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The problem of protein structure prediction is formulated here as that of evaluating how well an amino acid sequence fits a hypothetical structure. The simplest and most complicated approaches, secondary structure prediction and all-atom free energy calculations, can be viewed as sequence-structure fitness problems. Here, an approach of intermediate complexity is described, which involves; (1) description of a protein structure in terms of contact interface vectors, with both intra-protein and protein-solvent contacts counted, (2) derivation of sequence preferences for 2 up to 29 contact interface types, (3) generation of numerous hypothetical model structures by placing the input sequence into a large set of known three-dimensional structures in all possible alignments, (4) evaluation of these models by summing the sequence preferences over all structural positions and (5) choice of predicted three-dimensional structure as that with the best sequence-structure fitness. Evolutionary information is incorporated by using position-dependent core weights derived from multiple sequence alignments. A number of tests of the method are performed: (1) evaluation of cyclic shifts of a sequence in its native structure; (2) alignment of a sequence in its native structure, allowing gaps; (3) alignment search with a sequence or sequence fragment in a database of structures; and (4) alignment search with a structure in a database of sequences. The main results are: (1) a native sequence can very well find its native structure among a large number of alternatives, in correct alignment; (2) substructures, such as \((\beta_2\alpha)_{\text{a}}\) units, can be detected in spite of very low sequence similarity; (3) remote homologues can be detected, with some dependence on the set of parameters used; (4) contact interface parameters are clearly superior to classical secondary structure parameters; (5) a simple interface description in terms of just two states, protein-protein and protein-water contacts, performs surprisingly well; (6) the use of core weights considerably improves accuracy in detection of remote homologues; (7) based on a sequence database search with a myoglobin contact profile, the C-terminal domain of a viral origin of replication binding protein is predicted to have an all-helical fold. The sequence-structure fitness concept is sufficiently general to accommodate a large variety of protein structure prediction methods, including new models of intermediate complexity currently being developed.

Keywords: protein structure prediction; sequence-structure alignment; computer algorithm; database; evolutionary information.

1. Introduction

(a) A unified view of protein structure prediction: evaluation of sequence-structure fitness

The prediction of the three-dimensional structure of a protein from its one-dimensional amino acid sequence is an unsolved problem, in spite of much effort, using a variety of approaches. The problem can be cast in the following form: given a protein sequence, generate and evaluate all possible three-dimensional structures and then choose the structure (or structures) that best fits the sequence. We call this the sequence-structure fitness approach to protein structure prediction.

(b) The problem: generation and evaluation of hypothetical structures

In generating hypothetical structures, one must explore all reasonable alternatives, e.g. by
constructing explicit three-dimensional models or enumerating secondary structure states. In evaluating a hypothetical structure, i.e. the fitness of the structure for the sequence or the fitness of the sequence for the structure, one must be able to distinguish between correct and incorrect structures, i.e. identify those structural states that have a high probability of being observed (in given environmental conditions). Success or failure depends crucially on the underlying description of structural states and on the evaluation scheme of sequence-structure fitness.

(c) Most complicated: three-dimensional structures and free energy estimates

At one extreme, in the most complicated description, one can generate all-atom co-ordinates for every conceivable structure and evaluate its fitness by calculation of the free energy of unfolding. This fully three-dimensional approach is impractical. It takes too much computer time, so only a small fraction of the available conformational space can be explored this way. Furthermore, even for a single structure, current estimates of free energy differences between significantly different conformational states are not sufficiently accurate (Novotny et al., 1984, 1988).

(d) Simplest: one-dimensional secondary structure strings and preferences

At the other extreme, one of the simplest descriptions of protein structure is in terms of secondary structure, e.g. helix, β-strand and loop. All possible structures for a given sequence can be simply enumerated as combinations of secondary structure states for single residues and the fitness of structure for sequence can be evaluated by statistical preference parameters of single residues in secondary structure states (Garnier et al., 1978). This inherently one-dimensional approach can be executed rapidly, but fails to solve the prediction problem. The description in terms of secondary structure alone is much too simple and ignores important physical effects. Furthermore, even with a 100% successful prediction of secondary structure one would still lack the three-dimensional view that is essential for a full understanding of function.

(e) Intermediate: description of protein structure in terms of residue-residue contacts

For these reasons we believe that an intermediate description of protein structure is a key requirement for further progress with structure prediction, a description between all-atom three-dimensional models and one-dimensional strings of secondary structure symbols. To be of practical value, the description should not be so complicated as to be intractable and not so simple as to neglect important effects. Accordingly, we have developed a description of protein structure in terms of contacts between atoms, including contacts with solvent atoms. In this, we follow an idea developed in the context of analyzing contacts in parallel and antiparallel β-sheets: "As more protein structures become available, further distinctions of secondary structure elements according to the type of tertiary contacts should be made. For example, one can distinguish between different hydrogen bonding positions in β-sheets, solvent-exposed and interior faces of sheets and helices, segments in tertiary contacts with sheets compared to those in contact with helices. Such distinctions are likely to lead to more clear-cut statistical preferences, and also serve as a starting point for predicting tertiary structure" (Lifson & Sander, 1979). The first results from our approach are reported in a diploma thesis (Scharf, 1988).

The contact description of protein structure is a two-dimensional reduction of the full complexity of three-dimensional structure, with the aim of capturing the physically relevant effects. The basic element in this description is the enumeration of atomic contacts made by a residue. Contacts are best represented by a "contact map" (Fig. 1a,b), similar to a "distance plot" used in distance geometry calculations and in protein structure determination by nuclear magnetic resonance spectroscopy. The description is of size N(N+1), where N is the number of residues in the proteins and the slot number (N+1) is allocated to residue-solvent contacts.

(f) Generation of hypothetical structures: use of the Protein Data Bank

With a contact description of protein structure, how do we, in a sequence-structure fitness approach, solve the two problems of generating all reasonable structures and evaluating each of them? The universe of all possible protein structures, even in the contact description, is very large. One very powerful and practical way of circumventing this enormous complexity is by working within the much smaller universe of all known protein structure types, as deposited, for the most part, in the Protein Data Bank (Bernstein et al., 1977). For a given sequence, a set of alternative structures is then generated by implicitly trying out all possible alignments of the sequence in each of the known structures, with gaps permitted.

