $p$  and with a reduced polyspectrum  $\{P_{l_1 \dots l_p}(\cdot) : l_1, \dots, l_p \geq 0\}$ : for every  $x \in S^2$ ,*

$$ET(x)^p \equiv \sum_{l_1 \dots l_p} \sqrt{\frac{(2l_1 + 1) \dots (2l_p + 1)}{(4\pi)^p}} \sum_{\lambda_1 \dots \lambda_{p-3}} P_{l_1 \dots l_p}(\lambda_1, \dots, \lambda_{p-3}) C_{l_1 0 \dots l_{p-2} 0}^{\lambda_1 \dots \lambda_{p-3} l_p 0}.$$

**Proof.** We use the trivial fact that

$$T(x) \stackrel{d}{=} T(0) = \sum_l a_{l0} Y_{l0}(0) = \sum_l a_{l0} \sqrt{\frac{2l + 1}{4\pi}},$$

where 0 is the North Pole and we used the fact that, for  $m \neq 0$ ,  $Y_{lm}(0) = 0$  and  $Y_{l0}(0) = \sqrt{\frac{2l+1}{4\pi}}$  (see e.g. [12, Chapter 5]). Hence,

$$ET^p = \sum_{l_1 \dots l_p} \sqrt{\frac{(2l_1 + 1) \dots (2l_p + 1)}{(4\pi)^p}} E \{ a_{l_1 0} \dots a_{l_p 0} \}$$

$$= \sum_{l_1 \dots l_p} \sqrt{\frac{(2l_1 + 1) \dots (2l_p + 1)}{(4\pi)^p}} \sum_{\lambda_1 \dots \lambda_{p-3}} P_{l_1 \dots l_p}(\lambda_1, \dots, \lambda_{p-3}) C_{l_1 0 \dots l_{p-2} 0}^{\lambda_1 \dots \lambda_{p-3} l_p 0} \quad \blacksquare$$

**Example.** Take  $T = H_q(T_G)$ , where  $H_q$  is the  $q$ th Hermite polynomial. Then  $ET^p = c_{pq} \{ET^2\}^{qp/2}$ , where  $c_{pq} \in \mathbb{N}$  denotes the number of Gaussian diagrams without flat edges with  $p$  rows and  $q$  columns (see [36]). Therefore, one has the identity

$$\sum_{l_1 \dots l_p} \sqrt{\frac{(2l_1 + 1) \dots (2l_p + 1)}{(4\pi)^p}} \sum_{\lambda_1 \dots \lambda_{p-3}} P_{l_1 \dots l_p}(\lambda_1, \dots, \lambda_{p-3}) C_{l_1 0 \dots l_{p-2} 0}^{\lambda_1 \dots \lambda_{p-3} l_p 0} = c_{pq} \left\{ \sum_l \frac{(2l + 1)}{4\pi} C_l \right\}^{pq/2}.$$

### 6.3. The $\chi_v^2$ polyspectrum

Previously in (6.63), we have implicitly derived the “ $\chi_1^2$  bispectrum”, that is, the bispectrum associated with a field of the type  $T = H_2(T_G)$ , where  $T_G$  is Gaussian, centered, isotropic and with unit variance. More precisely, with the notation (6.58)–(6.60), one deduces from (6.63) that

$$E a_{l_1 m_1}(2) a_{l_2 m_2}(2) a_{l_3 m_3}(2) = \sum_{\substack{\ell_1 \ell_2 \ell_3 \\ \ell_4 \ell_5 \ell_6}} C_{\ell_1 0 \ell_2 0}^{\ell_1 0} C_{\ell_1 \mu_1 \ell_2 \mu_2}^{\ell_1 m_1} C_{\ell_3 0 \ell_4 0}^{\ell_3 0} C_{\ell_3 \mu_3 \ell_4 \mu_4}^{\ell_3 m_2} C_{\ell_5 0 \ell_6 0}^{\ell_5 0} C_{\ell_5 \mu_5 \ell_6 \mu_6}^{\ell_5 m_3}$$

