# A generalised finite mixture model 

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## Outline

(1) Nagin's Finite Mixture Model

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(2) Generalization of the basic model

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## (2) Generalization of the basic model

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## General description of Nagin's model

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This is still an inter-individual model, but unlike other classical models such as standard growth curve models, it allows the existence of subpolulations with completely different behaviors.

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Aim of the analysis: Find $r$ groups of trajectories of a given kind (for instance polynomials of degree 4, $P(t)=\beta_{0}+\beta_{1} t+\beta_{2} t^{2}+\beta_{3} t^{3}+\beta_{4} t^{4}$.

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\Rightarrow P\left(Y_{i}\right)=\sum_{j=1}^{r} \pi_{j} P^{j}\left(Y_{i}\right) \tag{1}
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- finite : sums across a finite number of groups
- mixture : population composed of a mixture of unobserved groups


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\begin{equation*}
y_{i_{t}}=\beta_{0}^{j}+\beta_{1}^{j} A g e_{i_{t}}+\beta_{2}^{j} A g e_{i_{t}}^{2}+\beta_{3}^{j} A g e_{i_{t}}^{3}+\beta_{4}^{j} A g e_{i_{t}}^{4}+\varepsilon_{i_{t}}, \tag{4}
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Software:
SAS-based Proc Traj procedure by Bobby L. Jones (Carnegie Mellon University).
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## Software:

Mplus package by L.K. Muthén and B.O Muthén.

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Fewer groups are required to specify a satisfactory model.

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(2) Group cross-over effects.
(0) Can create the illusion of non-existing groups.

## Model Selection

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## Rule:

The bigger the BIC, the better the model!

## Posterior Group-Membership Probabilities

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Bigger groups have on average larger probability estimates.
To be classified into a small group, an individual really needs to be strongly consistent with it.

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## Predictors of trajectory group membership

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Multinomial logit model:

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\pi_{j}\left(x_{i}\right)=\frac{e^{x_{i} \theta_{j}}}{\sum_{k=1}^{r} e^{x_{i} \theta_{k}}} \tag{11}
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L=\frac{1}{\sigma} \prod_{i=1}^{N} \sum_{j=1}^{r} \frac{e^{x_{i} \theta_{j}}}{\sum_{k=1}^{r} e^{x_{i} \theta_{k}}} \prod_{t=1}^{T} \phi\left(\frac{y_{i_{t}}-\beta^{j} t_{i_{t}}}{\sigma}\right) \tag{12}
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Confidence intervals for the probabilities of group membership can be computed by a parametric bootstrap technique.

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y_{i_{t}}=\beta_{0}^{j}+\beta_{1}^{j} t+\beta_{2}^{j} t^{2}+\beta_{3}^{j} t^{3}+\beta_{4}^{j} t^{4}+\alpha_{1}^{j} z_{1 t}+\ldots+\alpha_{L}^{j} z_{L t}+\varepsilon_{i_{t}} \tag{13}
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where $\varepsilon_{i_{t}} \sim \mathcal{N}(0, \sigma), \sigma$ being a constant standard deviation and $z_{l t}$ are covariates that may depend or not upon time $t$.

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where $\varepsilon_{i_{t}} \sim \mathcal{N}(0, \sigma), \sigma$ being a constant standard deviation and $z_{l t}$ are covariates that may depend or not upon time $t$.

Unfortunately the estimation of parameters $\alpha_{l}^{j}$ is not implemented in proc traj procedure; it is just possible to plot the impact of the covariates.

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Salaries of workers in the private sector in Luxembourg from 1940 to 2006.

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Some sociological variables:

- gender (male, female)


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About 7 million salary lines corresponding to 718.054 workers.
Some sociological variables:

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- year of birth of children


## Result for 9 groups (dataset 1 )

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## Adding covariates to the trajectories (dataset 2)

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-PRED1M
-PRED1F

- PRED $2 M$
- PRED 2F
- PRED 3M