(g) Evaluation in two-dimensions: residue-residue contacts

If one represents the known protein structure "templates" by two-dimensional contact maps, the evaluation of alternate sequence alignments in each structure becomes a two-dimensional alignment problem. Algorithmically, the problem of finding the alignment with the highest score, assuming additivity of fitness values, can be solved in a number of ways, e.g. by a two-level dynamic
Figure 1. Scheme of the basic procedure of structure-sequence alignment. a. From 3-dimensional structure to a 2-dimensional residue-residue contact map. Starting from the 3-dimensional structure, the strength of residue-residue and residue-solvent contacts in the known 3-dimensional structure (Contacts) is calculated. Contact strength is indicated by grey levels; contacts with the solvent are in right-most column (W). b. From contact map to contact interface profile. For each residue, i.e. for each row in the contact map, contacts are summed over all contacting residues in each interface type (5 types in this Fig.). The resulting set of 5 interface strengths is called the contact interface vector and describes the structural environment of a residue. The array of interface vectors, 1 for each residue, is a simplified representation of protein structure, called the interface contact profile (Interfaces). This description is 1-dimensional in the sense that each interface vector describes the local structural environment, independently of the type of the contacting residues. Preferences for a residue type in each of the interface states (Preferences) are derived from the interface profiles of all known structures in the database, removing from the database the protein to be aligned. c. From contact interface profile to fitness profile. In preparation of alignment, the fitness of each of the 20 amino acids at each structural position is evaluated by simply summing over the preference of that residue type for each interface, weighted with the strength of the interface at the structural position. The resulting table (Fitness profile) represents the fitness of each of the 20 amino acid residue types for this structural position. Mathematically, the fitness profile $f(R,j)$ is simply the matrix product of the interface profile $c(j,I)$ with the preference table $p(R,I)$. Such fitness profiles can also be derived from other types of structural preferences, e.g. those for secondary structure, as well as from multiple sequence alignments (Gribkov et al., 1987, 1990). d. From fitness profile to structure-sequence alignment. The fitness profile is just the right form of input to an alignment problem, here that of aligning some amino acid sequence to the given structure. The local similarity value for the alignment problem, at a given sequence position, is simply the appropriate column copied from the fitness table, representing the fitness of that residue type for each position in the structure. A dynamic programming algorithm then finds the optimal trace, such that the sum of fitness values along the trace is optimal. The result is an alignment of the sequence with the given structure. The alignment is the basis of an explicit 3-dimensional model, and the total fitness value quantifies how well the sequence fits into this structure.

programming approach (Taylor & Orengo, 1989). Statistical preference parameters that can be used in this type of alignment problem are residue-residue contact preferences, pseudo-energies, or potentials of mean force; typically a set of one or more tables of dimension 20 by 20 (Crippen, 1977; Tanaka & Scheraga, 1975; Warme & Morgan 1978; Lifson & Sander, 1980; Galaktionov & Rodionov, 1981; Miyazawa & Jernigan, 1985; Scharf, 1989; Sippl, 1990; Sander & Vriend, 1991; Sander et al., 1992), representing average interactions between the 20 different amino acid types. Only one of these (Sippl, 1990) has been used in full two-dimensional sequence-structure alignment (Jones et al., 1992), as far as we know. Here, we use an approximate one-dimensional reduction of the problem (Fig. 1).
Figure 2. Description of 3-dimensional protein structure by a 1-dimensional array of contact interface vectors. (a) Cartoon of a residue contact environment. In this example, a valine residue (Y-shaped side-chain) in a helix makes contacts (arrows) with residues (circles) adjacent in the same helix (interface HHp), on the same helix I turn away (interface HHi), on a beta-strand (interface HEE) and with solvent (interface HW). Not all contacts are shown, for clarity of the Figure, nor are side-chains. The extent to which a residue participates in various interfaces is calculated in terms of interatomic contacts. Only contacts with nearest neighbours are counted and summed for all atoms in the residue. A given atom makes contacts either with other protein atoms or with solvent atoms (substrate or co-factor atoms are treated here as solvent, for simplicity). When solvent contacts are expressed in the appropriate units (Colonna-Cesari & Sander, 1990), the total number of contacts an atom makes is approximately constant and proportional to the volume of a spherical shell. This allows an estimate of water contacts from the calculation of protein-protein contacts alone. The total number of contacts of a residue can then be partitioned according to the type and state of the contacting atoms. The result is a normalized contact interface vector for each residue (bottom). (b) Contacts are
(h) **Evaluation in one dimension:** residue-interface contacts

The two-dimensional contact view can be simplified by describing the contacts made by a single residue with its environment, i.e. by averaging over the amino acid type of the second contact partner. For example, a two-dimensional contact map enumerated in terms of pair contacts, e.g. Ala-Val, Ala-Ile, Ala-Thr, Ala-Water, etc. would be collapsed, e.g. to Ala-Protein, Ala-Water (with relative strengths summed up). In this way, a structure can be represented as a string of structural contact vectors attached to residue positions (Fig. 1; Fig. 2(d)). The description is of size \( NK \), where \( K \) is the number of distinct contact interface types \((K-1)\) intra-protein interfaces and one protein-water interface.

The representation of protein structures as one-dimensional strings of contact descriptors has the practical advantage that sequence-structure alignment can now be performed by "standard" dynamic programming algorithms developed for string comparisons (Levenshtein 1966; Smith & Waterman, 1981). The corresponding fitness parameters express the preference (information value, potential of mean force) of single residues for a particular type of contact interface.

Here, we describe and parametrize the sequence-structure fitness approach in the one-dimensional approximation. The full two-dimensional view in terms of explicit residue-residue contacts will be dealt with in a subsequent manuscript. Our initial approach (Scharf, 1989) is conceptually similar to methods developed independently by other groups (Bashford et al., 1987; Bowie et al., 1990, 1991; Hendlich et al., 1990; Sali et al., 1990; Sali & Blundell, 1990; Sippl & Weitzkus, 1992; Jones et al., 1992; Godzik & Skolnick, 1992; Godzik et al., 1992; Luethy et al., 1992; Goldstein et al., 1992b).

2. **Methods**

Central to our approach is the method of optimally aligning a single protein sequence ("input sequence"): a string of amino acid types, and a single protein structure ("template structure": a string of contact descriptors). When the single sequence is aligned against a representative database of protein folds, the highest score corresponds to a predicted 3-dimensional structure for the input sequence (Fig. 1).

(a) **Residue-interface contact vector**

Starting from the co-ordinates of the template structure, intramolecular contacts and solvent contacts are calculated for each residue, as a sum over the contacts made by its constituent atoms (Fig. 2(a) and (b)). Solvent contacts are always included in the description. The nature of the contacting partners is noted, e.g. the secondary structure of the residues, the polar/non-polar or protein/solvent nature of the contacting atoms. The residue contact vector \( c(j) \) describes the contact environment of a particular residue.

We define the contact strength between 2 atoms such that 2 atoms are counted as being in contact if they are so close that a water molecule cannot fit between them: the linear-square box potential function \( V(r) \) (Fig. 2(b)) is equal to 10 until the interatomic distance \( r \) equals the sum of the van der Waals radii (here 3.6 \( \AA \)) and decreases linearly until it reaches 0.0, when a water molecule just fits between the 2 atoms, i.e. at \( r = 3.6 + 2.8 \) \( \AA \).

The contact strength \( c(j,i) \) of a residue of type \( R \) at position \( j \) in the structure is the sum over all interatomic contacts the residue makes in interface \( I \). In this paper, only contacts made by the side-chain or \( C^\alpha \) of residue \( j \) with side-chain or backbone of other residues are counted, i.e. contacts made by backbone N-H or C-O of residue \( j \).