$$\times \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)(2\ell_3 + 1)(2\ell_4 + 1)(2\ell_5 + 1)(2\ell_6 + 1)}{(2\ell_1 + 1)4\pi(2\ell_2 + 1)4\pi(2\ell_3 + 1)4\pi}} E \{ a_{\ell_1 \mu_1} a_{\ell_2 \mu_2} a_{\ell_3 \mu_3} a_{\ell_4 \mu_4} a_{\ell_5 \mu_5} a_{\ell_6 \mu_6} \}$$

$$= 8(-1)^{l_3 - m_3} \sum_{\ell_1 \ell_2 \ell_3} C_{\ell_1 0 \ell_2 0}^{\ell_1 0} C_{\ell_1 0 \ell_3 0}^{\ell_2 0} C_{\ell_2 0 \ell_3 0}^{\ell_3 0} \frac{(2\ell_1 + 1)(2\ell_2 + 1)(2\ell_3 + 1)}{\sqrt{(4\pi)^3}} \frac{C_{\ell_1 m_1 \ell_2 m_2}^{\ell_3 - m_3}}{\sqrt{2\ell_3 + 1}} \begin{Bmatrix} \ell_1 & \ell_2 & \ell_3 \\ l_3 & l_2 & l_1 \end{Bmatrix} \{ C_{\ell_1} C_{\ell_2} C_{\ell_3} \}, \quad (6.64)$$

see [12, p. 260; p. 454]. We now wish to extend these results to polyspectra of order  $p = 4, 5, 6$  for random fields of the type  $T = H_2(T_G)$ , where (as above)  $T_G$  is Gaussian, centered, isotropic and with unit variance. As anticipated, here we focus on cumulants instead of moments. We have the following result.

**Proposition 15.** The cumulant  $\chi(a_{l_1 m_1}(2), \dots, a_{l_p m_p}(2))$  ( $p = 4, 5, 6$ ) associated with the harmonic coefficients of an isotropic random field of the type  $H_2(T_G)$  (where  $T_G$  is Gaussian and isotropic, with angular power spectrum  $\{C_l : l \geq 0\}$ ) given by

$$\chi(a_{l_1 m_1}(2), \dots, a_{l_p m_p}(2)) = (-1)^{l_p - m_p} \sum_{\lambda_1 \dots \lambda_{p-3}} C_{l_1 m_1 \dots l_{p-1} m_{p-1}}^{\lambda_1 \dots \lambda_{p-3} l_p - m_p} \times P_{l_1 \dots l_p}^{C;1}(\lambda_1, \dots, \lambda_{p-3}),$$

where the reduced cumulant polyspectrum  $\{P_{l_1 \dots l_p}^C(\cdot) : l_1, \dots, l_p \geq 0\}$  is given by

$$P_{l_1 l_2 l_3 l_4}^{C;1}(\lambda) = 48 \sqrt{\frac{(2\lambda + 1)}{(4\pi)^4 (2l_4 + 1)}} \sum_{\ell_1 \dots \ell_4} C_{\ell_1} \dots C_{\ell_4} C_{\ell_1 0 \ell_2 0}^{\ell_1 0} C_{\ell_2 0 \ell_3 0}^{\ell_3 0} C_{\ell_3 0 \ell_4 0}^{\ell_4 0} C_{\ell_4 0 \ell_1 0}^{\ell_1 0}$$

$$\times (2\ell_1 + 1) \dots (2\ell_4 + 1) (-1)^{l_1 + l_2 + l_3 + l_4} \begin{Bmatrix} l_1 & l_2 & \lambda \\ \ell_4 & \ell_2 & \ell_1 \end{Bmatrix} \begin{Bmatrix} \lambda & l_3 & l_4 \\ \ell_3 & \ell_4 & \ell_2 \end{Bmatrix} \quad \text{for } p = 4,$$