...calculated using a simple atom-atom potential \( V(r) \) that is fairly insensitive to errors in atomic co-ordinates: a linear-square box. A single contact event is counted with a strength of 1.0 when 2 atoms are "touching" (interatomic distance \( r \) less or equal to the sum of the van der Waals radii). With increasing interatomic distance the strength decreases linearly and reaches 0.0 when a water molecule (W) just fits between 2 atoms. No contacts are counted when the interatomic distance is larger than the sum of the van der Waals radii plus the diameter of a water molecule. The contact strength of a residue is the sum of the contact strengths over all its atoms. Here, to emphasize specificity, a contact of a residue with its environment excludes contacts made by its backbone (i.e. only contacts of side-chain plus \( C^\alpha \) with all other atoms are counted). c. Definition of 29 different contact interface types. A residue on a helix (H), \( \beta \)-strand (D), turn (T) or loop (X) (rows) can be in contact with other residues on a helix, \( \beta \)-strand, turn or loop or with water (columns). In the simplest description, with 2 interface types (used for parameter set AM2.4ce), the contacts in the rightmost column are grouped together as protein-water contacts (PW), the rest as protein-protein contacts (PP). Notation: interface type is \( S_1,S_2,P_{12} \) (HHH, HHI, HHE, HEE, etc.), where \( S_1 = H,E,T,O \) or X is the secondary structure of a residue; \( S_2 = H,E,T,O \) or X is the secondary structure of the contacting residue(s) or \( S_2 = W \) for contacts with water; and \( P_{12} = a,i,s,e \) is the chain distance (proximity) of any 2 contacting residues, defined as: a (adjacent): the 2 residues are adjacent in sequence), i (internal); the 2 residues are on the same element of secondary structure, i.e. on the same helix or strand), s (strand-strand: the 2 residues are on adjacent strands in the same beta sheet), e (external: the 2 residues are on 2 different elements of secondary structure; for strands, in different sheets). d. Description of the 3-dimensional structure of c-mabin (PDB (Protein Data Bank) data set 1cnn, Hendrickson & Teeter, 1981) in terms of contact interface vectors \( c(j) \). For each residue we have, left to right, the amino acid residue (1-letter code), the secondary structure state, according to the DSSP summary column, except that H.G.I→H and S.B,blank→X (Kabsch & Sander, 1983), and the contact strength in each of the 5 interface types (A555, H.E.T.X,W, on a scale of 0.0 (white square) to 1000 (black square), with grey squares for intermediate values (see bottom legend). For aligning a given sequence with this structural template, one needs contact interface preference parameters for residue types in these states. Their derivation is explained in Methods and numerical values are given in Fig. 4.
are not counted. In general, a residue participates in $K$ different interfaces (Fig. 2(a) and (c)). For the purposes of this paper, the vectors $c(j)$ with the components $c(j,l)$, $l = 1...K$ are normalized to unit length for each residue $j$. This is done to prevent sequence "read-through", i.e., to eliminate information about residue size. In the current implementation, the structure at position $j$ is represented by the contact vector derived from a single native structure. In future implementations, $c(j)$ can be an average over all equivalent positions in structurally similar proteins.

The simplest contact interface classification is in terms of 2 types, i.e., contacts made with other protein parts ("inside") or $I = PP$ for protein-protein) and contacts made with solvent ("outside") or $I = PW$ for protein-water). Note that the water contact strength $c(j, PW)$ of a residue can have any value between 0 and 1, and a distinctive advantage relative to methods that have to classify a residue as either being exposed or "buried" in binary fashion. If the secondary structure of the contacting partner is noted, one has 5 contact types, i.e., contact with a helix ($I = PH$ for protein-helix), with a strand ($I = PE$), with a turn ($I = PT$), with a loop ($I = PX$) or with water ($I = PW$). The most complicated classification (in this paper) is in terms of the secondary structure of both contacting partners and of chain proximity, for a total of 29 contact interface types (Fig. 2(c)).

The string $c(j)$, $j = 1...N$ of contact vectors (Fig. 2(d)), also called the contact profile, is an approximate description of the 3-dimensional structure of the desired intermediate complexity. The profile has length $N$, where $N$ is the number of residues in the protein structure, and width $K$, where $K$ is the number of different types of contact interfaces. An example of a 5-state contact profile for the small protein crambin is in Fig. 2(c). With this description of protein structures we now derive preference parameters for residue participation in different interface types.

(b) Residue-interface contact preferences

To quantify how well particular residues are adapted to particular interfaces, we choose a statistical approach. Preference parameters are defined as the logarithm of the ratio of observed over expected contact counts. These are derived from a database of 64 mutually non-homologous proteins (Fig. 3).

Scanning over the database, total contact counts $C(R, I)$ for each residue type $R$ in each interface type $I$ are calculated by summing single residue contacts $c(R, I)$ over all residues $j$ of type $R$ in all protein chains:

$$C(R, I) = \sum_j c(j, I), \text{ residue at } j \text{ is of type } R. \quad (1)$$

For example, $C(\text{Ala}, \text{HHe}) = 11210$ is the total contact strength of all alanine residues in helix-sheet interfaces.

From the raw contact counts $C(R, I)$, preferences are derived as:

$$p(R, I) = ld \left( \frac{C(R, I)}{C(R) C(I)} \right), \quad (2)$$

where $C(R)$, $C(I)$ and $C$ are the partial sums:

$$C(R) = \sum_I C(R, I), \quad C(I) = \sum_R C(R, I), \quad C = \sum_{R, I} C(R, I), \quad (3)$$

and $ld$ is the logarithm base 2. The set of preferences $p(R, I)$, $I = 1...K$ can also be interpreted as a vector, written $p(R)$.

These formulas are identical to those used in, e.g., secondary structure prediction, except that the counts $C$ used here are contact strengths (sums over atomic contacts) rather than residue occurrences. The preferences can be interpreted as the logarithm of the ratio of observed counts, $C(R, I)$, over expected counts, $E(R, I) = C(R) C(I) / C$, or as the information in units of bits that a residue of type $R$ has about the structural state $I$ (e.g., $R = \text{Ala}$, $I = \text{HHe}$). Low counts can introduce serious fluctuations. This problem is dealt with here by scaling the preference values $p(R, I)$ with a damping factor, min$\{10, E(R, I) / 100\}$. The factor is 10 if $E(R, I)$ is 100 or more and linearly decreases for lower expected counts until it reaches 0 if $E(R, I) = 0$. Thus, states with very low expected counts have "neutral" preference values near 0. This is an important technical detail. Other forms of damping noise from low counts have been used (Sippl, 1990). The set of preferences $p(R, I)$, $I = 1...K$ of 1 residue type for the various contact interface types is called here the preference vector for that residue type (Figs 1 and 4). Numerical values are tabulated in Sander & Vriend (1991) and Sander et al. (1992).

(c) Evaluation of sequence-structure fitness

Given a position $j$ in the template structure and a residue of a certain type $R$ in the input sequence, one can now quantify how well the residue is adapted to this position, i.e., one can calculate the sequence-structure fitness at this position. We simply need to accumulate the preferences of residue type $R$ for the various interface types, weighted with the extent to which interface $I$ is present in the contact environment at position $j$. Mathematically, this weighted sum is equivalent to the scalar (inner) product of the contact interface vector $c(j, I)$ and the contact preference vector $p(R, I)$. For each protein structure template we precalculate and store the fitness of all 20 amino acid types at each structural position $j$ as sequence-structure fitness profiles:

$$f(R, j) = \sum_I p(R, I) c(j, I), \quad (4)$$

where $R$ covers all 20 amino acid types, $I$ all interface types (Fig. 5(a)). The underlying assumption is that of statistical independence of the individual residue terms. An example of a fitness profile for crambin is given in Fig. 5(b). It has 20 real numbers, one for each residue type ($R = \text{VL, ND}$), at each sequence position. The profiles $f(R, j)$ are analogous to profiles used in sequence database searches (Grishkov et al., 1987, 1990), and can be used as input to profile alignment software, e.g., MaxHom (Sander & Schneider, 1991; and unpublished). However, here they are derived from quantification of residue contacts in the 3-dimensional structure, rather than from the amino acid sequence. The profiles can be used to evaluate different arrangements of an input sequence in a template structure.