$$P_{l_1 \dots l_5}^{C;1}(\lambda_1, \lambda_2) = 384 \sqrt{\frac{(2\lambda_1 + 1)(2\lambda_2 + 1)}{(4\pi)^5 (2l_5 + 1)}} \sum_{\ell_1 \dots \ell_5} C_{\ell_1} \dots C_{\ell_5} C_{\ell_1 0 \ell_2 0}^{\ell_1 0} C_{\ell_2 0 \ell_3 0}^{\ell_2 0} C_{\ell_3 0 \ell_4 0}^{\ell_4 0} C_{\ell_4 0 \ell_5 0}^{\ell_5 0} C_{\ell_5 0 \ell_1 0}^{\ell_1 0}$$

$$\times (2\ell_1 + 1) \dots (2\ell_5 + 1) (-1)^{\ell_1 + \ell_5 + l_3} \begin{Bmatrix} l_1 & l_2 & \lambda_1 \\ \ell_3 & \ell_1 & \ell_2 \end{Bmatrix} \begin{Bmatrix} \lambda_1 & l_3 & \lambda_2 \\ \ell_5 & \ell_3 & \ell_1 \end{Bmatrix} \begin{Bmatrix} \lambda_2 & l_4 & l_5 \\ \ell_4 & \ell_5 & \ell_3 \end{Bmatrix} \quad \text{for } p = 5,$$

and

$$P_{l_1 \dots l_6}^{C;1}(\lambda_1, \lambda_2, \lambda_3) = 3840 \sqrt{\frac{(2\lambda_1 + 1)(2\lambda_2 + 1)(2\lambda_3 + 1)}{(4\pi)^6 (2l_5 + 1)}} \sum_{\ell_1 \dots \ell_5} C_{\ell_1} \dots C_{\ell_6} C_{\ell_1 0 \ell_2 0}^{\ell_1 0} C_{\ell_2 0 \ell_3 0}^{\ell_2 0} C_{\ell_3 0 \ell_4 0}^{\ell_3 0} C_{\ell_4 0 \ell_5 0}^{\ell_5 0} C_{\ell_5 0 \ell_6 0}^{\ell_6 0} C_{\ell_6 0 \ell_1 0}^{\ell_1 0}$$

$$\times (2\ell_1 + 1) \dots (2\ell_6 + 1) (-1)^{\lambda_1 + \ell_3 + \ell_6 + l_4} \begin{Bmatrix} l_1 & l_2 & \lambda_1 \\ \ell_3 & \ell_1 & \ell_2 \end{Bmatrix} \begin{Bmatrix} \lambda_1 & l_5 & \lambda_2 \\ \ell_5 & \ell_3 & \ell_1 \end{Bmatrix} \begin{Bmatrix} \lambda_2 & l_3 & l_4 \\ \ell_4 & \ell_5 & \ell_3 \end{Bmatrix}$$

for  $p = 6$ .

**Proof.** The result can be proved by means of the standard graphical techniques for convolutions of Clebsch–Gordan coefficients, as described in [12, Chapters 11 and 12]. Here, we only provide the complete proof for the case  $p = 6$ . Let  $\{a_{\ell m}\}$  be the random harmonic coefficients associated with the underlying Gaussian field  $T_G$ . By definition, the field  $H_2(T_G)$  admits the expansion

$$H_2(T_G) = \sum_{l \geq 0} \sum_{m=-l}^l a_{lm}(2) Y_{lm},$$

where

$$\begin{aligned} a_{lm}(2) &= \sum_{\ell_1 m_1 \ell_2 m_2} a_{\ell_1 m_1} a_{\ell_2 m_2} \int_{S^2} Y_{\ell_1 m_1}(x) Y_{\ell_2 m_2}(x) \overline{Y_{lm}(x)} dx \\ &= \sum_{\ell_1 m_1 \ell_2 m_2} a_{\ell_1 m_1} a_{\ell_2 m_2} \begin{pmatrix} \ell_1 & \ell_2 & l \\ m_1 & m_2 & -m \end{pmatrix} \times (-1)^m \begin{pmatrix} \ell_1 & \ell_2 & l \\ 0 & 0 & 0 \end{pmatrix} \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)(2l + 1)}{4\pi}} \\ &= \sum_{\ell_1 m_1 \ell_2 m_2} a_{\ell_1 m_1} a_{\ell_2 m_2} C_{\ell_1 m_1 \ell_2 m_2}^{lm} C_{\ell_1 0 \ell_2 0}^{lm} \sqrt{\frac{(2\ell_1 + 1)(2\ell_2 + 1)}{4\pi(2l + 1)}}. \end{aligned}$$

By using once again the multilinearity of cumulants, one obtains that

$$\begin{aligned} \text{Cum} \{a_{l_1 m_1}(2), \dots, a_{l_6 m_6}(2)\} &= \sum_{\ell_{11} m_{11} \ell_{12} m_{12}} \dots \sum_{\ell_{61} m_{61} \ell_{62} m_{62}} \text{Cum} \{a_{\ell_{11} m_{11}} a_{\ell_{12} m_{12}}, \dots, a_{\ell_{61} m_{61}} a_{\ell_{62} m_{62}}\} \\ &\times \prod_{j=1}^6 \left\{ C_{\ell_{j1} m_{j1} \ell_{j2} m_{j2}}^{l_j m_j} C_{\ell_{j1} 0 \ell_{j2} 0}^{l_j m_j} \sqrt{\frac{(2\ell_{j1} + 1)(2\ell_{j2} + 1)}{4\pi(2l_j + 1)}} \right\}. \end{aligned}$$

For a given  $\mathbf{lm} = (\ell_{11} m_{11}, \ell_{12} m_{12}; \dots; \ell_{61} m_{61}, \ell_{62} m_{62})$ , the quantity  $\text{Cum} \{a_{\ell_{11} m_{11}} a_{\ell_{12} m_{12}}, \dots, a_{\ell_{61} m_{61}} a_{\ell_{62} m_{62}}\}$  is computed as follows:

- Build the  $6 \times 2$  matrix

$$\Lambda(\mathbf{lm}) = \begin{bmatrix} \ell_{11} m_{11} & \ell_{12} m_{12} \\ \ell_{21} m_{21} & \ell_{22} m_{22} \\ \ell_{31} m_{31} & \ell_{32} m_{32} \\ \ell_{41} m_{41} & \ell_{42} m_{42} \\ \ell_{51} m_{51} & \ell_{52} m_{52} \\ \ell_{61} m_{61} & \ell_{62} m_{62} \end{bmatrix}.$$

- Define the class  $M(\Lambda(\mathbf{lm}))$  of connected, Gaussian non-flat diagrams over  $\Lambda$ , that is, every  $\gamma \in M(\Lambda(\mathbf{lm}))$  is a partition of the entries of  $\Lambda(\mathbf{lm})$ , into pairs belonging to different rows; moreover, such a partition has to be *connected*, in the sense that  $\gamma$  cannot be divided into two separate diagrams. For instance, an element of  $M(\Lambda(\mathbf{lm}))$  is

$$\gamma = \{\{\ell_{11} m_{11}, \ell_{21} m_{21}\} \{\ell_{22} m_{22}, \ell_{32} m_{32}\} \{\ell_{31} m_{31}, \ell_{41} m_{41}\} \{\ell_{42} m_{42}, \ell_{52} m_{52}\} \{\ell_{51} m_{51}, \ell_{61} m_{61}\} \{\ell_{62} m_{62}, \ell_{12} m_{12}\}\}$$

- For every  $\gamma \in M(\Lambda(\mathbf{lm}))$ , write

$$\delta(\gamma) = \prod_{\{\ell_{ab} m_{ab}, \ell_{cd} m_{cd}\} \in \gamma} \delta_{\ell_{cd}}^{\ell_{ab}} \delta_{m_{cd}}^{-m_{ab}} (-1)^{m_{ab}} C_{\ell_{ab}}$$

(where  $\delta_a^b$  is the usual Kronecker symbol).