(d) Sequence-structure alignment algorithm

A dynamic programming algorithm provides an efficient way of determining the best arrangement of a particular sequence in a particular structure. We use a straightforward adaptation of the alignment algorithm for pairs of sequences described by Smith & Waterman (1981). Sequence similarity between residues at position $i$ in one protein and $j$ in the other protein is simply replaced by the local sequence-structure fitness $f(R, j)$, where $R$ is the residue type at $i$. The global similarity, or fitness, is
Figure 3. Representative subset of proteins of known 3-dimensional structure used as the database for the derivation of contact preference parameters. A total of 67 chains in 64 proteins with 12,460 amino acid residues were selected from the Protein Data Bank (PDB) (Bernstein et al., 1977). No 2 protein chains in the selection are homologous to each other, using as a criterion the threshold for structural homology (Sander & Schneider, 1991). For protein chains longer than 50 residues, this translates to a sequence identity of maximally 24% for any 2 proteins in the list. The threshold is higher for shorter chains, e.g. 52% for length 50. The shortest chain has 47 residues, the longest 414. Steps in the selection of the non-homologous proteins were as follows (Hobohm et al., 1991): (1) Of the more than 400 data sets of experimental protein structures in PDB, 111 mutually non-homologous chains were selected by performing all pair comparisons using a dynamic programming alignment algorithm, and then selecting unique data sets one by one, going down a list sorted according to resolution and not using chains homologous to a previously selected one. A subsequent exclusion filter imposed the following requirements: crystallographic resolution as listed in PDB 2.6 Å or better (REZ); chain length 40 or more residues (SIZ); number of Cys residues involved in disulfide bonds less than 8% of the chain length (CSS); well-formed secondary structure, i.e. 35 or more hydrogen bonds involved in helix (%H) or β-strand (%B) secondary structure per 100 residues (SEC) (sum of hydrogen bonds in parallel (%BP) and antiparallel (%BA) bridges, and in (i,i+4) and (i,i+3) type H-bonds (%H)), as defined in Kabsch & Sander, 1983); number of heteroatoms (non-protein atoms) less than 8% of protein atoms (HET); not membrane protein (MEM). Protein chains are identified by the PDB 4 letter code (PDB), the chain identifier (C), the name of the corresponding Swiss-Prot (Bairoch & Bucher, 1991) protein sequence entry (SID) (identified by: Swiss-Prot line DB, or, sequence identity between Swiss-Prot and PDB entry more than 96% and total sequence length within 3 residues), the species (ORIGIN) and the protein name.

The dynamic programming algorithm requires additivity and independence. Both are fulfilled: the fitness values are additive because the fitness values are logarithms of probabilities, assumed to be independent of another, which are multiplied along the alignment trace; and, the best path ending at positions i and j is independent of subsequent choices, as the contact profile is a 1-dimensional string of contact interface vectors derived calculated by summing over all pairs (i,j) in the alignment.

The dynamic programming algorithm requires additivity and independence. Both are fulfilled: the fitness values are additive because the fitness values are logarithms of probabilities, assumed to be independent of another, which are multiplied along the alignment trace; and, the best path ending at positions i and j is independent of subsequent choices, as the contact profile is a 1-dimensional string of contact interface vectors derived solely from the template structure, with no dependence on the amino acid type of the 2nd contact partner that results from fitting the input sequence into the template structure.

(c) Alignment parameters

In the dynamic programming algorithm, 3 parameters have to be set at the appropriate values in order to obtain realistic alignments. The 1st parameter determines the
interfaces, line He those for helix-sheet interfaces. The 20 standard amino acids are given in 1-letter code. Secondary structure notation is: H (helix), E (extended or beta sheet), T (hydrogen bonded turn), X (everything else, called loop). Contacts with water are labelled W. Chain distance (proximity) of 2 contacting residues is: a = adjacent, i = internal to strand or helix, s = strand-strand, e = different segments, d = different sheets. Numerical values for the parameter sets are given by Sander & Vriend (1991) and Sander et al. (1992).

(a) Alnt29: Preferences of amino acid side-chains for contacts in 29 contact interface types, as defined in Fig. 2(c). For example, Pro has a strong preference for TTP (Pro located in a turn makes contacts with other residue(s) in the same turn); Lys has clear preference for HW, EW, TW, and XW (Lys located on any element of secondary structure make contacts with water); the strongest preferences for EHe are expressed by Ile and Phe (Ile or Phe in a beta-strand make helix-strand contacts).

(b) AS5: Preferences of amino acid side-chains for contacts in 5 contact interface types: e.g. contact with a helix, contact with a sheet, or contact with water. The counts in these simpler “anything-structure” interface types are derived from those in the 29 interface types (Fig. 2(c)) used in (a), by summing over the secondary structure state $S_1$ of the central residue. So the 5 “contact-with” interface types are: H = residue contact of the 1st residue (in any secondary structure state) with a helix residue, E = contact with a beta-sheets residue, T = contact with a turn residue, X = contact with a loop residue, W = contact with solvent. Examples of the resulting preferences (see the text for definition): Val and Ile have a clear preference to be in contact with beta-sheet residues; Ala, for making contacts with helix residues; Lys, for making contact with water; and so on. It appears that these preferences are dominated by the secondary structure state of the central residue, simply because residues in a helix are likely to make contacts with other helix residues. The AS5 parameters are primarily used for comparison with other sets, not for production runs.

(c) AM2: Preferences of amino acid side-chains for contacts in 2 contact interface types, i.e. contact with protein atoms (Prot) or contact with water molecules (Wat). These very simple protein-water interface types are derived from the Alnt29 (Fig. 2(c)) parameters used in (a), by summing protein-protein contacts over the secondary structure states of both participating residues or from the AS5 parameters used in (b), by summing over the secondary structure state $S_2$ of the 2nd residue. The only remaining distinction is that between contacts of a protein atom with other protein atoms or with solvent atoms. These parameters resemble a hydrophobicity scale, e.g. Lys has the strongest preference for water contacts while Ile, Phe, Trp and Cys have the strongest preference for contacts with protein atoms. The apparently weaker contrast in line Protein is a numerical effect, due to the fact that, in the database used, the total number of contacts with protein atoms exceeds by far that with water atoms.

(d) S4: Preferences of amino acid side-chains for residue occurrence in 4 secondary structure states, given for comparison. These are the classical occurrence residue preferences used in secondary structure prediction methods (Chou & Fasman, 1978; Garnier et al., 1978; Maxfield & Scheraga, 1979). There is significant correlation of these parameters with those in (b). The AS5 parameters in (b), however, include water contacts in a natural and consistent fashion, e. AM2 preference parameters, numerical values. The parameters are calculated as logarithms of ratios of probabilities and are thus additive along a-chain (see Methods).

Figure 4. Contact preference parameters extracted from the non-redundant dataset of 67 protein chains. The parameters can be used to evaluate how well a particular sequence fits into a particular 3-dimensional structure, e.g. in sequence-structure alignment. For example, line HHe contains the single residue preference for helix-helix
distribution of similarity values relative to zero and, as a result, the average length of alignments. Here, to establish a link with experience accumulated in the practice of sequence alignments, we scale the local similarity values \( f(R,j) \) to new values \( s(i,j) \) using a linear transformation. The transformation is such that the mean value of \( f(R,j) \) minus 1 standard deviation (s.d.) maps to a similarity \( s_{\min} = -0.5 \), while the mean value plus 1 standard deviation maps to a similarity \( s_{\max} = 1.0 \). The averages are taken over all positions \( j \) in the database of 64 proteins and over all residue types \( R \). Their values are for \( A\text{Int}_{29} \): mean = -0.125, s.d. = 0.08; for \( A\text{M}_{26} \): mean = -0.032, s.d. = 0.138; for \( A\text{S}_{5} \): mean = -0.076, s.d. = 0.486. As a result, most of the transformed similarity values \( s(i,j) \) lie between \(-0.5 \) and \( 1.0 \), for all parameter sets. By adjusting the constant \( s_{\text{min}} \) with fixed \( s_{\text{max}} \), the average length of alignments can be adjusted. The other 2 parameters are penalties for gap opening and gap elongation. For the results reported here we chose a gap open penalty of \( 40 \) or \( 30 \) and gap elongation penalty of \( 1 \) per residue, so that typically a gap can be compensated for by 3 or 4 (or more) optimal residue fits.

(f) Core weights

In order to explore the importance of the protein core in fitting sequence to structure, we have introduced “core weights” in the alignment procedure. For this purpose we define the protein core as consisting of residues that are conserved in sequence and not exposed to solvent. Core weights are calculated as follows: from the multiple sequence alignment, sequence variability \( \sigma \) is calculated as described by Sander & Schneider (1991) and linearly scaled to weights \( w \), which for a protein family, as defined by a multiple sequence alignment, average to 1.0. So conserved residues have \( w > 1.0 \), variable residues have \( 0.1 < w < 1.0 \) (Sander & Schneider, unpublished results). These weights are only used for residues that have a relative solvent accessibility of less than 30\%, relative to a fully extended chain, and a variability of \( \sigma < 25 \% \), all other residues are given a weight of \( w = 0.5 \). When evaluating the sequence-structure fit at positions \( i \) and \( j \) in the alignment, weighted similarities \( w 	imes s(i,j) \) are used.

† Abbreviations used: s.d., standard deviation; r.m.s., root-mean-square.

Figure 5. Sequence-structure fitness. (a) Calculation of sequence-structure fitness of residue \( R(i) \) for the contact environment \( c(j) \) in terms of the 5 contact interface types PX, PT, PE, PH and PW. The fitness quantifies the match between the interface vector at position \( j \) of the template structure and the preference vector for residue type \( R \) at position \( i \) of the input sequence. The numbers \( f(R,j) \) constitute the structure-derived profile in (b). (b) Structure-derived profile for crambin, using 5-state (ASS) preference parameters. The amino acid type and secondary structure is given in the left margin, as in Fig. 2(d). At each position in the structure (rows \( j = 1-46 \)), the fitness \( f(R,j) \) of each amino acid type \( R \) (columns \( V \) to \( D \)) is represented by the grey level of the squares, on a scale of \(-10 \) (white) to \(+10 \) (black). The fitness of any amino acid sequence for this structural template is obtained by looking up the fitness of the particular amino acid (column) for a particular structural position (row) and summing these values over all positions in the sequence-structure alignment. For a given set of contact preference parameters, the sequence-structure profiles can be precalculated for all database proteins and reused in all subsequent sequence-structure alignments. Other preference parameters, such as secondary structure preferences, can also be represented in this way.
profiles and the fitness of different sequences for these structures is evaluated. Different types of tests are performed, in order of increasing difficulty: shift self test, align self test, search for structures, search for folding units and search for sequences. In each case and in all tests the input protein is explicitly removed from the database of 64 non-homologous proteins (Fig. 3) and all preference parameters are recalculated (jackknife test, see Methods).

(a) Shift self test: can the correct start position of a sequence in its own structure be identified?

In this test, the sequence of a protein, without insertions or deletions, is started at all possible different offsets relative to its own native structure, with residues that would extend beyond the end of the structure wrapped to the beginning in cyclic fashion. For each such arrangement, the sequence-structure fitness is evaluated (see Methods). Which set of parameter produces a clear maximum at the origin, i.e. for the native sequence-structure arrangement?

The result is astonishingly clear cut. The fitness of the native arrangement is clearly superior to any other shifted arrangement, with by far the highest peak at the origin (zero shift, Fig. 6(a) to (d)). This result holds for all 64 proteins tested here and for all sets of contact preference parameters, with only a single exception: α-amylase inhibitor 1hne, using AM2 and AS5 contact parameters. Typically, the peak at the origin is 4 to 7 standard deviations above background, defined as all shifted arrangements in the same protein. The second highest peak is typically 2 to 3 standard deviations above background. When the same test is performed with classical secondary structure preference parameters (S4), (Fig. 6a), analogous to those of Chou & Fasman (1978), Garnier et al. (1978), or Maxfield & Scheraga (1979), the number of proteins with a highest peak at the origin drops to 46 out of 64 proteins (although 60 out of 64 have the maximum within 1 residue of the origin) and the resolution is inferior, i.e. the signal (standard deviation above background) of the strongest peak relative to the second best peak is not as strong. We conclude that contact preferences, even in the simplest two-state description (AM2), outperform classical (S4) secondary structure preferences, primarily because they include the effect of solvent. Apparently, hydrophobic inside/outside preferences (protein-protein contacts versus protein-water contacts) carry more information than secondary structure preferences (α, β, turn or loop).