- Use the standard diagram formula (see again [36]), to obtain that

$$\text{Cum} \{a_{\ell_{11} m_{11}} a_{\ell_{12} m_{12}}, \dots, a_{\ell_{61} m_{61}} a_{\ell_{62} m_{62}}\} = \sum_{\gamma \in M(\Lambda(\mathbf{lm}))} \delta(\gamma).$$

It follows that

$$\text{Cum} \{a_{l_1 m_1}(2), \dots, a_{l_6 m_6}(2)\} = \sum_{\mathbf{lm}} \sum_{\gamma \in M(\Lambda(\mathbf{lm}))} \delta(\gamma) \prod_{j=1}^6 \left\{ C_{\ell_{j1} m_{j1} \ell_{j2} m_{j2}}^{l_j m_j} C_{\ell_{j1} 0 \ell_{j2} 0}^{l_j m_j} \sqrt{\frac{(2\ell_{j1} + 1)(2\ell_{j2} + 1)}{4\pi(2l_j + 1)}} \right\},$$

where the first sum runs over all vectors of the type  $\mathbf{lm} = (\ell_{11}m_{11}, \ell_{12}m_{12}; \dots; \ell_{61}m_{61}, \ell_{62}m_{62})$ . The proof now follows directly from graphical techniques. In particular, the previous term can be associated with a hexagon, having in each vertex an outward line corresponding to a “free” (i.e. not summed up) index  $l_i m_i$ ,  $i = 1, \dots, 6$ . An expression for convolutions of Clebsch–Gordan coefficients corresponding to such a configuration can be found in [12, p. 461], Eq. 12.1.6.30. From this, standard combinatorial arguments and a convenient relabelling of the indexes, we obtain that

$$P_{l_1 \dots l_6}^{C;1}(\lambda_1, \lambda_2, \lambda_3) = 3840 \sqrt{\frac{\left\{ \prod_{j=1}^3 (2\lambda_j + 1) \right\}}{(4\pi)^6 (2l_p + 1)}} \times (-1)^{\lambda_1 + \ell_3 + \ell_6 + l_4} \\ \times \sum_{\ell_1 \dots \ell_6} (2\ell_1 + 1) \dots (2\ell_6 + 1) C_{\ell_1} \dots C_{\ell_6} C_{\ell_1 0 \ell_2 0}^{l_1 0} C_{\ell_2 0 \ell_3 0}^{l_2 0} C_{\ell_3 0 \ell_4 0}^{l_3 0} C_{\ell_4 0 \ell_5 0}^{l_4 0} C_{\ell_5 0 \ell_6 0}^{l_5 0} C_{\ell_6 0 \ell_1 0}^{l_6 0} \\ \times \begin{Bmatrix} l_1 & l_2 & \lambda_1 \\ \ell_3 & \ell_1 & \ell_2 \end{Bmatrix} \begin{Bmatrix} \lambda_1 & \lambda_2 & l_3 \\ \ell_4 & \ell_3 & \ell_1 \end{Bmatrix} \begin{Bmatrix} \lambda_2 & l_4 & \lambda_3 \\ \ell_6 & \ell_4 & \ell_1 \end{Bmatrix} \begin{Bmatrix} \lambda_3 & l_5 & l_6 \\ \ell_5 & \ell_6 & \ell_4 \end{Bmatrix}.$$

Note that  $3840 = 2^{p-1} (p - 1)! = 2^5 5!$  is the number of automorphisms between graphs belonging to  $M(\Delta(\mathbf{lm}))$ . ■

We recall that the Clebsch–Gordan coefficients  $\{C_{ab0}^{c0}\}$  are identically zero unless  $a + b + c$  is even; it is hence easy to see that the previous polyspectra are non-zero only if the sum  $\{l_1 + \dots + l_p\}$  is even as well.

From the previous Proposition, we can derive the corresponding expressions for the cumulant polyspectra for  $\chi_v^2$  random field.

**Definition B.** We say the random field  $T_{\chi_v^2}$  has a chi-square law with  $\nu \geq 1$  degrees of freedom if there exist  $\nu$  independent and identically distributed Gaussian random fields  $T_i$  such that

$$T_{\chi_v^2} \stackrel{law}{=} T_1^2 + \dots + T_\nu^2.$$

It is trivial to show that  $T_{\chi_v^2}$  is mean-square continuous and isotropic if  $T_i$  is. We have the following

**Proposition 16.** The cumulant polyspectra of  $T_{\chi_v^2}$  (for  $p \geq 2$ ) are given by

$$P_{l_1 \dots l_p}^{C;v}(\lambda_1, \dots, \lambda_{p-3}) = \nu P_{l_1 \dots l_p}^{C;1}(\lambda_1, \dots, \lambda_{p-3}).$$

**Proof.** Note that the cumulant polyspectra of order  $p \geq 2$  of  $T_{\chi_v^2}$  coincide with those of the centered field  $T_{\chi_v^2} - ET_{\chi_v^2}$  (due to the translation-invariance properties of cumulants). Then, the proof is an immediate consequence of Proposition 15 and the of the standard multilinearity properties of cumulants. ■

## 7. Further issues and applications

The purpose of this final Section is to introduce what we view as promising directions for further research, where the ideas of this paper may perhaps yield further insights. We shall delay to future work a more thorough investigation of the issues which are left open below.

### 7.1. Representations of the symmetric group

As a further link between representation theory and higher order angular power spectra, we mention the following. It is to be stressed that the decomposition of  $\Delta_{l_1 \dots l_n}$  that we achieved in the previous Proposition 11 is by no means unique. In particular, what we did was to choose a particular sequence of “couplings”, i.e. we partitioned tensor products of the Wigner’s matrices  $D^l$  in a specific order before decomposing them into direct sums. Alternative partitions yield different eigenvectors and, therefore, different expressions for the polyspectra/joint moments. Alternatively, we could maintain the same coupling scheme (for instance, “start always from the first pair on the left”, as we did earlier) but acting on  $(l_1, \dots, l_n)$  by the symmetric group  $S_n$ . However, not all coupling schemes can be achieved by simply permuting the elements of  $(l_1, l_2, \dots, l_n)$ . This is the well-known *problem of parentheses* in Mathematical Physics (see for instance [35]).

We suggest here that one can establish a link between alternate expressions for the angular polyspectra and representations of the symmetric group. More precisely, the alternate expressions that we find for the polyspectra  $P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3})$  of a strongly isotropic field (with  $n$ -moments) must be such that for every permutation  $\pi \in \mathfrak{S}_n$ ,

$$\sum_{\lambda_1} \dots \sum_{\lambda_{n-3}} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3}; l_n - m_n} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) = \sum_{\lambda'_1} \dots \sum_{\lambda'_{n-3}} C_{\pi(l_1) m_1 \dots \pi(l_{n-1}) m_{n-1}}^{\lambda'_1 \dots \lambda'_{n-3}; l_n - m_n} P_{\pi(l_1) \dots \pi(l_n)}(\lambda'_1, \dots, \lambda'_{n-3}).$$

Now let us multiply both sides by  $C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1'' \dots \lambda_{n-3}''; l_n m_n'}$ , where  $(\lambda_1'', \dots, \lambda_{n-3}'')$  is fixed, and sum over  $(m_1, \dots, m_n)$ . In view of the unitary properties of Clebsch–Gordan coefficients we obtain for the left-hand side

$$\begin{aligned} & \sum_{m_1 \dots m_n} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1'' \dots \lambda_{n-3}''; l_n m_n'} \left\{ \sum_{\lambda_1} \dots \sum_{\lambda_{n-3}} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3}; l_n m_n} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) \right\} \\ &= \sum_{\lambda_1} \dots \sum_{\lambda_{n-3}} \left\{ \sum_{m_1 \dots m_n} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1'' \dots \lambda_{n-3}''; l_n m_n'} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1 \dots \lambda_{n-3}; l_n m_n} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) \right\} \\ &= \sum_{\lambda_1} \dots \sum_{\lambda_{n-3}} \left\{ \delta_{\lambda_1}^{\lambda_1''} \dots \delta_{\lambda_{n-3}}^{\lambda_{n-3}''} P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_{n-3}) \right\} = P_{l_1 \dots l_n}(\lambda_1'', \dots, \lambda_{n-3}''); \end{aligned} \tag{7.65}$$