Co-operativity appears to be the reason why the shift self test is so selective and the native optimum so sharp. In typical globular proteins, with secondary structure segments and loops of varying lengths, only the native arrangement has correct phasing in which all single residue preferences on average add up to a positive number. Shifts of only one residue can switch many side-chains from
Figure 6. Shift test: detection of the correct alignment of a sequence in its own structure, allowing no gaps. In this shift test, the sequence of a protein is shifted along its native structure, in cyclical fashion. Residues that leave at the C terminus re-enter at the N terminus. For a given shift (in units of number of residues), preference parameters are used to evaluate how well the shifted sequence is adapted to the structure. A shift of zero residues corresponds to the native structure. In all cases, the native arrangement has the highest preference, with a large positive peak, but interface parameters have a sharper maximum than classical secondary structure preference parameters. To 1st approximation, the different interface parameters (protein-water, etc.) work equally well in this shift test. (a) Adenylate kinase, a mixed α/β structure, evaluated with 4-state (S4) secondary structure occurrence parameters, i.e. not using the interface approach and not including the effect of water contacts. Note the ambiguity of ±1 residue near the native arrangement (shift = 0); 194 residues, PDB code 3adk (Schulz et al., 1974). (b) Adenylate kinase evaluated with 2-state (AM2) protein-water contact preference parameters. Note the improved performance relative to (a), in spite of the smaller number of interface states. (c) Adenylate kinase evaluated with 29-state (AInt29) contact preference parameters. (d) Immunoglobulin-like RE11 protein, a homodimeric anti-parallel beta sandwich structure with 4 sheets, evaluated with AInt29 preference parameters; 107 residues per chain, PDB code 1rei. Weak periodicity (4-on-4 beta strands?) appears to be reflected in the sequence-structure fitness signal.

solvent contact to contact in the protein interior, and vice versa. Larger shifts put loop sequences onto secondary structure and vice versa. Shifts large enough to place one loop sequence onto the structure of a subsequent loop lead to mismatches elsewhere (unless the structure is periodic, e.g. Fig. 6(d)). So only in the native arrangement do many positive contributions add up co-operatively to give a dominant peak.
The results of the shift test indicate that evaluation of sequence-structure alignments can be a powerful filter for rejecting incorrect sequence placements in a structural framework and that surface/interior preferences of amino acids are the most important single factor. A similar conclusion was drawn from testing protein models using solvation preference parameters (Holm & Sander, 1992). Whether this can be exploited for structure prediction depends on the influence of alignment gaps. The effect of gaps is tested below.

(b) Align self test: can the sequence be aligned correctly to its own structure?

In a more demanding align self test, a sequence is aligned with its own structure, allowing gaps (but not cyclic wrapping), i.e. all sequentially ordered arrangements of a sequence in its own structure are evaluated. The alignment is performed using a dynamic programming algorithm. In the matrix of local similarities, the algorithm finds the globally best trace among a very large number of possible traces (Fig. 7). The local similarity is evaluated using the sequence-structure fitness profile (Fig. 5(b)). The best trace is the one with the highest cumulative similarity score.

The result is positive for almost all proteins in the database. The native alignment is identified as best, although there are many different reasonable ways of fitting sequence pieces into structure segments (off-diagonal traces in Fig. 7). The test is more severe for shorter sequences, as they can be fit into many of the larger proteins over their entire length, while longer sequences have fewer sufficiently long realistic templates in the database. The quality of the resulting alignment can be measured by the resulting effective sequence similarity, as measured, e.g. by the percentage of identical residues (see columns in Fig. 8). For example, the sequence identity of 76% for trypsin (4ptp) means at least one insertion or deletion causes a shift of 24% of the residues away from their correct position. The three different sets of contact parameters tested perform as follows. With 29-state parameters (AInt29) 63/64 proteins are 100% correctly aligned (except for trypsin with 24% mismatch); with five-state parameters (AS5), 63/64 are correct (except virus coat protein 2stv with 14% mismatch); with two-state parameters (AM2), 60/64 are correct (except 1g11, 13%, 6dh, 15%, 2tn, 4%, 4xia, 20%). For classical four-state secondary structure parameters, which lack solvent contact information, about one third of the alignments contain errors of up to 42% mismatch.

Aligning a sequence with its own structure is a non-trivial exercise when all direct sequence information has been removed and a residue position is only characterized by its (normalized) contact environment. However, the correct alignment of a sequence in its own structure does have a non-specific competitive advantage compared to shorter, off-diagonal, alignments. This occurs in any alignment procedure that aims to maximize the total alignment score, i.e. the sum of local similarity along the entire alignment trace (Smith & Waterman, 1981). Theoretically speaking, the main diagonal would be the one with the highest score, because of its length, even if the entire matrix of local similarities were uniform (but not if the matrix were noisy). So success in the align self test is a necessary, but not sufficient, condition for the overall success of any sequence-structure alignment method.

(c) Sequence in search of structures: can native and homologous structures be identified in a database search?

In this test, a given protein sequence is aligned to a dataset of 64 different structures, one at a time, presented as contact profiles. Can the native structure be identified, i.e. does it have the highest score? If not, what is the highest scoring structure and does it reflect an essentially correct structure for this sequence? For each sequence-structure pair, the five best alternative alignments (not sharing any subtrace) are evaluated. Thus, the native structure has to compete with more than 300 alternatives.

The result of this test is very encouraging (Fig. 8). For 58 out of 64 proteins the native structure scores highest, i.e. at position 1 out of 320, using the 29-state contact interface description (AInt29). The exceptions are: 1ef5 (rank 2/320), 1hke (rank 11), 5xrn (rank 2), 2aga (rank 5), 4rgb (rank 2) and 1ugl (rank 12). The quality of the native sequence-structure alignments is excellent (100% sequence identity with the native alignment in most cases), in spite of the fact that insertions or deletions are allowed. Using AInt29 parameters, only 4ptp has a 26% alignment error.

This result is almost independent of the type of contact parameters used, i.e. parameters based on
29 (A1nt29) and five (A55) contact states perform equally well and those based on two states (AM2) almost as well. Remarkably, however, four-state secondary structure prediction parameters perform less well, as already seen in the cyclic shift tests: about one half of the native structures do not rank as number one (Fig. 8, column S4).

The practical aim of the one-sequence against many-structures search mode is the prediction of three-dimensional structure, given a sequence. It answers the following question: if the protein has one of the known folds, which is the correct one? The predicted fold is that of the top-scoring structure. If the top-scoring fold has a relatively low score, in absolute terms, one rejects the hypothesis that this sequence has a known fold. Work to determine an appropriate absolute criterion is in progress. This predictive procedure works very well when the interface contact profile is derived from the native structure: the native structure has a high
score and the alignment is correct (see previous section). For useful practical applications detection of the correct fold also needs to work for structures remotely homologous to the native fold, e.g. the pair immunoglobulin/CD4 receptor, globin/phyocyanin; this is not consistently achieved in the current implementation.

(d) Sequence in search of structural folding units: can correct structural domains or folding units be identified in a database search?

A more demanding test is the search for substructures, rather than entire structures. Can correct structural domains or folding units be identified even when a native-like structure is not among the structures searched? Down to what level of structural unit does the search procedure work? An example is given in Figure 9, where the sequence of D-galactose binding protein (2gpb) is scanned against a set of structures, including that of 2gpb. The sequence fits best into the structures of 2gpb and two known homologues (1abp and 2lil, with sequence relation to 2gpb below the twilight zone), as well as into the structures of 3icd and 3pgk. What is detected in the latter two structures is not the same overall structure, but the presence of (β2)_n units (supersjective structure, embedded in different folds. In all cases the secondary structure agreement is remarkable. This type of local structure agreement is also apparent in many other test runs (data not shown), including runs with sequences of all-β and all-α proteins. The substructure units detected by the procedure may be folding units. In the future, one may be able to use these correctly detected units to build a predicted three-dimensional structure, even in cases when a native-like structure is not in the database.