on the right-hand side we get

$$\begin{aligned} & \sum_{m_1 \dots m_n} C_{l_1 m_1 \dots l_{n-1} m_{n-1}}^{\lambda_1'' \dots \lambda_{n-3}''; l_n m_n'} \left\{ \sum_{\lambda_1'} \dots \sum_{\lambda_{n-3}'} C_{\pi(l_1) m_1 \dots \pi(l_{n-1}) m_{n-1}}^{\lambda_1' \dots \lambda_{n-3}'; l_n m_n} P_{\pi(l_1) \dots \pi(l_n)}(\lambda_1', \dots, \lambda_{n-3}') \right\} \\ &= \sum_{\lambda_1'} \dots \sum_{\lambda_{n-3}'} \sum_{m_1 \dots m_n} C_{\pi(l_1) m_1 \dots \pi(l_{n-1}) m_{n-1}}^{\lambda_1'' \dots \lambda_{n-3}''; l_n m_n'} C_{\pi(l_1) m_1 \dots \pi(l_{n-1}) m_{n-1}}^{\lambda_1' \dots \lambda_{n-3}'; l_n m_n} P_{\pi(l_1) \dots \pi(l_n)}(\lambda_1', \dots, \lambda_{n-3}'). \end{aligned} \tag{7.66}$$

Similarly as in the previous section, the sum of products of Clebsch–Gordan coefficients on the right hand side can be expressed in terms of higher order Wigner’s coefficients. Since this section is just informal, for brevity’s sake we do not give explicit expressions (see e.g. [12, Chapter 10]). The two expressions (7.65) and (7.66) imply that, for every fixed  $(l_1, \dots, l_n)$  and every permutation  $\pi$ , there exists a square matrix  $A((l_1, \dots, l_n); \pi)$  such that

$$P_{l_1 \dots l_n} = A\{(l_1, \dots, l_n); \pi\} P_{\pi(l_1) \dots \pi(l_n)},$$

where  $P_{l_1 \dots l_n}$  is the vector with entries  $P_{l_1 \dots l_n}(\lambda_1, \dots, \lambda_n)$ . We conjecture that in this way one can build a representation of the symmetric group  $\mathfrak{S}_n$  on the vector space generated by admissible polyspectra  $P_{l_1 \dots l_n}$ . If this is indeed the case, some important questions are left open: for instance, whether or not the representation is *faithful* (see [1]), and whether these ideas can lead to algorithms for the numerical simulation of representation matrices, along the lines of what we shall pursue in the next subsection.

**Remark.** Another interesting issue is whether the representation associated with the matrices  $A\{(l_1, \dots, l_n); \pi\}$  is *irreducible*. Generally speaking, it is well-known that the collection of the (equivalence classes of the) irreducible representations of  $\mathfrak{S}_n$  can be indexed by the family of *partitions* of the integer  $n$ . In particular, recall that: (i) A partition of  $n$  is a vector  $\lambda = (\lambda_1, \dots, \lambda_k)$  of weakly decreasing positive integers such that  $\sum_{j=1}^k \lambda_j = n$ . (ii) The partitions of  $n$  can be represented by so-called *Young diagrams*, a finite collection of boxes, or cells, arranged in left-justified rows, with the row sizes weakly decreasing (each row has the same or shorter length than its predecessor). (iii) A *Young tableau* is obtained by filling the diagram with letters from some alphabet (for instance the integers  $1, \dots, n$ ). (iv) A *Young symmetrizer* (also called a *Specht module*) of parameter  $\lambda$  is an element of the group algebra of the symmetric group, constructed in such a way that the image of the element corresponds to an irreducible representation of the symmetric group over the complex numbers. (v) Every irreducible representation of  $\mathfrak{S}_n$  is equivalent to a Young symmetrizer of parameter  $\lambda$ , for some partition  $\lambda$  of  $n$ . Young symmetrizers can also be related to the problem of parentheses we mentioned above, and from a broader point of view to representation theory for the general linear group  $GL(n)$ . It is then natural to ask whether the formalism of Young diagrams and tableaux could help to shed further lights on the results of this paper, and in particular to explore further the connection with representations of the symmetric group. We plan to investigate these connections further in future work; the reader is referred e.g. to [1], [37, pp. 61–62] and [38] for more discussion on these issues.