(e) Structure in search of sequences: problems in scanning large sequence databases

The search method can be inverted by scanning with a single structure against a database of sequences. In this inverted search one attempts to ask the ambitious question of identifying all protein sequences that contain a structural domain like that of the search protein. Does the native sequence or that of a homologue appear at rank 1? We aligned the structural template of each of the 64 structures against 640 sequences: the sequences of the 64 search structures plus 576 sequences chosen randomly from Swiss-Prot (Bairoch & Boekmann, 1991). Parameters used were the 29-state interface preferences (AInt29, normalized, gap open = 100, gap elongation = 0.3, s_min = -0.3, s_max = 10, nbest = 5, maxdel = 10.

Figure 8. Sequence in search of a structure: rank of the native structure. Results of an alignment search with an input sequence against all structures in the selected database of 64 proteins, using contact interface parameters and, for comparison, secondary structure parameters. For each pair comparison, the 5 best alignments are noted and the 5 x 64 = 320 scores are sorted. The native structure is then ranked in the sorted list (self rank) and the quality of the corresponding alignment is reported in terms of percentage identical residues. Rank 1 and sequence identity 100%, implies that the sequence-structure search was highly successful, both in finding the native structure and in aligning the sequence to it. Contact parameter sets (AInt29, AAS, AM2) outperform pure secondary structure preferences (S4). A dash indicates that the sequence identity was below 50%, interpreted as a negative result. Alignment parameters: gap open = 40, gap elongation = 0.1 (units of sigma relative to 0 = 10), s_min = -0.5, s_max = 10, nbest = 5, maxdel = 10.
sequence-structure fits are, realistically, accompanied by several gaps of varying length per 100 residues. For the two-state preferences (AM2) the results are comparable (rank 1: 73%, rank 1 or 2: 83%, rank top 10: 84%). The overall results of this test appear inferior to those of the sequence in search of structure tests. However, most of the low-ranking cases actually have close homologues at top ranks, e.g. the all-helical folds of globin leen, globin Imdb, urotoglobin 2utg, myohemerythrin 4mhr, calcium-binding protein 4cpv all pick up all-helical myosin or tropomyosin at top ranks, i.e. correct identification at the segment level. Note that in the independent but conceptually similar structure in search of sequence test by Bowie et al. (1991), the results for only a handful of proteins are given without any indication of the quality of alignments, while here we test 64 different structural templates and evaluate alignment errors.

(f) Improvement by use of core weights

Evolutionary information can be used to improve the performance of sequence-structure alignment. This is done (see Methods) by placing higher weights on residues in the conserved core of a structure, as derived from multiple sequence alignments and from the solvent accessibility profile. The idea is to place less emphasis on residues that are very exposed to solvent or highly variable in sequence.

Core weights are particularly valuable in the detection of remote homologues. For example, a search with the sequence of malate dehydrogenase (4mdh) against a set of structure-derived contact profiles with core weights detects the structurally related lactate dehydrogenase (6ldh) at rank 1, in spite of the very low sequence similarity. The quality of the implied three-dimensional model is quite good as judged by direct comparison of the two known structures (Fig. 10). However, because of the above-average size of the dehydrogenases (more than 300 residues), the detection at rank 1 in this and similar cases is only moderately difficult when ranking is according to absolute score: shorter contact profiles are unlikely to lead to a comparably large score. Fortuitous length match of sequence and structure may also in part be responsible for the

Figure 9. Sequence in search of substructures (folding units). Results of an optimal alignment search with the sequence of D-galactose binding protein (2gpb) against a database of 64 protein 3-dimensional interface profiles. Only residues 1 to 85 of 2gpb are shown (residue numbers, sequence, secondary structure, sequence identities as asterisks, gaps as dots, inserts bracketed by lower case letters). The 4 top-scoring profiles (over their entire length of more than 300 residues) were arabinose binding protein (1abp), isocitrate dehydrogenase (3icd), leucine-isoleucine-valine binding protein (2liv) and phosphoglycerate kinase (3pgk). Two of these have a similar overall topology (1abp, 2liv) and are correctly detected, with good (but not perfect) alignments. The fold of the other 2 (3icd, 3pgk) is of the same general type, (zβ)8, but the topology of chain connections is different. Yet, over most of the aligned length, the secondary structure of these 2 also agrees well with that of the search sequence (of which the structure, of course, was not used). This indicates that prediction of substructures or folding units using sequence-structure fitness searches may be a practical proposition.

Figure 10. Application of core weights: search of remote homologues. The sequence of malate dehydrogenase (4mdh) detects the structural profile of the remote homologue lactate dehydrogenase (6ldh) at rank 2, right after the native structure, in competition with 68 alternative folds. The alignment is quite good: the sequence-structure alignment corresponds to a Cα positional r.m.s. deviation of 4.7 Å over 309 residues and a sequence identity of 15%, compared to the optimal 2.7 Å r.m.s. and 18% sequence identity derived from direct structure comparison (Holm et al., 1992). Rank 3 and 4 are filled by other mixed αβ proteins. Contact interface parameters were Alnt29; alignment parameters gap open = -100, gap elongation = -0.3, smin = -0.7.
successful detection of remote homologues in similar searches by Bowie et al. (1991) and Jones et al. (1992).

Another example is the more demanding search with the myoglobin structure (1mbl) against the entire Swiss-Prot database of 25,000 proteins (Fig. 11). The overlap between the scores of globins and non-globins is significantly reduced when using core weights (Fig. 11a, b). Moreover, the search picks up some remote homologues not detectable by sequence-structure alignment. The discrimination between true positives, i.e., globins and the background, is fairly sharp as seen in a two-dimensional scatter plot in terms of sequence-structure fitness (length-normalized as described by Sander & Schneider, 1991) and the resulting sequence identity (Fig. 11c).

Sequences at the border of signal and background in this type of search have an implied predicted structure. In the myoglobin search, five sequences are tentatively identified to contain an all-helical domain (Fig. 11c). The src-related kinase is a false positive as judged by the known structure of a homologue, cAMP-dependent protein kinase (Knighton et al., 1991). The origin of replication binding protein of herpes simplex virus (McGeoch et al., 1988) is a likely true positive: the C-terminal end (residues 701 to 851) is predicted to be an all-helical
structure that possibly adopts the globin fold. The prediction is supported by additional independent evidence: a stretch of 85 residues has 29.4% sequence identity to a hemoglobin alpha-chain; and, a secondary structure prediction method, rated at 79.8% sustained three-state accuracy (Rost & Sander, 1993) predicts six helices. This prediction is open to falsification.

4. Discussion

(a) Background: structure prediction by sequence-sequence alignment

Prediction of protein structure by homology has been a practical proposition for some time, based on the detection of significant similarities at the sequence level. A number of methods have been developed to search for profile-sequence or template-sequence matches in a database of many sequences, using alignment algorithms (dynamic programming or block matching) with gaps allowed (Taylor, 1986; Bashford et al., 1987; Gribskov et al., 1987; Staden, 1988; Smith & Smith, 1990; Hennikof & Hennikof, 1991). When a significant (Sander & Schneider, 1991) match with a sequence of known structure is found in the database, then by implication the three-dimensional structure of the search protein can be modelled with reasonable accuracy. The new and simple idea here and in related approaches is to evaluate sequence-structure fitness directly, rather than indirectly via the comparison of sequences.