### 7.2. Random data compression

In this subsection we shall show how we can exploit the previous results to develop a probabilistic algorithm to compress information on Clebsch–Gordan coefficients. Note first that

$$\# \left\{ C_{l_1 m_1 l_2 m_2}^{l_3 m_3} : l_1, l_2, l_3 \leq L, \left| C_{l_1 m_1 l_2 m_2}^{l_3 m_3} \right| \neq 0 \right\} \approx O(L^6);$$

it is therefore clear how for most applications the storage of Clebsch–Gordan coefficients for future usage is simply unfeasible, whatever the supercomputing facilities (for instance, for CMB data analysis,  $L \approx 3 \times 10^3$  is currently required, so that the number of Clebsch–Gordan coefficients to be saved would exceed  $10^{20}$ ). Let us consider again a chi-square field as defined before, i.e.

$$T_{\chi^2}(x) = H_2(T_G(x)) = \sum_{lm} a_{lm}(2) Y_{lm}(x);$$

we have proved earlier in (6.64) that

$$Ea_{l_1 m_1}(2)a_{l_2 m_2}(2)a_{l_3 m_3}(2) = (-1)^{m_3} C_{l_1 m_1 l_2 m_2}^{l_3 m_3} h_{l_1 l_2 l_3}$$

where

$$h_{l_1 l_2 l_3} := 8 \sum_{\ell_1 \ell_2 \ell_3} C_{\ell_1 0 \ell_2 0}^{l_1 0} C_{\ell_1 0 \ell_3 0}^{l_2 0} C_{\ell_2 0 \ell_3 0}^{l_3 0} \frac{(2\ell_1 + 1)(2\ell_2 + 1)(2\ell_3 + 1)}{\sqrt{(4\pi)^3}} \frac{1}{\sqrt{2l_3 + 1}} \begin{Bmatrix} \ell_1 & \ell_2 & \ell_3 \\ l_1 & l_2 & l_3 \end{Bmatrix} \{C_{\ell_1} C_{\ell_2} C_{\ell_3}\},$$

which can be calculated analytically and stored, with storage dimension

$$\# \{h_{l_1 l_2 l_3} : l_1, l_2, l_3 \leq L, |C_{l_1 0 l_2 0}^{l_3 0}| \neq 0\} \approx O(L^3).$$

Let us assume we simulate  $B$  times  $T_{\chi^2}(x)$ , which is trivially done by simply squaring a Gaussian field: the latter is obtained by sampling independent complex Gaussian variables with variance  $C_l$ . We store the triangular arrays  $\{a_{lm}^i\}_{l=1, \dots, L; m=-l, \dots, l}$ ,  $i = 1, \dots, B$ ; here the dimension is of order  $B \times L^2$ . We can then recover any value  $C_{l_1 m_1 l_2 m_2}^{l_3 m_3}$  by means of the Monte Carlo estimate

$$\widehat{C}_{l_1 m_1 l_2 m_2}^{l_3 m_3} = h_{l_1 l_2 l_3}^{-1} \sum_{i=1}^B \frac{a_{l_1 m_1}^{(i)} a_{l_2 m_2}^{(i)} a_{l_3 m_3}^{(i)}}{B},$$

which requires  $B$  steps and  $B \times L^2 + L^3$  storage capacity, as opposed to  $L^6$  storage capacity by the direct method. We leave for further research a more thorough investigation on the convergence properties of this algorithm; we stress, however, that the procedure we advocate is completely general, i.e. it does not depend on peculiar features of the group  $SO(3)$  we are currently considering. We believe, hence, that similar ideas can be implemented for the numerical estimation of Clebsch–Gordan coefficients for other compact groups of interest for theoretical physicists. We leave this and the previous issues in this Section as topics for further research.

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