(b) Background: measures of sequence-structure fitness

Measures of sequence-structure fitness for entire proteins or protein domains, as opposed to single residues or secondary structure segments, have been developed over the last ten years by a number of groups, originally to distinguish between properly and improperly folded protein models. They are based on intramolecular potential energy (Novotny et al., 1984, 1988), volume considerations (Gregoret & Cohen, 1990), contact counts (Bryant & Amzel, 1987), empirical solvation terms (Eisenberg & McLachlan, 1986; Baumann et al., 1989; Chiche et al., 1990; Holm & Sander, 1992), potentials of mean force derived from contact counts (Sippl, 1990; Hendlich et al., 1990; Sippl & Weitckus, 1992), interresidue contact potential optimized to yield a global minimum for native structures (Crippen, 1991; Maiorov & Crippen, 1992), a self-consistent
hydrophobic molecular field (Finkelstein & Reva, 1991), environment-specific residue preferences (Luethy et al., 1992) or alignment-based associative memory Hamiltonians (Goldstein et al., 1992a,b). Effective contact energies or preferences for use in structure prediction were earlier derived by, e.g. Tanaka & Scheraga (1975), Crippen (1977), Liščon & Sander (1980), Galaktionov & Rodionov (1981), Miyazawa & Jernigan (1988), Scharf (1989). In related work, environment-specific substitution tables were derived from multiple alignment of sequences or structures (Overington et al., 1990; Luethy et al., 1991; Sander & Schneider, unpublished results). When summed over an entire protein, such substitution probabilities also provide a measure of sequence-structure fitness.

(c) Different approaches to sequence-structure alignment

Several groups have realized that sequence-structure fitness can be successfully used for structure prediction if the protein fold belongs to one of the known structural classes. The fold is identified among the many alternatives by techniques similar to those used in searching sequence databases with profiles derived from multiple sequence alignments alone (see above), or in combination with inspection of three-dimensional structures, as done for the globin fold by Bashford et al. (1987), and for the immunoglobulin fold by Taylor (1986). Simple profiles derived from structures alone were used by Bowie et al. (1990), who aligned solvent accessibility patterns (structure information) to hydrophobicity patterns (sequence information). Hendlich et al. (1990) used pair potentials to test various sequence arrangements of one sequence in a known structure. Luethy et al. (1991) combined secondary structure and solvent exposure to derive search profiles. Refinements were then made in the definition of structural states and in the definition of potentials (Bowie et al., 1991; Casari & Sippl, 1992; Godzik & Skolnick, 1992; Godzik et al., 1992; Goldstein et al., 1992b). Geometrically generated hypothetical folds, rather than just known folds, were tested by Finkelstein & Reva (1991, 1992) using an iterative molecular field approach and by Taylor (1991). The optimization of fitness among various sequence-structure arrangements is usually treated as a one-dimensional alignment problem. The problem becomes two-dimensional when contact statistics for residue pairs are used without averaging over one of the contact partners. This more difficult problem has been solved by an algorithm analogous to one used in structure-structure alignment (Taylor & Orengo, 1989; Jones et al., 1992).

(d) Quality of alignments in the twilight zone of structural homology

How do the results of these methods compare to straightforward detection of homology by sequence alignment? Sequence alignment works well down to a level of sequence similarity that corresponds to about 25 to 30% identical residues, for a length of 80 or more residues (Sander & Schneider, 1991). So the goal of new methods must be the detection of structural homologies below this level, in the twilight zone, e.g. the structural similarity between the two domains of rhodanese (sequence identity below 15%). None of the sequence-structure alignment methods has been proven to consistently and generally detect remote structural homologies with a high score and with the correct alignment. However, several interesting examples in addition to the ones given here have been reported, e.g. the relation between actin and heat shock protein hsp70 (Bowie et al., 1991) or between phycoerytin and myoglobin (Jones et al., 1992).

It would be interesting to perform a comprehensive test of these different methods using a large number of control examples, jack-knifing (removal of homologues of test proteins from the parameter database), predetermined gap penalties (rather than adjusting gap penalties to fit the known examples), and reporting not only the score of the best hits, but also the quality of the resulting alignments. Work along these lines is continuing in several groups. Exhaustive examples of sequence-remote homologies to known structures can be taken from the database of structurally aligned protein families (Holm et al., 1992) available via anonymous file transfer protocol from ftp.embdb-heidelberg.de in the directory /pub/databases/protein-extras/fssp.

(e) Database searches: sequence seeks structure or structure seeks sequence?

There is a not-so-subtle asymmetry in the direction of the search. Taking one sequence and scanning again, say, against 200 different protein structures, corresponds to testing 200 different three-dimensional structures for the input sequence, a small but reasonable exploration of the set of all possible structures for this sequence. Most groups working in this field have concentrated on this mode (sequence seeks structure), as a way of predicting three-dimensional structure for a given sequence, with the apparently best results reported by Jones et al. (1992). In the reverse direction (structure seeks sequence), one takes one input structure, e.g. a ββββ barrel, and scans a large database of 25,000 protein sequences, with the intent of identifying all known sequences compatible with the input structure (Bowie et al., 1991). The sequence-structure fitness function needs to be well calibrated on an absolute scale for this to work, as the only physical competition in folding is between different structures for an absolute sequence (only protein design or natural evolution explore different sequences for one structure!). It would be interesting to see reports of both search directions in future publication in this field.

(f) Quest for the best parameter set

The main conceptual difference of our approach to that of others is in the contact vector formulation.
(Scharf, 1989). Rather than classifying a residue into one of several discrete environmental states (Bowie et al., 1991), we retain for each residue information about its environment on a sliding scale, in terms of a set of real numbers that describe all interatomic contacts made by the residue. Evaluation of the preferences is done not by a simple table lookup, but by a vector product that effectively weights each participating interresidue contact by the corresponding contact strength.

This conceptual framework allows a large variety of different definitions of environmental preference parameters, or potentials of mean force, in a unified language, that of interatomic contacts. Solvent contacts are described in this language in a natural way. So far, the comparison of five different parameter sets has led to the conclusion that; (1) classical secondary structure preferences are inferior to contact interface preferences, (2) the best interface definition is the most complicated one, with 29 states, but only marginally so and (3) the simplest two-state preferences (protein-protein, protein-water) work almost as well as the most sophisticated 29-state description used here. Recent analysis of many-parameter mean field contact potentials confirms this view (Casari & Sippl, 1992). Future work will show which of the parameter sets currently being developed by several groups have the best performance in terms of identifying three-dimensional folds within and below the twilight zone of sequence similarity.

(g) Anticipated improvements

Improvement of sequence-structure alignments for protein structure prediction in the twilight zone may come from a more adequate definition of structural states (not necessarily more states), from use of homologous sequence information, e.g. in the form of conservation weights or multiple sequence alignments, from mixing sequence and structure information in correct proportions, from improved optimization methods in combining different interaction terms, from genuine two-dimensional alignment optimization that takes into account the change of contact partner with alignment, and from variation in backbone geometry and general plasticity of homologous structures. The problem is an urgent one, as genome projects will soon flood us with many protein sequences lacking functional or structural information. When developed and used properly, computational sequence analysis and structure prediction algorithms can save countless hours in the laboratory, by deriving probable three-dimensional structures.

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